

Graph Synopses, Sketches, and Streams: A Survey



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University of Pennsylvania

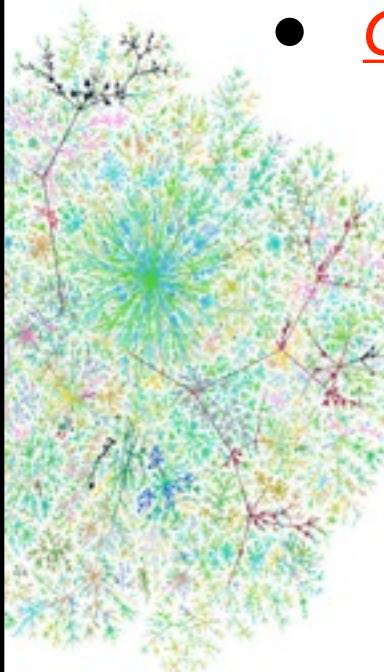
Andrew McGregor

University of Massachusetts

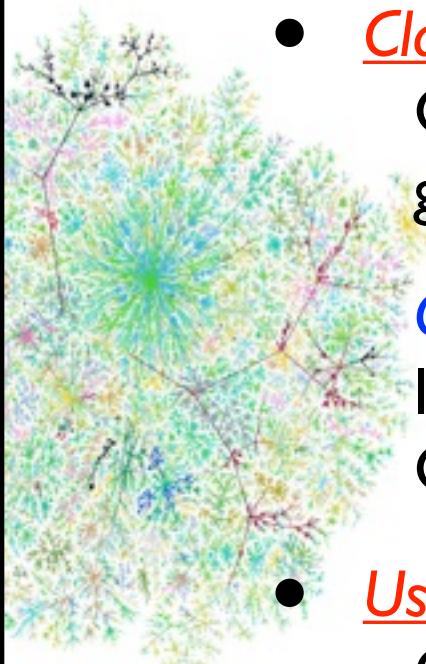
Massive Graphs

- Classic Big Graphs:
Call graph (5×10^8 nodes), web graph (5×10^{10} nodes), IP graph (2^{32} nodes), social networks (10^9 nodes), ...

Challenge: Can't use conventional algorithms on graphs this large. Sometimes can't even store graph in memory!
Graphs may be dynamic and/or distributed.



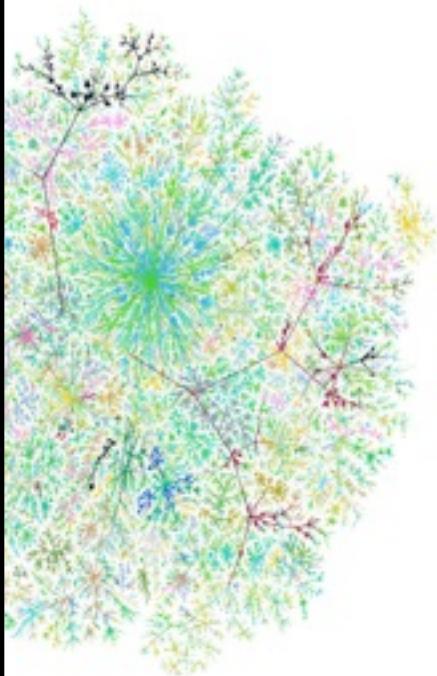
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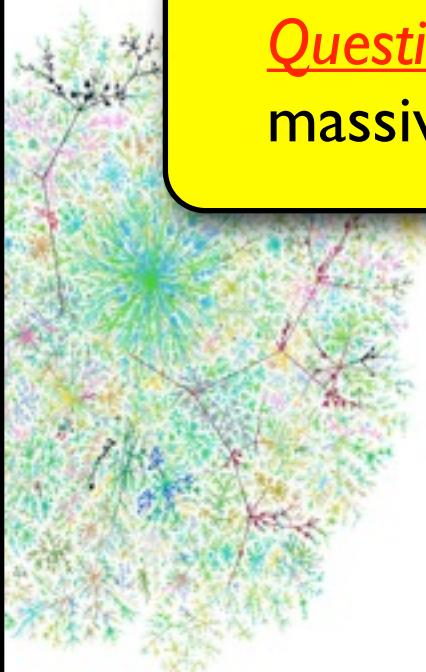
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Graphs may be dynamic and/or distributed.
- *Use Abstraction of Structure:*
Graphs are a natural way to encode structural information where we have data about both **basic entities** and their **relationships**. Examples include graphical networks, citation networks, protein interaction and metabolic networks, ...

Focus of Tutorial



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Question 2: How can we construct these synopses **efficiently**? In particular, what is the input is **streaming** or **distributed**?

- Tutorial focuses on the algorithmic and theoretical issues.
Consider arbitrary graphs rather than being domain specific.

[**This Talk:**](#) Definitions & Basic Building Blocks

[**Next Talk:**](#) Applications & Extensions



Mark and Erica are now friends.

 Like · Add Friend



Mark and Erica are no longer friends.

 Like · Add Friend



Eduardo and Mark are now friends.

 Like · Add Friend



Tyler and Cameron are friends with Mark.

 Like · Add Friend



Sean and Mark are now friends.

 Like · Add Friend



Eduardo and Mark are no longer friends.

