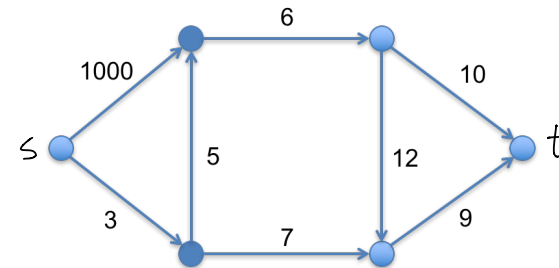


Goals

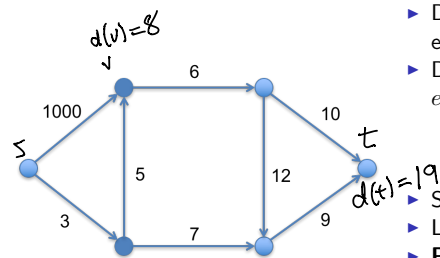
- Introduce the shortest path problem in directed graphs with nonnegative edge lengths

Shortest Paths Problem

Problem: find shortest paths in a directed graph with edge *lengths* (e.g., Google maps)



Let's Formalize the Problem



- Directed graph $G = (V, E)$ with **nonnegative** edge lengths $\ell(e) \geq 0$ $\ell(u, v)$ $e = (u, v)$
- Define *length* of path P consisting of edges e_1, e_2, \dots, e_k as

$$\ell(P) = \ell(e_1) + \ell(e_2) + \dots + \ell(e_k)$$

- Starting node s
- Let $d(v)$ be the length of shortest $s \rightsquigarrow v$ path.
- **Problem:** Can we efficiently find $d(v)$ for all nodes $v \in V$?

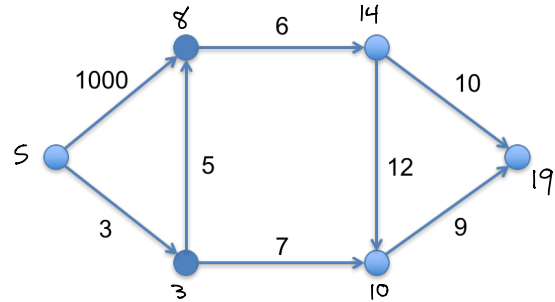
- **Question:** Why for all nodes at the same time?

Goals

- Derive Dijkstra's algorithm for shortest paths

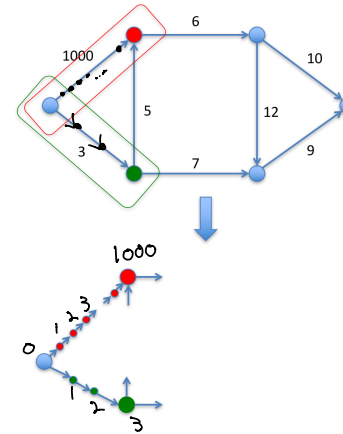
Dijkstra Derivation

Suppose all edges have integer length. Can we use BFS to solve this problem?

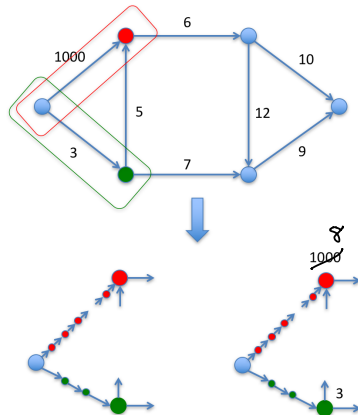


Recall: nodes in layer L_i are at distance i from start.

