Lecture 5 – Multivariate Linear Regression

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Question From Last Time

Can you find matrices A and B such that $BA = I$, but $AB \neq I$?

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, \qquad B = A^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}.$$

Check that

$$BA = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I, \qquad AB = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Question From Last Time

Vectors $\mathbf{x}$ and $\mathbf{y}$ are *orthogonal* if their dot product is zero:

$$\mathbf{x}^T\mathbf{y} = \sum_{i=1}^{N} x_i y_i = 0.$$

E.g.,

$$\begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -0.5 \\ -0.5 \end{bmatrix} = 0$$

Question From Last Time

Let $\mathbf{x}_1, \mathbf{x}_2, \ldots, \mathbf{x}_k \in \mathbb{R}^n$ be *mutually* orthogonal *unit vectors*

$$\mathbf{x}_i^T \mathbf{x}_j = 0, \quad i \neq j$$
$$\mathbf{x}_i^T \mathbf{x}_i = 1$$

Consider the product

$$A^T A = \begin{bmatrix} - & \mathbf{x}_1^T & - \\ & \vdots & \\ - & \mathbf{x}_2^T & - \\ - & \mathbf{x}_k^T & - \end{bmatrix} \begin{bmatrix} | & | & & | \\ \mathbf{x}_1 & \mathbf{x}_2 & \ldots & \mathbf{x}_k \\ | & | & & | \end{bmatrix} = I_k$$

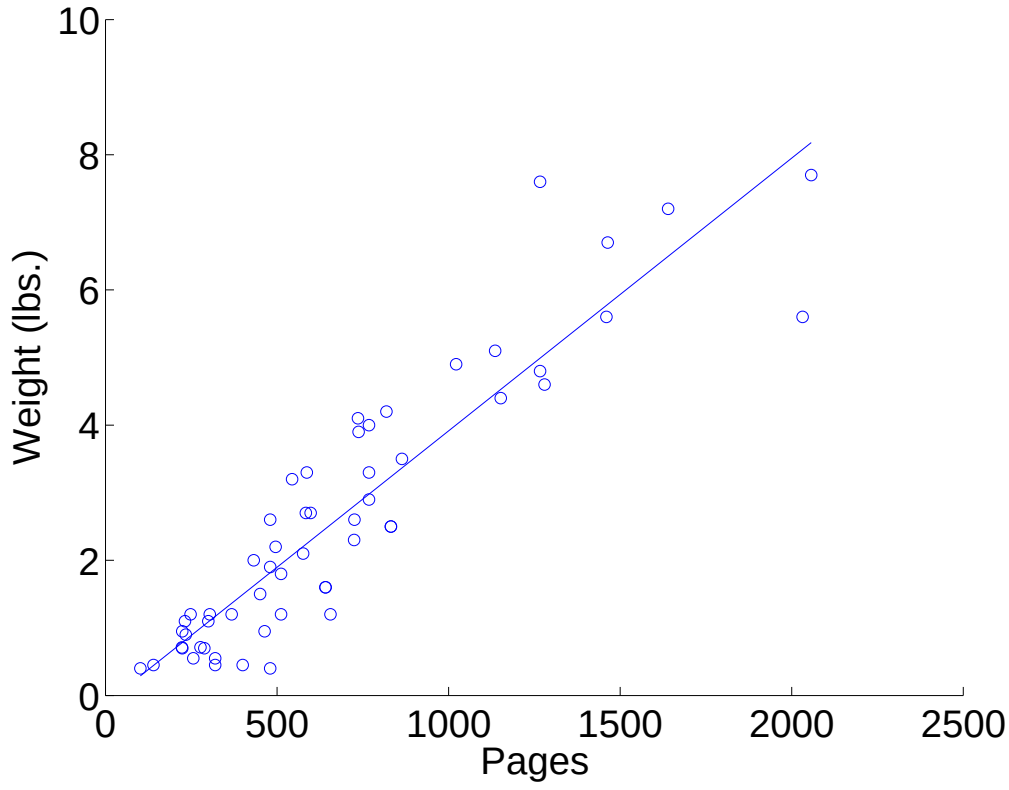
Today's Topics

Multivariate linear regression

- Model
- Cost function
- Normal equations
- Gradient descent
- Features

MATLAB (time permitting)

Book Data



$$y = 0.004036x - .122291$$

Book Data

Can we predict better with multiple features?

Width	Thickness	Height	# Pages	Hardcover	Weight
8	1.8	10	1152	1	4.4
8	0.9	9	584	1	2.7
7	1.8	9.2	738	1	3.9
6.4	1.5	9.5	512	1	1.8

Training data

$$(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \ldots, (\mathbf{x}_N, y_N)$$

Multivariate Linear Regression

- Input: $\mathbf{x} \in \mathbb{R}^d$
- Output: $y \in \mathbb{R}$
- Model (hypothesis class): ?
- Cost function: ?