 Like · Add Friend



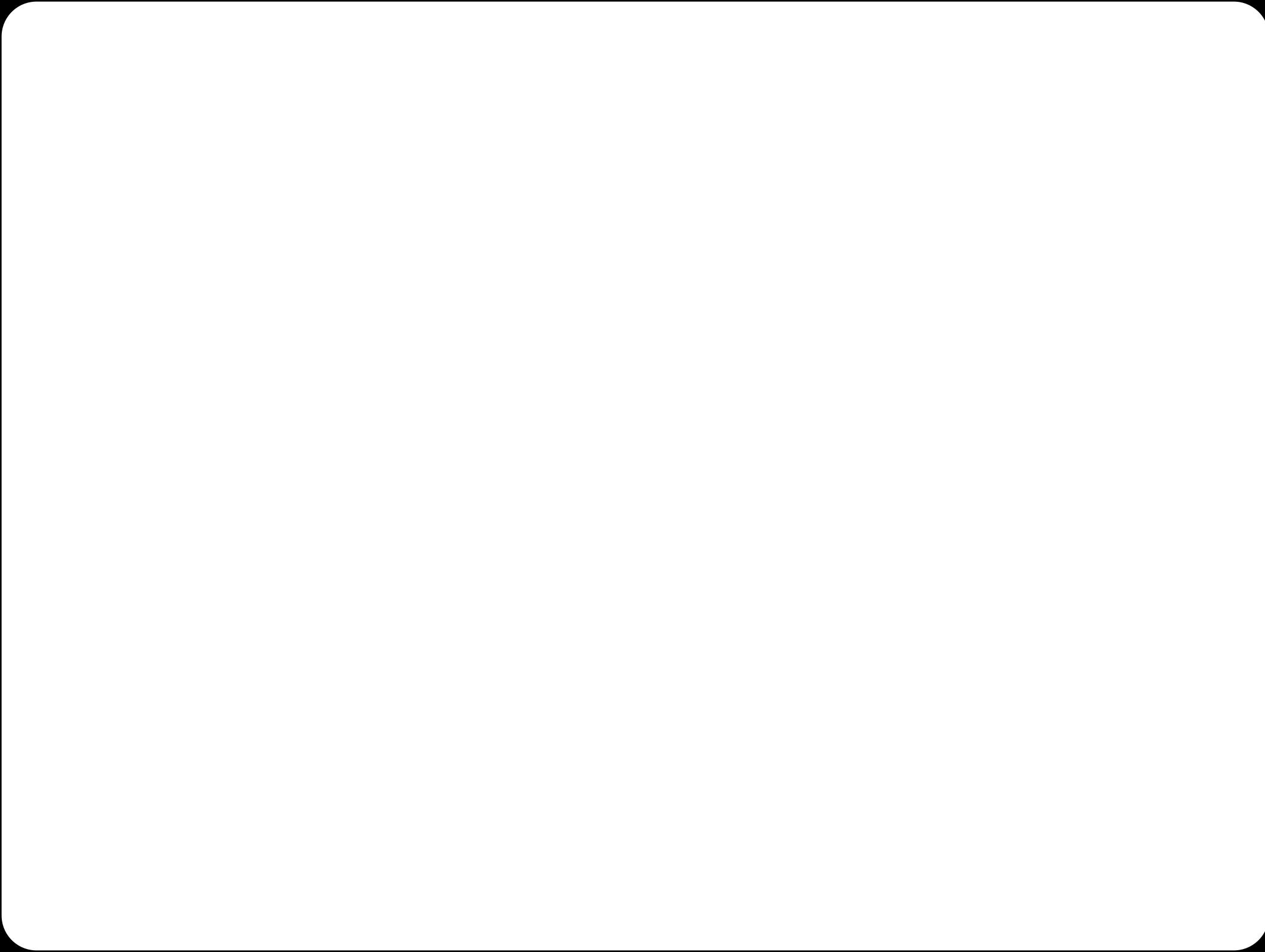
Tyler and Cameron are no longer friends with Mark.

 Like · Add Friend



Lawyers are now friends with everyone.

 Like · Add Friend



Data Streams

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- *Example:* Using $\tilde{O}(n)$ space, maintain connected components.

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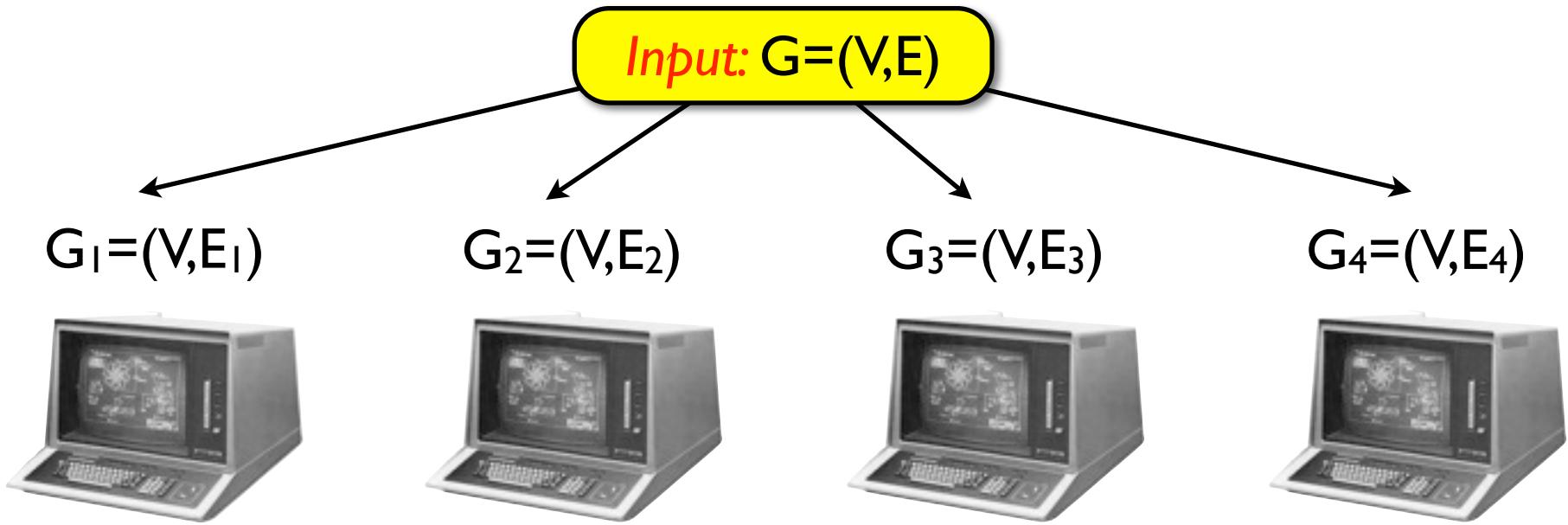
- *Input:* Observe stream of edges on n nodes added/deleted.
- *Example:* Using $\tilde{O}(n)$ space, maintain connected components.
- *Other Results:* Dense subgraphs, matchings, distances, clustering, partitioning and cuts, diameter, random walks, ...

e.g., [Feigenbaum, Kannan, McGregor, Suri, Zhang 2004, 2005], [McGregor 2005]
[Jowhari, Ghodsi 2005], [Zelke 2008], [Sarma, Gollapudi, Panigrahy 2008, 2009]
[Eggert, Kliemann, Srivastav 2009], [Epstein, Levin, Mestre, Segev 2009]
[Ahn, Guha 2009, 2011], [Kelner, Levine 2011], [Goel, Kapralov, Khanna 2012]