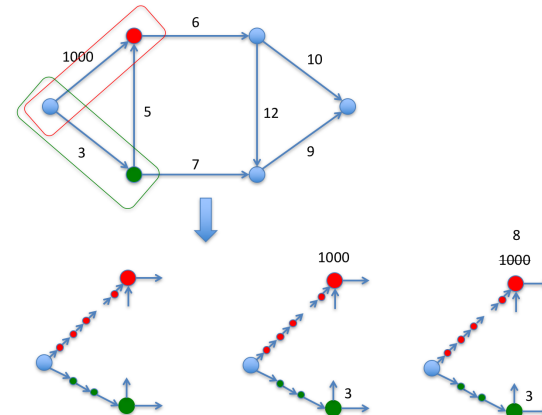
Dijkstra Derivation



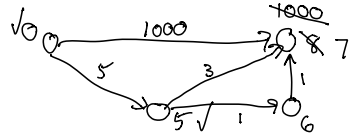
Dijkstra Derivation



Dijkstra Derivation



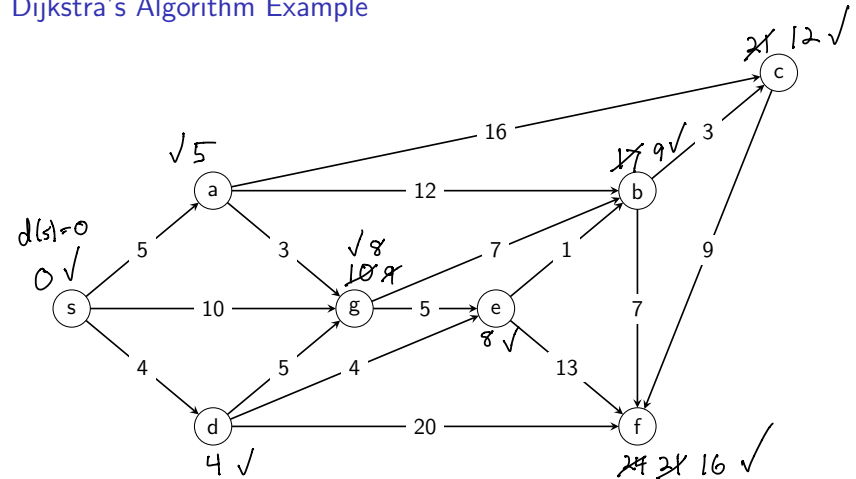
Dijkstra's Algorithm



Idea: keep track of expanding "wavefront" (arrival time at $v = d(v)$)

- find next node v to be hit by wave (= unexplored node closest to s)
- explore v : update tentative arrival time at each neighbor

Dijkstra's Algorithm Example



Goals

- Describe implementation of Dijkstra's algorithm and analyze its running time

Dijkstra's Algorithm Implementation

Notation:

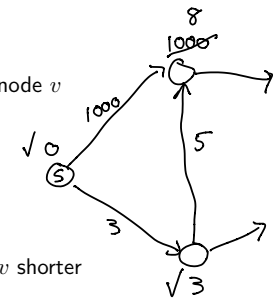
- $d'(v)$ — earliest tentative arrival time so far for node v
- $d(v)$ — shortest distance (actual arrival time)

How to keep track of the wavefront?

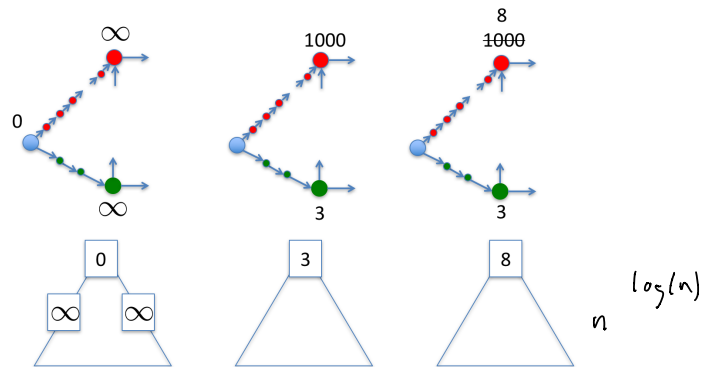
- Find *next arrival*: node v with smallest $d'(v)$
- Set shortest distance: $d(v) = d'(v)$
- Update $d'(v)$ for neighbors of v if path through v shorter

What data structure supports **find smallest** and **update values**?

priority queue



Shortest Paths Problem



Dijkstra's Algorithm

← *unexplored nodes*

```

set  $A = V$ 
set  $d'(v) = \infty$  for all nodes
set  $d'(s) = 0$ 
while  $A$  not empty do
  extract node  $v \in A$  with smallest  $d'(v)$  value
  set  $d(v) = d'(v)$ 
  for all edges  $(v, w)$  where  $w \in A$  do
    if  $d(v) + \ell(v, w) < d'(w)$  then
       $d'(w) = d(v) + \ell(v, w)$ 
  
```

- ▷ Priority queue
- ▷ Tentative arrival time
- ▷ Nodes left to explore
- ▷ Wave arrives at v
- ▷ Shorter path to w ??

Running Time?

