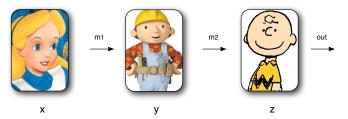
#### Data Streams & Communication Complexity Lecture 3: Communication Complexity and Lower Bounds

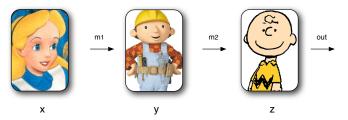
#### Andrew McGregor, UMass Amherst



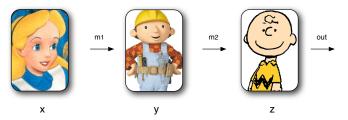
► Three friends Alice, Bob, and Charlie each have some information x, y, z and Charlie wants to compute some function P(x, y, z).



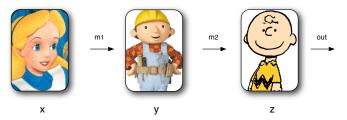
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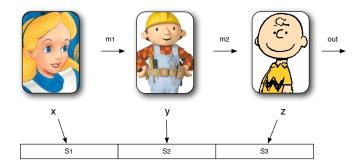


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  - Deterministic:  $m_1(x)$ ,  $m_2(m_1, y)$ ,  $out(m_2, z) = P(x, y, z)$

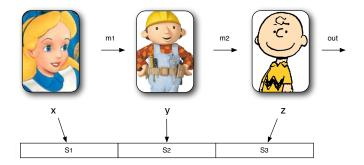


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  - Deterministic:  $m_1(x)$ ,  $m_2(m_1, y)$ ,  $out(m_2, z) = P(x, y, z)$
  - ▶ Random:  $m_1(x, r)$ ,  $m_2(m_1, y, r)$ ,  $out(m_2, z, r)$  where r is public random string. Require  $\mathbb{P}_r[out(m_2, z, r) = P(x, y, z)] \ge 9/10$ .

▶ Let Q be some stream problem. Suppose there's a reduction  $x \to S_1$ ,  $y \to S_2$ ,  $z \to S_3$  such that knowing  $Q(S_1 \circ S_2 \circ S_3)$  solves P(x, y, z).

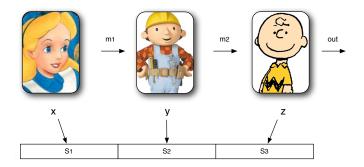


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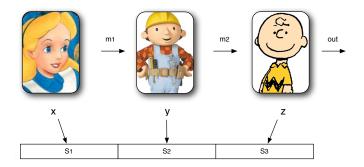
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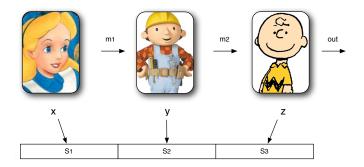
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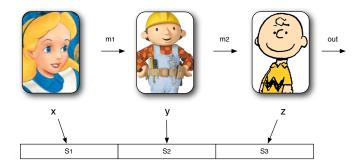
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An s-bit stream algorithm A for Q yields 2s-bit protocol for P: Alice runs A of S<sub>1</sub>; sends memory state to Bob; Bob instantiates A with state and runs it on S<sub>2</sub>; sends state to Charlie who finishes running A on S<sub>3</sub> and infers P(x, y, z) from Q(S<sub>1</sub> ∘ S<sub>2</sub> ∘ S<sub>3</sub>).

Communication Lower Bounds imply Stream Lower Bounds

► Had there been t players, the s-bit stream algorithm for Q would have lead to a (t - 1)s bit protocol P.

#### Communication Lower Bounds imply Stream Lower Bounds

- ► Had there been t players, the s-bit stream algorithm for Q would have lead to a (t - 1)s bit protocol P.
- ► Hence, a lower bound of L on the communication required for P implies s ≥ L/(t − 1) bits of space are required to solve Q.