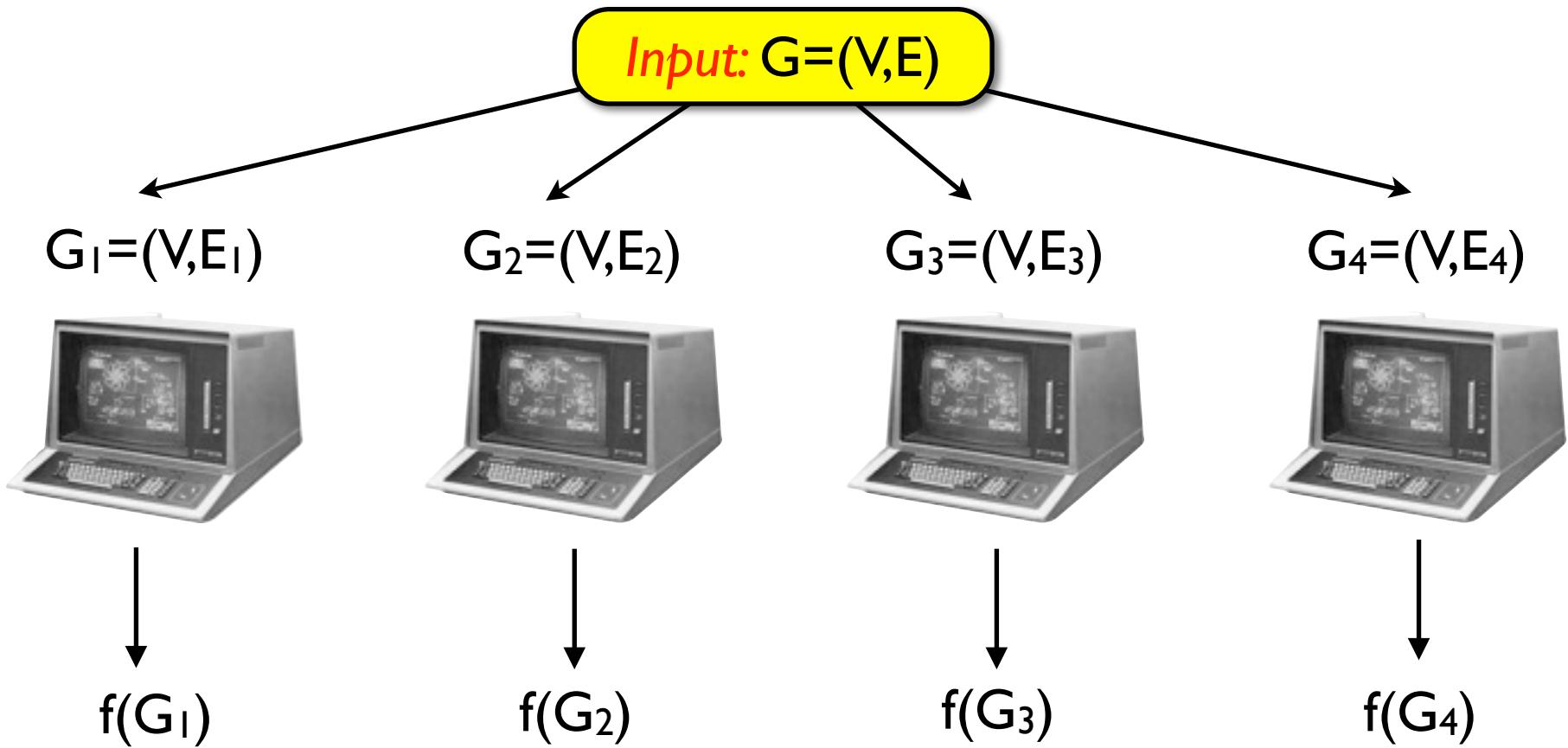
Distributed Processing

Input: $G=(V,E)$

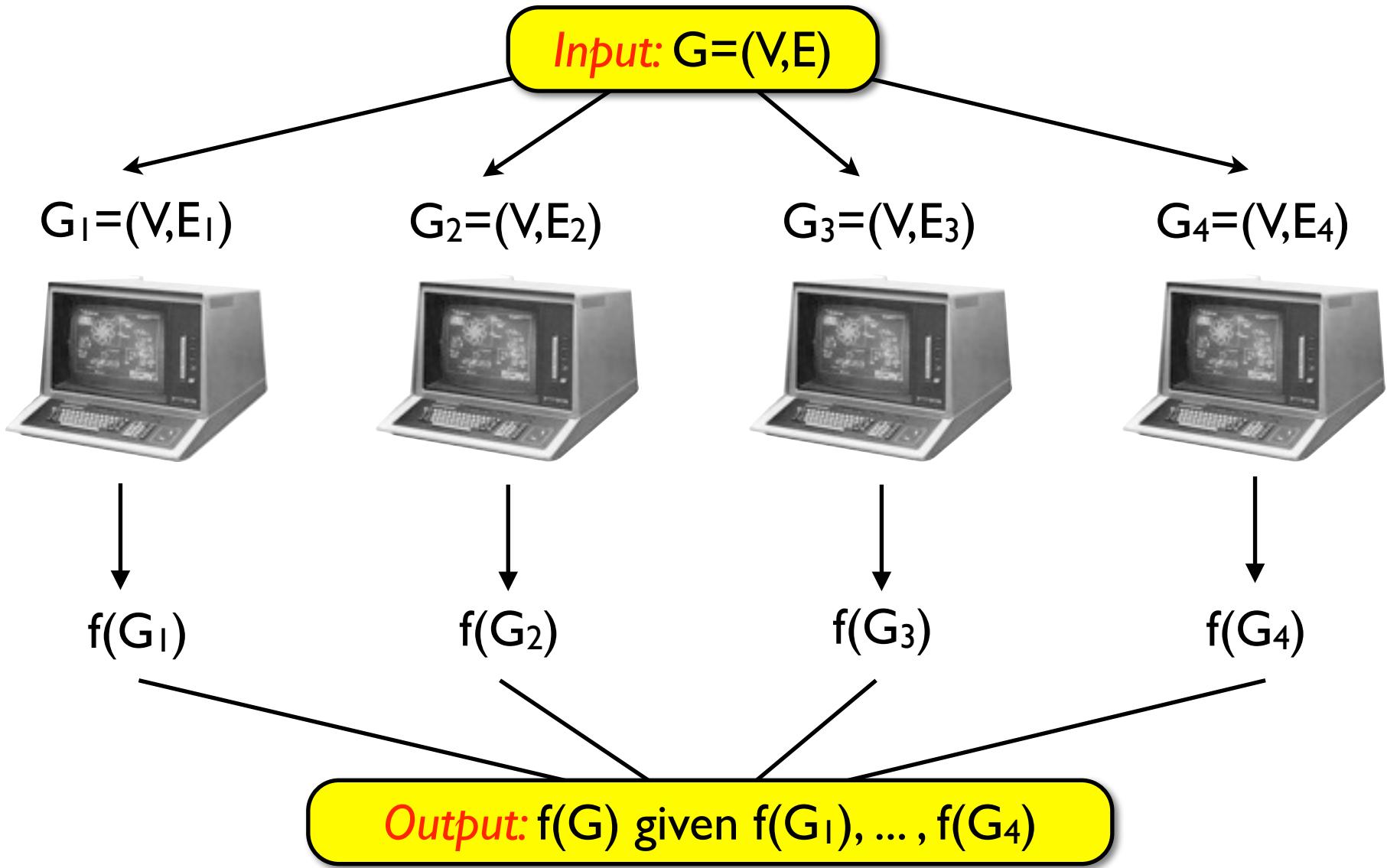
Distributed Processing



Distributed Processing



Distributed Processing





I. Spanners



II. Sparsifiers



III. Sketches



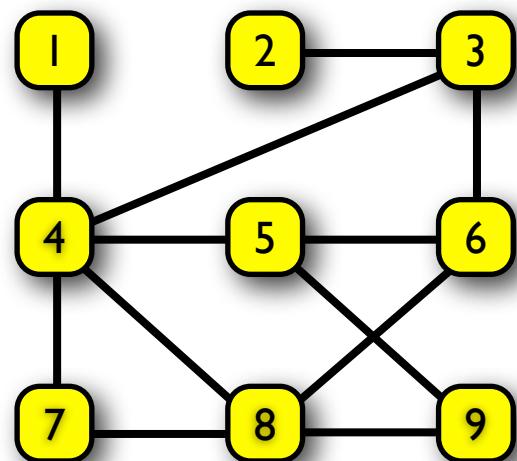
I. Spanners

*Synopsis for Distance Estimation
“Greedy” Stream Algorithm
Extensions*

Spanners & Distances

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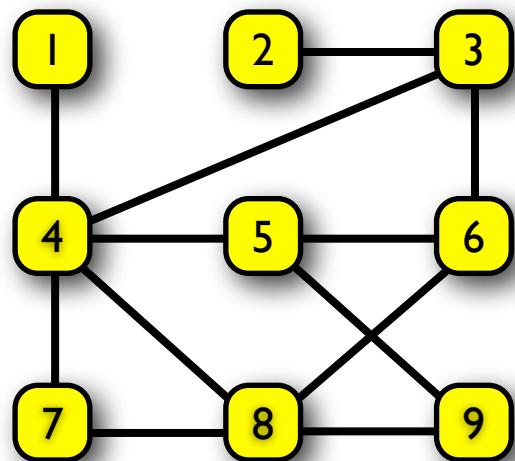
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Original Graph G

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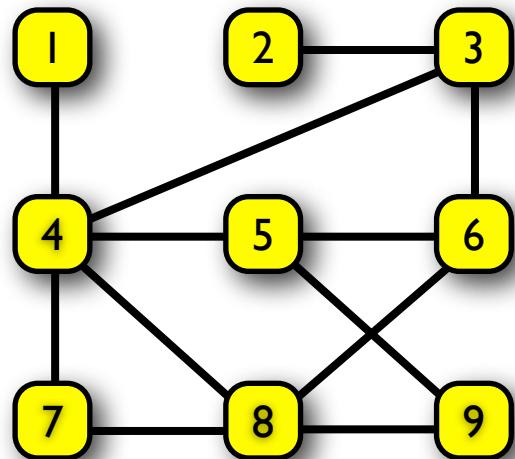