Use heap-based priority queue for A

```

set  $A = V$ 
set  $d'(v) = \infty$  for all nodes
set  $d'(s) = 0$ 
while  $A$  not empty do
  extract node  $v \in A$  with smallest  $d'(v)$  value  $n$       ▷ Extract-min
  set  $d(v) = d'(v)$ 
  for all edges  $(v, w)$  where  $w \in A$  do  $m$ 
    if  $d(v) + \ell(v, w) < d'(w)$  then
       $d'(w) = d(v) + \ell(v, w)$   $\leq m$       ▷ Update-key
  
```

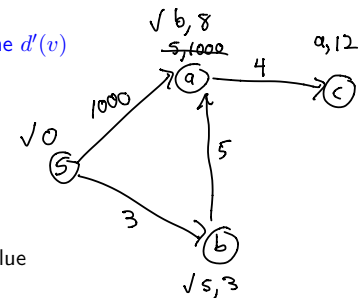
- ▶ n extract-min operations. $O(n \log n)$
- ▶ m update-key operations. $O(m \log n)$
- ▶ **Total:** $O((m + n) \log n)$

Tracking the Shortest Path

Keep track of node that last updated arrival time $d'(v)$
 Call it $\text{prev}(v)$ = predecessor in shortest path

```

set  $A = V$ 
set  $\text{prev}(v) = \text{null}$  for all nodes
set  $d'(v) = \infty$  for all nodes
set  $d'(s) = 0$ 
while  $A$  not empty do
  extract node  $v \in A$  with smallest  $d'(v)$  value
  set  $d(v) = d'(v)$ 
  for all edges  $(v, w)$  where  $w \in A$  do
    if  $d(v) + \ell(v, w) < d'(w)$  then
       $d'(w) = d(v) + \ell(v, w)$ 
       $\text{prev}(w) = v$ 
  
```



Goals

- Prove that Dijkstra's algorithm is correct

Proof of Correctness

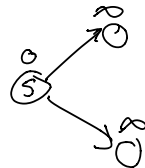
- **Idea:** nodes are explored in increasing order of distance from s .
- At each step, we have:
 - A : set of nodes still to explore ✓
 - $S = V \setminus A$: explored nodes, $d(v)$ assigned ✓
- **Claim (invariant):**
 - (1) for $v \in S$, $d(v)$ is length of shortest $s \rightsquigarrow v$ path (correctness)
 - (2) for $y \in A$, $d'(y)$ is the length of the shortest $s \rightsquigarrow y$ path with all nodes in S except y .
- **Proof:** By induction on $|S|$

Induction Proof

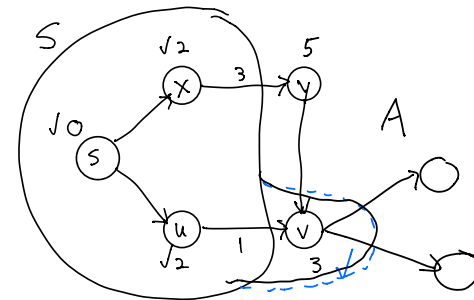
Base case: Initially $S = \emptyset$. Both (1) and (2) are true. ✓

Induction step:

- Assume the invariant is true for $|S| = k \geq 0$.
- Let v = next node added to S , so we set $d(v) = d'(v)$
- We claim (1) is true: the shortest $s \rightsquigarrow v$ path has length $d(v) = d'(v)$.
 - By (2), $d'(v)$ is length of the shortest path $s \rightsquigarrow v$ path with all prior nodes in S . We claim this is the shortest $s \rightsquigarrow v$ path overall.
 - Why? Every path to v must leave S eventually; if it first hops to some other node y outside of S , it is **already at least as long as** $d'(v)$, because $d'(v) \leq d'(y)$.
 - Paths can't get shorter after leaving S because edge lengths are non-negative.



- 1) $v \in S \Rightarrow d(v) = \text{length of shortest } s \rightsquigarrow v \text{ path}$
- 2) $y \in A \Rightarrow d'(y) = \text{length of shortest } s \rightsquigarrow y \text{ path with all nodes but } y \in S$



Induction Proof: Invariant (2)

Invariant (2) is directly maintained by the algorithm: after adding v to S , it updates $d'(w)$ for all neighbors w if a shorter path is found through v .

```
for all edges  $(v, w)$  where  $w \in A$  do  
  if  $d(v) + \ell(v, w) < d'(w)$  then  
     $d'(w) = d(v) + \ell(v, w)$ 
```