Model

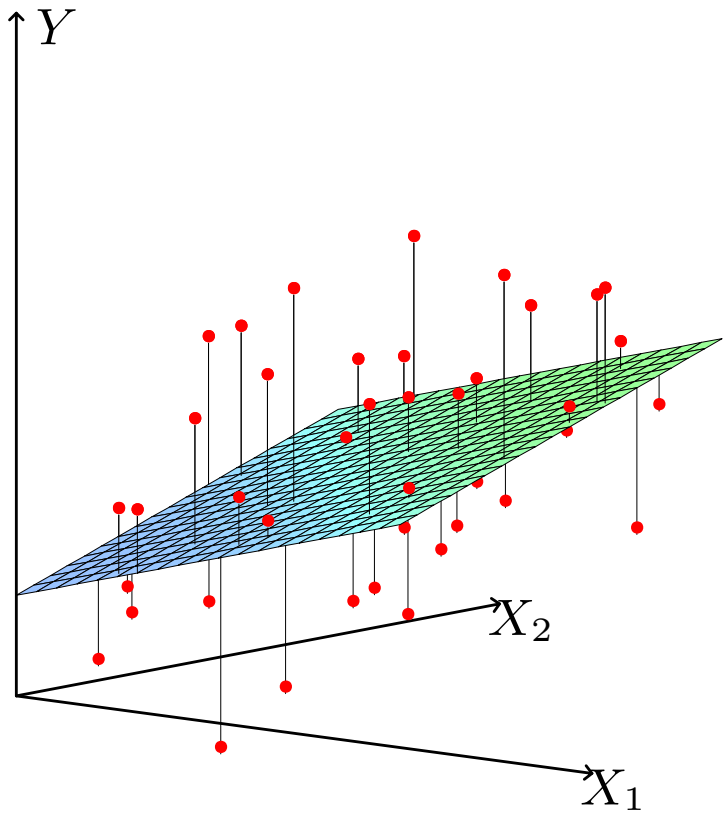
$$h_{\mathbf{w}}(\mathbf{x}) = w_0 + w_1 x_1 + w_2 x_2 + \ldots + w_d x_d$$

$$h_{\mathbf{w}}(\mathbf{x}) = \begin{bmatrix} w_0 & w_1 & \ldots & w_d \end{bmatrix} \begin{bmatrix} 1 \\ x_1 \\ \vdots \\ x_d \end{bmatrix}$$

$$h_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^T \mathbf{x} = \mathbf{x}^T \mathbf{w}$$

(Augment feature vector with 1)

Illustration



The Problem

Find $\mathbf{w}$ such that

$$y_i \approx h_{\mathbf{w}}(\mathbf{x}_i), \qquad i = 1, \ldots, N$$

$$\begin{bmatrix} y_1 \\ y_2 \\ \ldots \\ y_N \end{bmatrix} \approx \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \ldots & x_{1,d} \\ 1 & x_{2,1} & x_{2,2} & \ldots & x_{2,d} \\ \ldots & & & & \\ 1 & x_{N,1} & x_{N,2} & \ldots & x_{N,d} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ \ldots \\ w_d \end{bmatrix}$$

$$\mathbf{y} \approx X\mathbf{w}$$

Inputs

Data matrix, label vector

$$X = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,d} \\ & & \vdots & & \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,d} \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}.$$

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Cost Function

$$J(\mathbf{w}) = \sum_{i=1}^{N} (h_{\mathbf{w}}(\mathbf{x}_i) - y_i)^2$$

Exercise: write this succinctly in matrix-vector notation

Cost Function

Answer:

$$J(\mathbf{w}) = (X\mathbf{w} - \mathbf{y})^T (X\mathbf{w} - \mathbf{y})$$

Solution 1: Normal Equations

Normal equations

$$\mathbf{w} = (X^T X)^{-1} X^T \mathbf{y}$$

Heuristic derivation:

Proper Approach

- Set all partial derivatives to zero

$$0 = \frac{\partial}{\partial w_j} J(\mathbf{w})$$

- Solve a system of $d + 1$ linear equations for $w_0, \ldots, w_d$
- Tedious, but leads to normal equations

Aside: Matrix Calculus

Succinct (and cool!) way to solve for normal equations:

$$
\begin{aligned}
0 &= \frac{d}{d\mathbf{w}}(X\mathbf{w}-\mathbf{y})^T(X\mathbf{w}-\mathbf{y}) \\
0 &= 2(X\mathbf{w}-\mathbf{y})^T X \\
0 &= X^T(X\mathbf{w}-\mathbf{y}) \\
X^T X\mathbf{w} &= X^T\mathbf{y} \\
\mathbf{w} &= (X^T X)^{-1}X^T\mathbf{y}
\end{aligned}
$$