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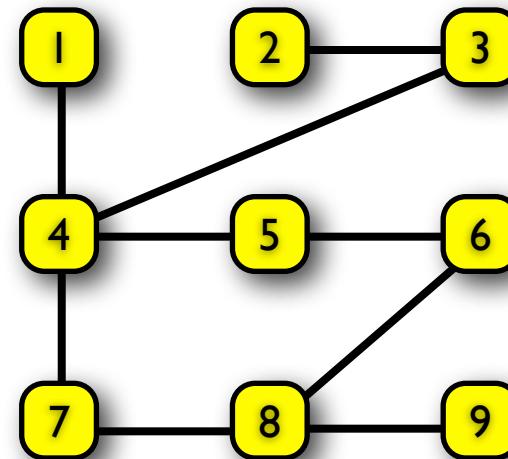
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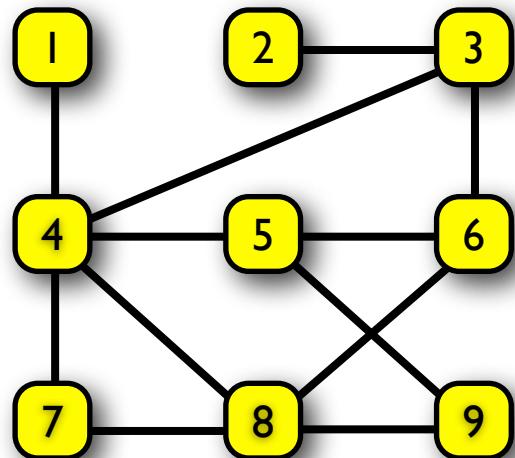


Spanner Graph H

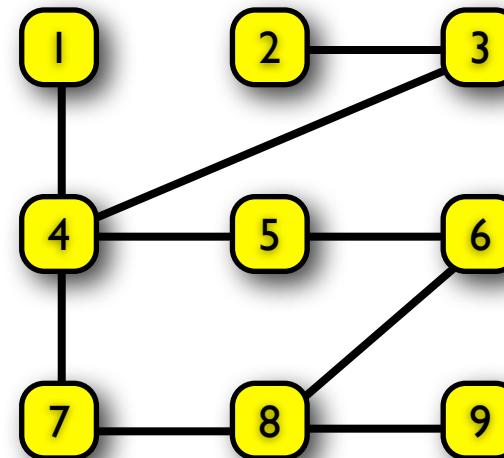
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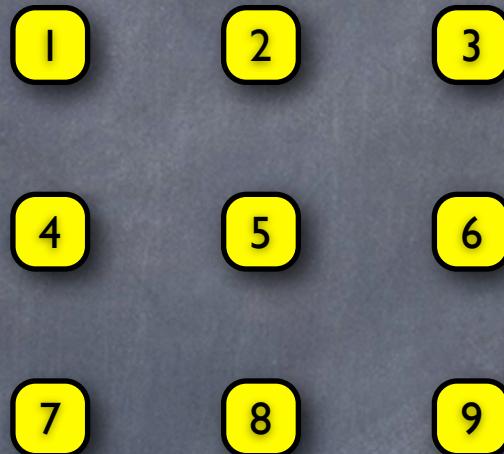


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- Thm: Streaming construction using $O(n^{1+2/(k+1)})$ space.

Spanner: Algorithm

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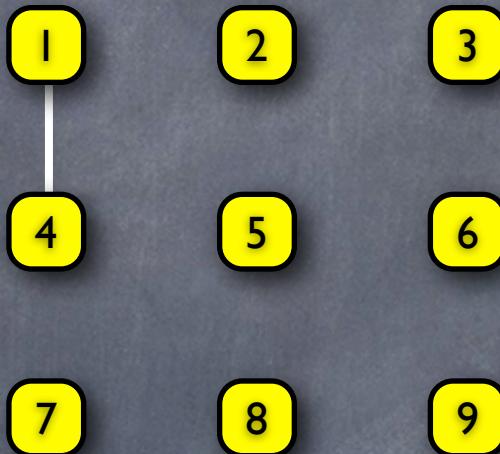


