

Hw 4: wed

COMPSCI 688: Probabilistic Graphical Models

Lecture 19: Black-Box Stochastic Variational Inference

→ VAE → Hw5

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Review

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Variational Inference

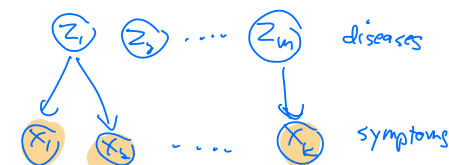
1. **Input:** $p(z, x)$ and fixed x
2. Choose some approximating family $q_\phi(z)$
3. Maximize $\text{ELBO}(\phi)$ wrt ϕ — equivalent to minimizing $\text{KL}(q_\phi(z) \parallel p(z|x))$
4. Use $q_\phi(z)$ as a proxy for $p(z|x)$

$$\text{ELBO}(\phi) = \mathbb{E}_{q_\phi(Z)} \left[\log \frac{p(Z, x)}{q_\phi(Z)} \right] = \mathbb{E}_{q_\phi(Z)} [\log p(Z, x)] - \mathbb{E}_{q_\phi} [\log q_\phi(Z)]$$

$$\sum_z q_\phi(z) \log \frac{p(z, x)}{q_\phi(z)}$$

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Variational Inference



Something we skipped: $p(z, x)$ discrete graphical model, $q(z) = \prod_j q_j(z_j)$ ("mean field") → "coordinate ascent VI, CAVI", message-passing

Today: z continuous, $p(z, x)$ **black box**, $q(z)$ TBD

Applications: • stats model, PPL (stan)
• VAEs, interpretable generative models

BIVI ~ HMC

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Motivation: Continuous Latent Variable Models

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Factor Analysis

$$p(z) \approx q_\phi(z)$$

Factor analysis is a classical statistical model. It posits an observed vector $\mathbf{x} \in \mathbb{R}^d$ is generated as a linear combination of basis vectors $\mathbf{w}_1, \dots, \mathbf{w}_m$ with weights z_1, \dots, z_m plus noise:

$$\mathbf{x} = \begin{bmatrix} | & | & & | \\ \mathbf{w}_1 & \mathbf{w}_2 & \dots & \mathbf{w}_m \\ | & | & & | \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_m \end{bmatrix} + \text{noise}$$

$\mathbf{X} = z_1 \vec{w}_1 + z_2 \vec{w}_2 + \dots + z_m \vec{w}_m + \text{noise}$

"dictionary"
↓
 $\mathbf{x} = \mathbf{W}\mathbf{z} + \text{noise}$
↑
"factor weights"

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$$\mathbf{x} = \mathbf{W}\mathbf{z} + \text{noise}, \quad \text{noise} \sim \mathcal{N}(0, \Psi)$$

$$\Rightarrow \mathbf{x} \sim \mathcal{N}(\mathbf{W}\mathbf{z}, \Psi)$$

Probabilistic factor analysis assumes the weights are drawn from a standard normal. The generative process is:

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}; 0, I)$$

$$p(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}; \mathbf{W}\mathbf{z}, \Psi)$$

(Typically Ψ is diagonal and the data is pre-processed so \mathbf{x} has zero mean.)

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Visualization: PCA Demo

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Factor Analysis: Learning

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}; 0, I)$$

$$p(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}; \mathbf{W}\mathbf{z}, \Psi)$$

$$\theta = (\mathbf{W}, \Psi)$$



Consider learning the parameters $\theta = (\mathbf{W}, \Psi)$ given data $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}$ assumed to be independently drawn from this model.

Since \mathbf{z} is latent, the log-likelihood of a single datum \mathbf{x} is $\log p(\mathbf{x})$, the “log-marginal likelihood”.

In this model, the marginal likelihood is available in *closed form*:

$$p(\mathbf{x}) = \int \mathcal{N}(\mathbf{z}; 0, I) \mathcal{N}(\mathbf{x}; \mathbf{W}\mathbf{z}, \Psi) d\mathbf{z} = \mathcal{N}(\mathbf{x}; 0, \mathbf{W}\mathbf{W}^\top + \Psi)$$

$p(\mathbf{z})$ $p(\mathbf{x}|\mathbf{z})$

Therefore, we can learn by maximizing the log-marginal likelihood:

$$\mathcal{L}(\theta) = -\frac{N}{2} \log(|2\pi\Sigma|) - \frac{1}{2} \sum_{n=1}^N \mathbf{x}^{(n)\top} \Sigma^{-1} \mathbf{x}^{(n)}, \quad \Sigma = \mathbf{W}\mathbf{W}^\top + \Psi$$

Alternately, there is an EM algorithm for this model where both E and M steps have simple forms.

Factor Analysis: Generalizations

This model is “easy”, but factor analysis has many generalizations that make exact learning and inference intractable.

A variational autoencoder (VAE) uses a nonlinear-function f_θ instead of a linear transformation \mathbf{W} to map from \mathbf{z} to the mean of \mathbf{x} :

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}; 0, I)$$

$$p(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}; f_\theta(\mathbf{z}), \Psi)$$

$$\uparrow$$

$$\mathbf{W}_z$$

$$\mathbf{z} \mapsto \mu$$

$$\mathbf{z} \mapsto f_\theta(\mathbf{z})$$

A typical structure for f_θ is a multi-layer neural network, e.g.

$$f_\theta(\mathbf{z}) = h_2(\mathbf{b}_2 + \mathbf{W}_2 \cdot \overbrace{h_1(\mathbf{b}_1 + \mathbf{W}_1 \mathbf{z})}^{\mathbf{z}'})$$

where h_2, h_1 are element-wise nonlinear functions.

$$\mathbf{x} = \boldsymbol{\mu} + \text{noise}$$

$$x_j \sim \text{Bernoulli}(\mu_j)$$

Another generalization changes the likelihood, e.g., to a Bernoulli distribution:

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}; \mathbf{0}, \mathbf{I})$$

$$p(x_j | \mathbf{z}) = \text{Bernoulli}(x_j; (f_{\theta}(\mathbf{z}))_j), \quad j = 1, \dots, d$$

$$\mu_j$$

$$\mu_j = 0.7$$

Inference and Learning in Generalized Models

Almost any change from the basic factor analysis model makes it so we can't compute the marginal likelihood $p(\mathbf{x})$ exactly, so inference and learning become hard.

The model is *only* tractable with linear transformations and a Gaussian likelihood.

We need additional inference tools for the generalizations.

Black-Box Stochastic Variational Inference

Black-Box Stochastic Variational Inference

A general inference approach that works well for models with continuous latent variables, including factor analysis, is *black-box stochastic variational inference*:

- **Black box**: only requires computing $\log p(z, x)$ and its gradients for different z
- **Stochastic**: optimizes the ELBO using Monte Carlo estimates

Stochastic Variational Inference

$$\max_{\phi} \text{ELBO}(\phi) = \mathbb{E}_{q_{\phi}(z)} \left[\log \frac{p(z, x)}{q_{\phi}(z)} \right]$$

- ▶ **Input:** $p(z, x)$ and fixed x
- ▶ Start with some ϕ
- ▶ For $t = 1, 2, \dots, T$
 - ▶ $g \leftarrow$ **unbiased estimate** of $\nabla_{\phi} \text{ELBO}$
 - ▶ Take a small step: $\phi \leftarrow \phi + \epsilon g$ (or Adam or other optimizer)
- ▶ **Return** ϕ

Main issue: how to get g ?

$$\log p_{\theta}(x)$$

$$p(z|x)$$