CS 335: Kernel SVMs Dan Sheldon November 18, 2014	First, a quick review Hard-margin SVM $ \begin{array}{c} \min_{w,b} \frac{1}{2} \mathbf{w} ^2 \\ \text{subject to } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \geq 1 \text{for all } i \\ \end{array} $ Functional margin at least one for all training examples 1D Exercise: which examples have functional margin = 1? > 1?
Support Vectors Definition: in a hard-margin SVM, a support vector is a training example with functional margin exactly equal to one.	Visualization MATLAB demo: hard-margin SVM (1) Another interpretation of functional margin constraint: $y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \ge 1$ All training examples at least one contour from decision boundary MATLAB demo: hard-margin SVM w/ outlier (2)
Soft-Margin SVM $\begin{array}{c} \min_{w,b,\xi} \frac{1}{2} \mathbf{w} ^2 + C \sum_{i=1}^{m} \xi_i \\ \text{subject to } y^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b) \ge 1 - \xi_i \text{for all } i \\ \xi_i \ge 0, \ i = 1, \dots, m \end{array}$ 1D exercise MATLAB demo (3). Exercise: is C increasing or decreasing?	Support Vectors Definition: a support vector is a training example with functional margin less than or equal to one. (i.e., it falls on the wrong side of the 1-contour) (definition works for hard or soft margin SVM)



Kernel Trick	Kernel Trick
Suppose you have a black box $K(\cdot, \cdot)$ to compute the dot product for any two feature vectors \mathbf{x} and \mathbf{z} : $K(\mathbf{x}, \mathbf{z}) := \mathbf{x}^T \mathbf{z}$ Thought experiment: I hold feature vectors in a box. You can ask me only for dot products. Can you still solve the learning problem? Make predictions?	$\max_{\boldsymbol{\alpha}} \sum_{i=1}^{m} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{m} y^{(i)} y^{(j)} \alpha_i \alpha_j K(\mathbf{x}^{(i)}, \mathbf{x}^{(j)})$ s.t. $\alpha_i \ge 0$, for all i , $\sum_{i=1}^{m} \alpha_i y^{(i)} = 0$ $h_{\mathbf{w},b}(\mathbf{x}) = b + \mathbf{w}^T \mathbf{x} = b + \sum_{i=1}^{m} \alpha_i y^{(i)} K(\mathbf{x}^{(i)}, \mathbf{x})$
Kernel Trick	Feature Mapping
This doesn't seem that special Real trick: fancy non-linear feature expansions in a computationally efficient way	Let ϕ be a feature mapping from original features to expanded features. E.g., $\phi : \mathbb{R}^n \to \mathbb{R}^{n^2}$: $\phi(\mathbf{x}) = \begin{bmatrix} x_1 x_1 \\ x_1 x_2 \\ x_2 x_1 \\ x_2 x_2 \end{bmatrix}$ (products of two original features)
Kernel	Example: Polynomial Kernel
Given any feature mapping ϕ , the kernel corresponding to ϕ is $K(\mathbf{x}, \mathbf{z}) = \phi(\mathbf{x})^T \phi(\mathbf{z})$ (map to higher dimensional space, then take dot product)	Important trick: we can often compute kernel without actually doing the expansion $K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^T \mathbf{z})^2$ Claim: this is the kernel corresponding to $\phi(\mathbf{x}) = \begin{bmatrix} x_1 x_1 \\ x_1 x_2 \\ x_2 x_1 \\ x_2 x_2 \end{bmatrix}$ Exercise: verify this on board