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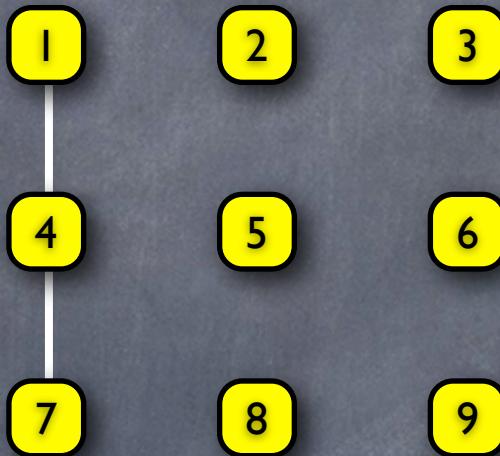
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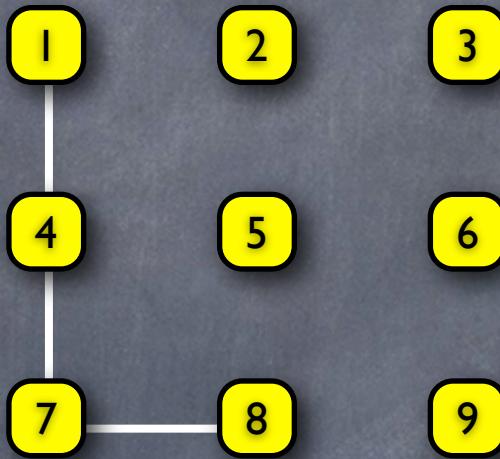
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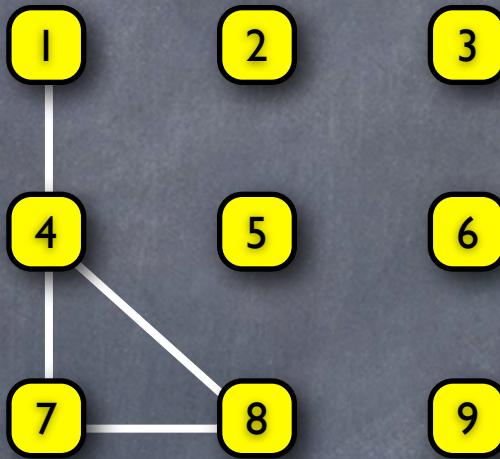
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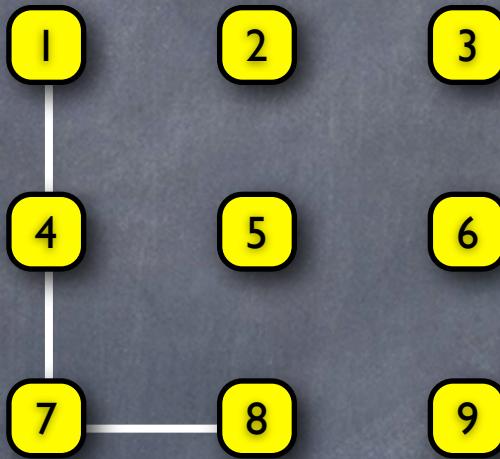
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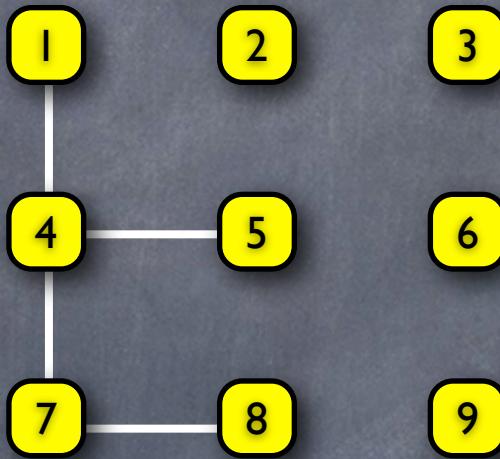
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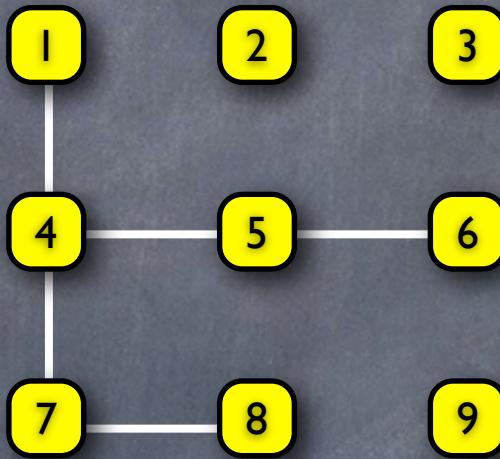
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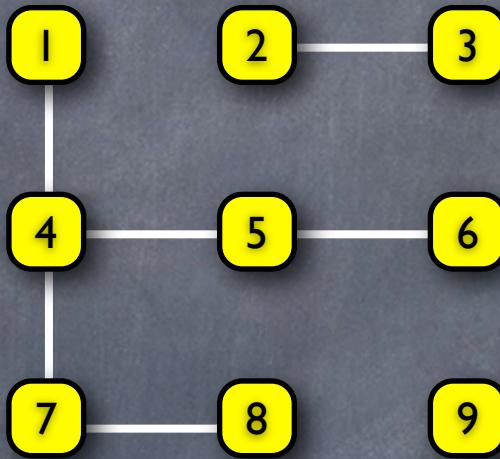
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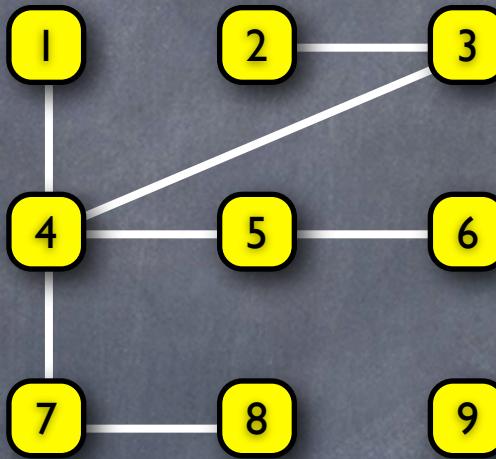
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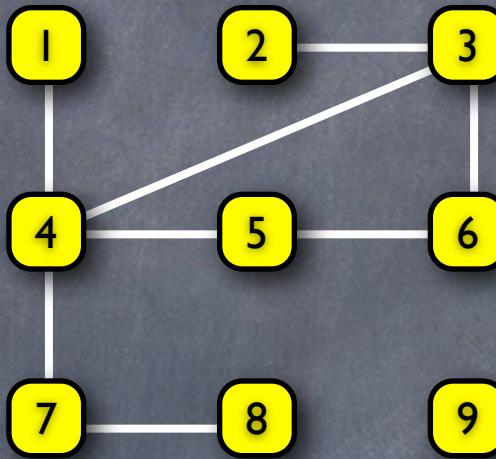
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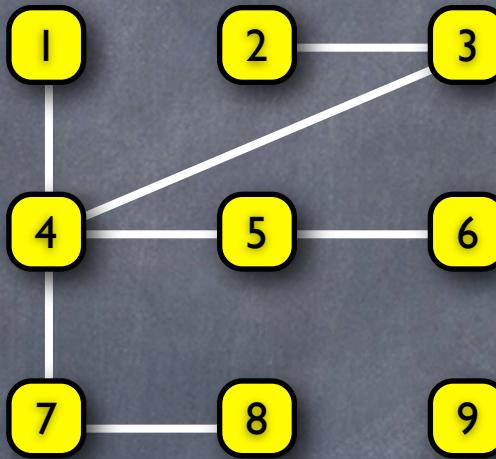
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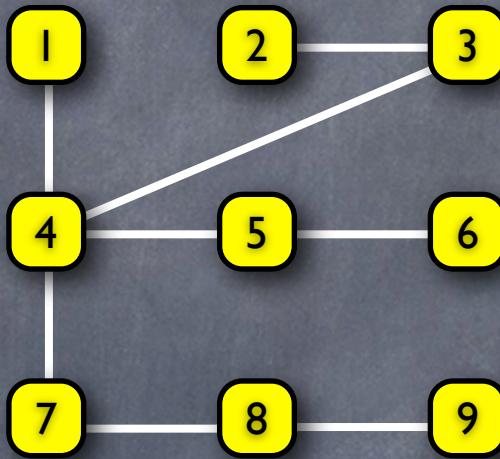
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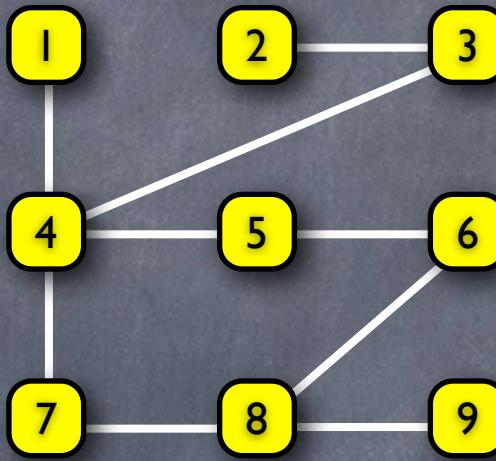
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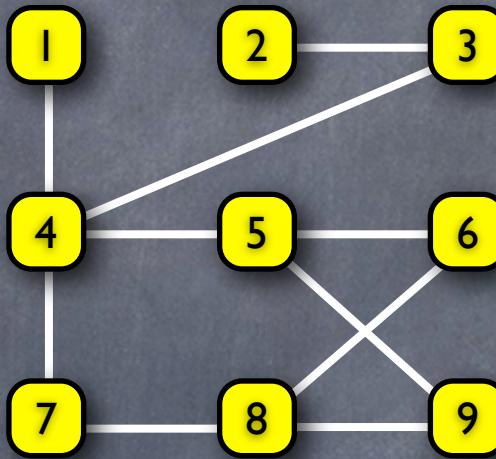
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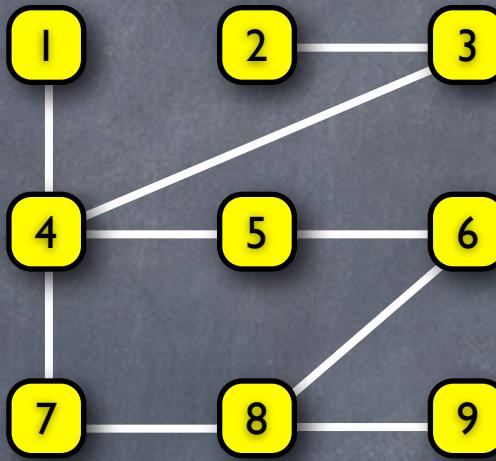
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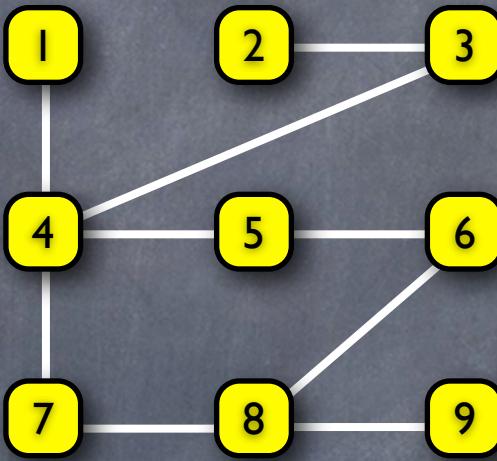
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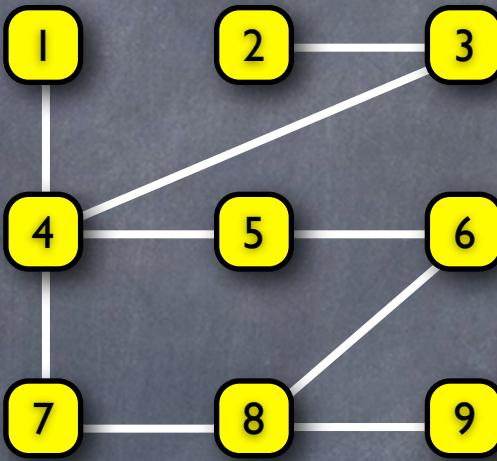
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- Lemma: $O(n^{3/2})$ edges stored since shortest cycle among stored edges has length at least 5.