## Outline of Lecture

**Classic Problems and Reductions** 

Information Statistics Approach

Hamming Approximation

### Outline

**Classic Problems and Reductions** 

Information Statistics Approach

Hamming Approximation

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$$x = (\begin{array}{ccccccc} 0 & 1 & 0 & 1 & 1 & 0 \end{array})$$
 and  $j = 3$ 

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- Then median $(S_1 \cup S_2) = 2j + x_j$  and this determines INDEX(x, j).
- ► An *s*-space algorithm implies an *s*-bit protocol so

$$s = \Omega(n)$$

by the communication complexity of indexing.

• Consider a  $t \times n$  matrix where column has weight 0, 1, or t, e.g.,

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- An s-space 2-approximation implies an s(t-1) bit protocol so

$$s = \Omega(n/t^2) = \Omega(n^{1-2/k})$$

by the communication complexity of set-disjointness.

• Consider 2 binary vectors  $x, y \in \{0, 1\}^n$ , e.g.,

$$x = (0 \ 1 \ 0 \ 1 \ 1 \ 0)$$
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- An s-space  $(1 + \epsilon)$ -approximation implies an s bit protocol so

$$s = \Omega(n) = \Omega(1/\epsilon^2)$$

by communication complexity of approximating Hamming distance.

#### Outline

**Classic Problems and Reductions** 

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Hamming Approximation

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▶ We'll first give some definitions and then run through an example.

• Let X and Y be random variables.

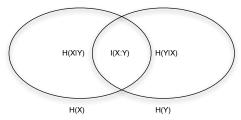
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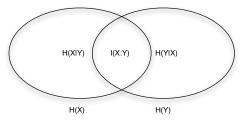
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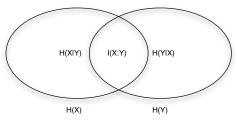


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Useful Facts:

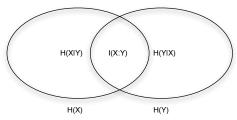
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- If X takes at most  $2^{\ell}$  values, then  $H(X) \leq \ell$ .
- If X and Y are independent, then  $I(XY : Z) \ge I(X : Z) + I(Y : Z)$ .

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Note that

$$icost(\Pi) = I(M : X) \le H(M) \le cost(\Pi)$$
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• Express  $DISJ_t$  in terms of  $AND_t$  where  $AND_t(x_1, \ldots, x_t) = \prod_i x_i$ :

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• Result follows by showing  $icost(\Pi_{AND_t,i}|D) = \Omega(1/t)$ .

#### Outline

**Classic Problems and Reductions** 

Information Statistics Approach

Hamming Approximation

Some communication results can be proved via a reduction from other communication results.

#### Theorem

If Alice and Bob have  $x, y \in \{0, 1\}^n$  and Bob wants to determine  $\Delta(x, y)$  up to  $\pm \sqrt{n}$  with probability 9/10, then Alice must send  $\Omega(n)$  bits.

▶ Reduction from INDEX problem: Alice knows z ∈ {0,1}<sup>t</sup> and Bob knows j ∈ [t]. Let's assume |z| = t/2 and this is odd.

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• Lemma: For some constant c > 0,

$$\mathbb{P}\left[\operatorname{sign}(r.z) = \operatorname{sign}(r_j)\right] = \begin{cases} 1/2 & \text{if } z_j = 0\\ 1/2 + c/\sqrt{t} & \text{if } z_j = 1 \end{cases}$$

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and by Chernoff bounds  $\mathbb{P}\left[|\Delta(x, y) - \mathbb{E}[\Delta(x, y)]| \ge 2\sqrt{n}\right] < 1/10.$ • Hence, a  $\pm \sqrt{n}$  approx. of  $\Delta(x, y)$  determines  $z_j$  with prob. > 9/10.

Claim

Let A be the event  $A = {sign(r.z) = r_j}$ . For some constant c > 0,

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▶  $\mathbb{P}[A|s \neq 0] = 1/2$  since  $s \neq 0 \Rightarrow s = {\dots, -4, -2, 2, 4, \dots}$ . Hence, sign(r.z) = sign(s) which is independent of  $r_j$ .

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• So 
$$\mathbb{P}[A] = \mathbb{P}[s=0] + \frac{\mathbb{P}[s\neq 0]}{2} = \frac{1}{2} + \frac{\mathbb{P}[s=0]}{2} = \frac{1}{2} + \frac{c}{\sqrt{t}}.$$