Solution 2: Gradient Descent

1. Initialize $w_0, w_1, \ldots, w_d$ arbitrarily
2. Repeat until convergence

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\mathbf{w}), \qquad j = 0, \ldots, d.$$

Partial derivatives:

$$\frac{\partial}{\partial w_j} J(\mathbf{w}) = 2 \sum_{i=1}^{N} (h_{\mathbf{w}}(\mathbf{x}_i) - y_i) x_{i,j}$$

Feature Normalization

- Features may have very different numeric ranges

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- Advice: normalize your features!
  - Subtract mean (center)
  - Divide by standard deviation (scale)

Feature Normalization

For each feature j, compute

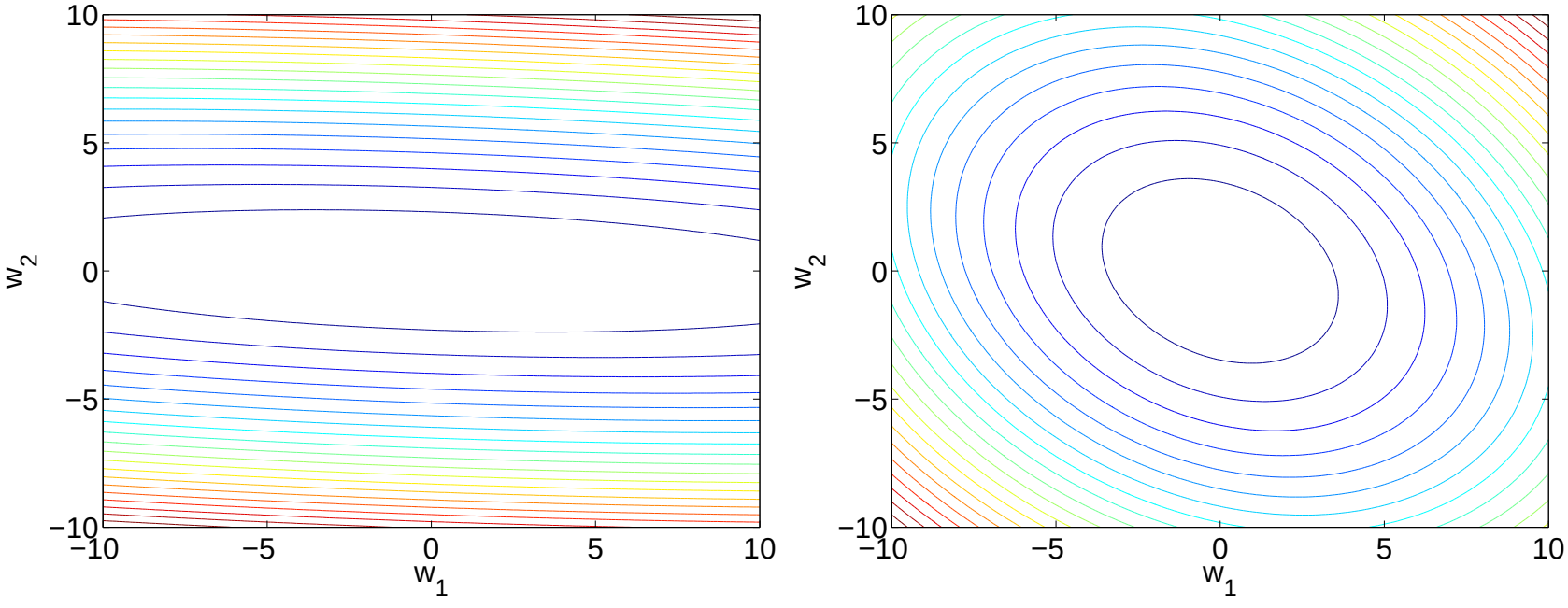
$$\mu_j = \frac{1}{N}\sum_{i=1}^{N} x_{i,j}, \qquad \sigma_j^2 = \frac{1}{N}\sum_{i=1}^{N}(x_{i,j} - \mu_j)^2$$

Then, subtract μ_j and divide by σ_j:

$$x_{i,j} \leftarrow (x_{i,j} - \mu_j)/\sigma_j$$

Feature Normalization

Example: cost function contours before and after normalization



Feature Design

It is possible to fit *nonlinear* functions using linear regression:

$$(x_1, x_2, x_3) \mapsto (x_1, x_2, x_3, x_1^2, \log(x_2), x_1 + x_3)$$

Approaches

- Try standard transformations
- Design features you think will work

Polynomial Regression

$$x \mapsto (1, x, x^2, x^3, \ldots)$$