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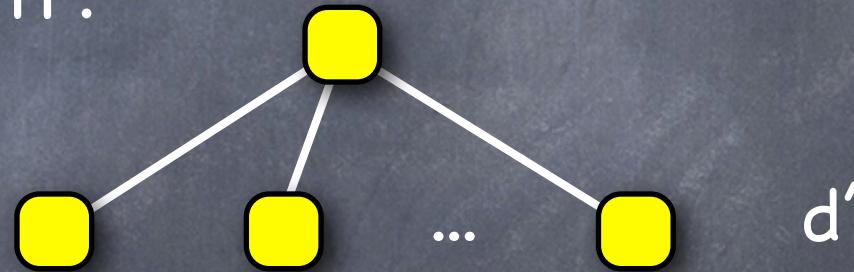
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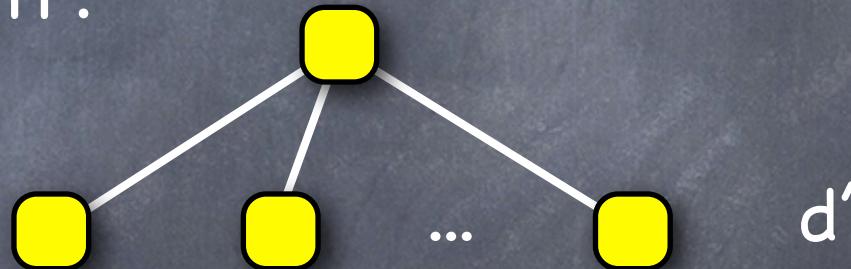
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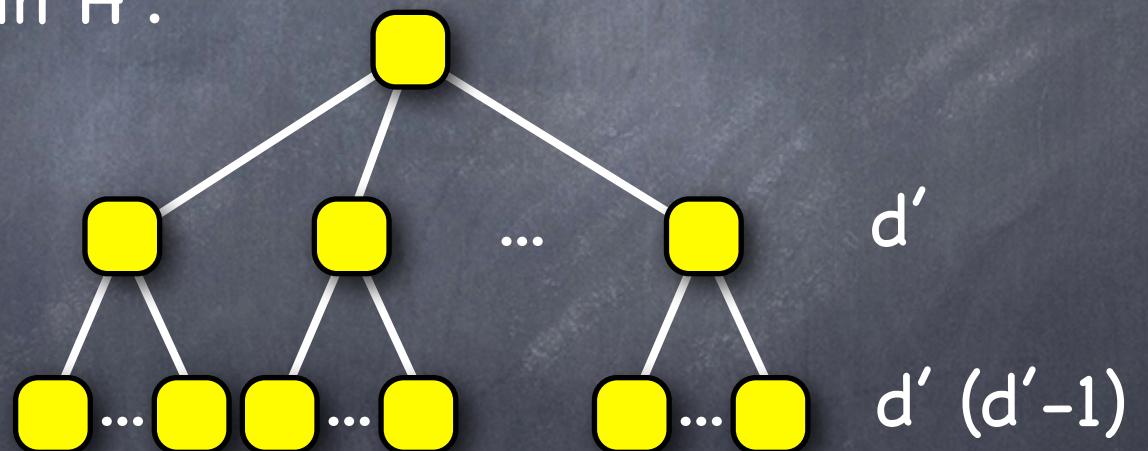
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Spanners Summary

- Thm: There's a $O(n^{1+1/t})$ -space stream algorithm returns a $(2t-1)$ -spanner. [Feigenbaum, Kannan, McGregor, Suri, Zhang 05]
- Extension: Can process weighted graphs by rounding weights and constructing spanners for each weight class.





I. Spanners



II. Sparsifiers



III. Sketches



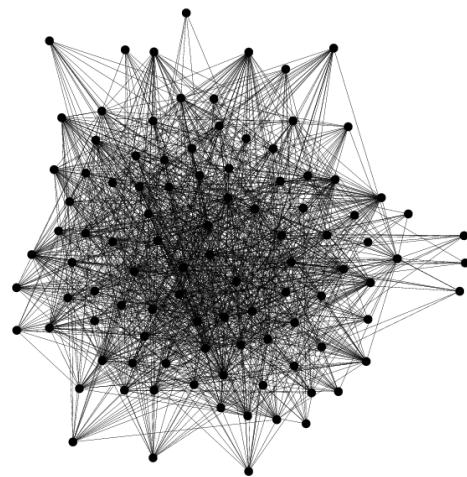
II. Sparsifiers

*Synopsis for Cut Estimation
Merge-Reduce Stream Algorithm
Extensions*

Sparsifiers & Cuts

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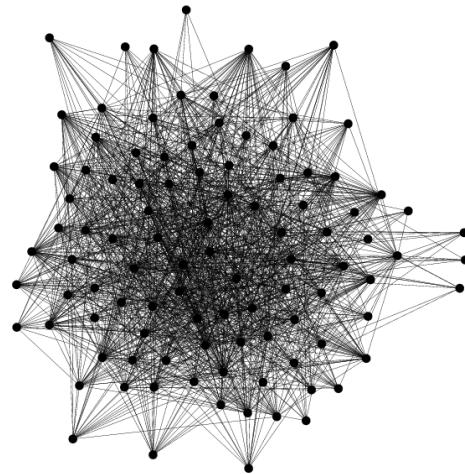
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Original Graph G

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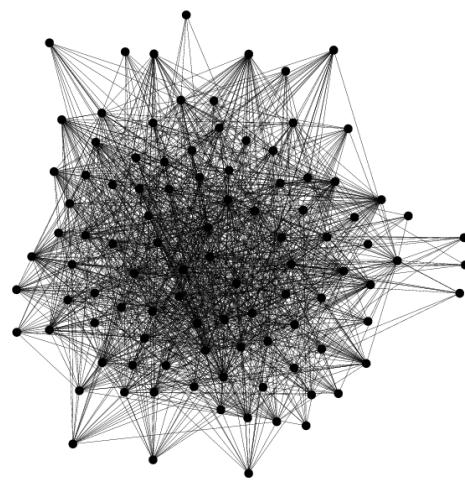


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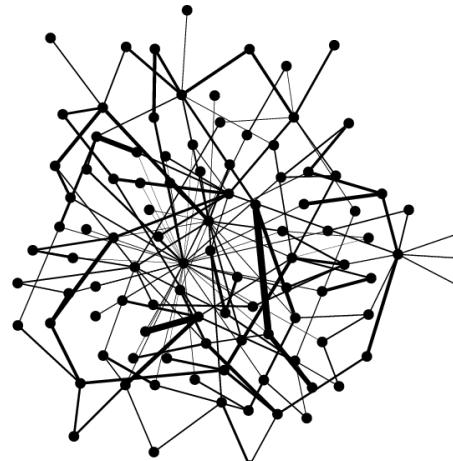
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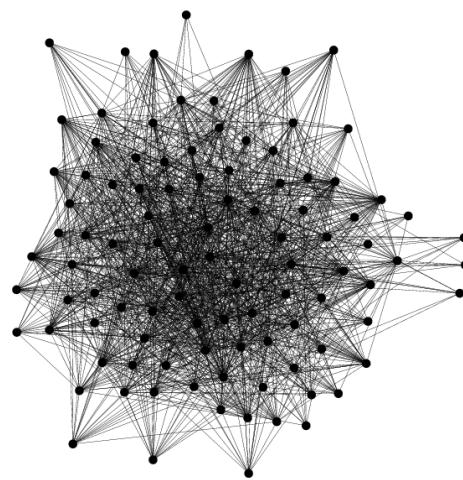
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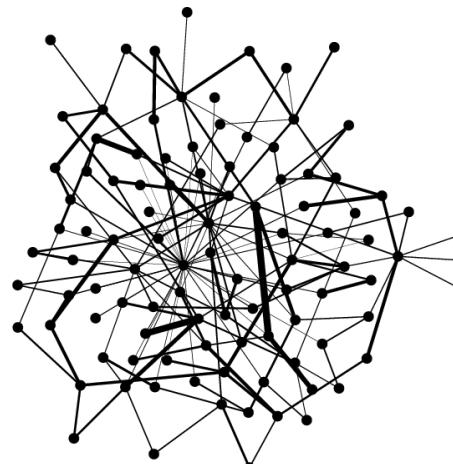
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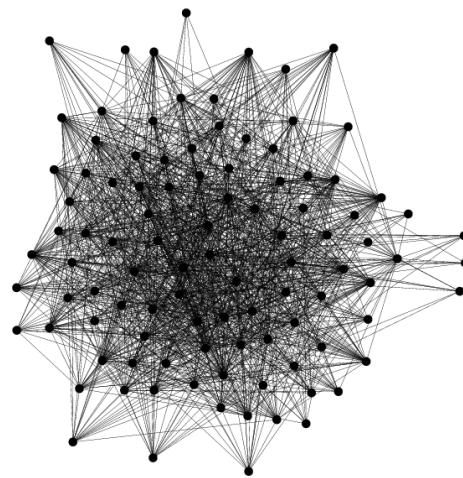


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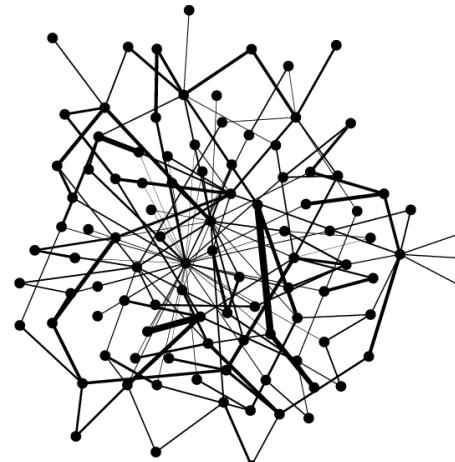
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- Thm: Streaming construction in $O(\varepsilon^{-2} n \log^3 n)$ space.

Sparsifier: Algorithm

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- ⦿ **Main Idea:** Segment stream as E_1, E_2, \dots each of size $O(\epsilon^{-2}n)$. Let H_1 be $(1+\gamma)$ sparsifier of $E_1 \cup E_2$ etc.

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E_1

E_2

E_3

E_4

E_5

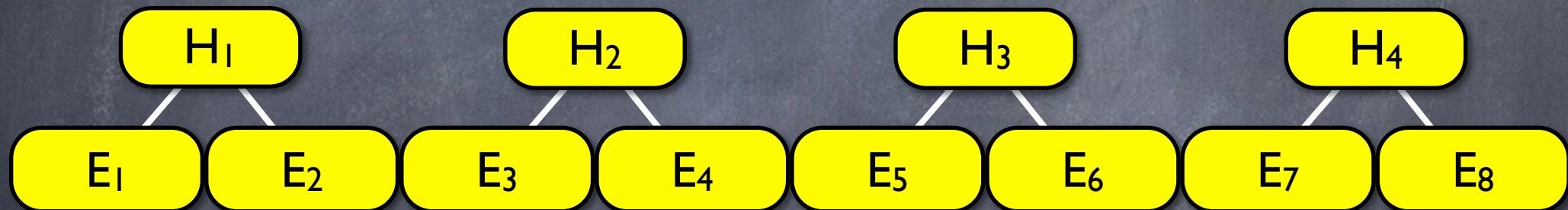
E_6

E_7

E_8

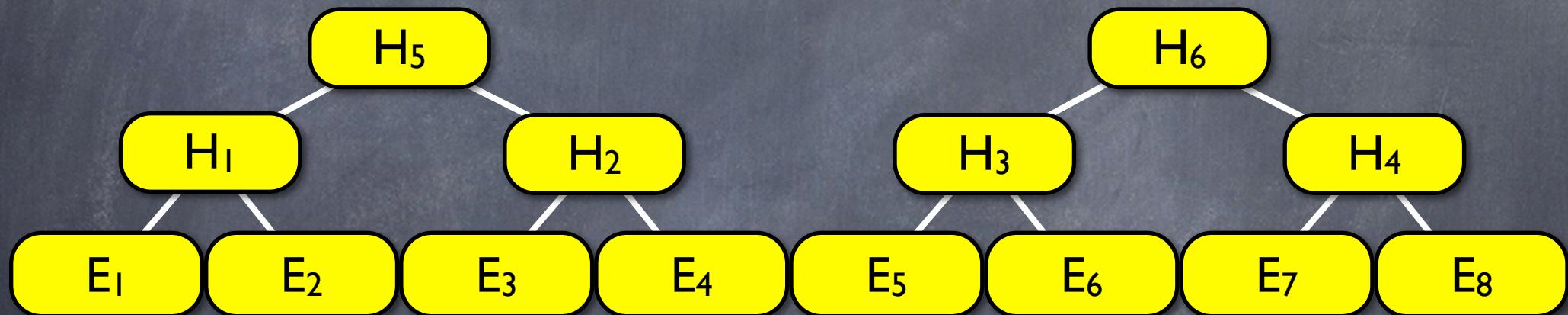
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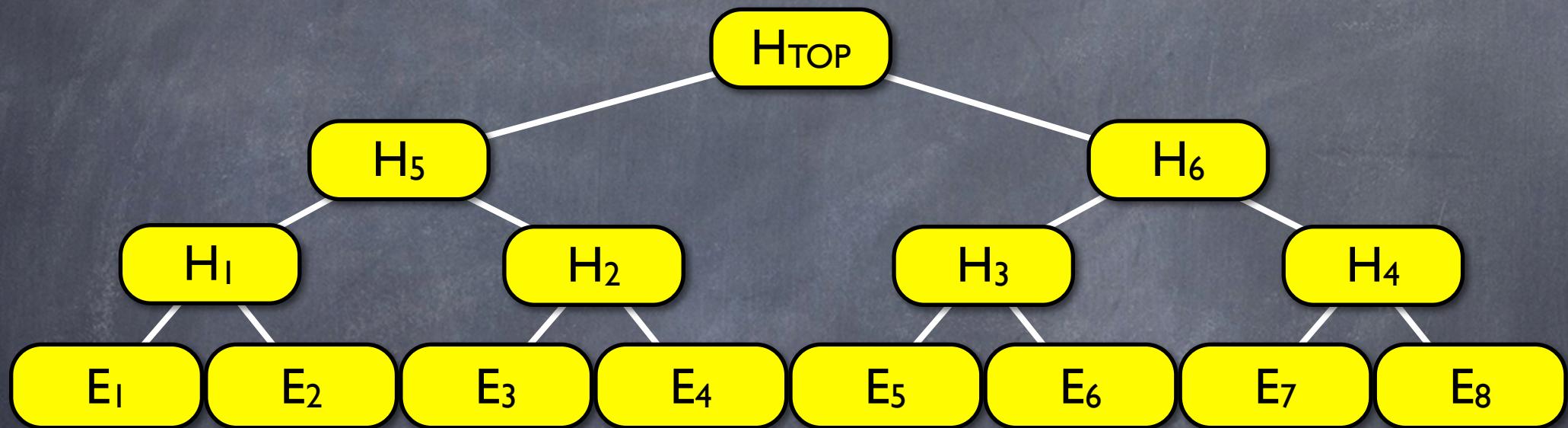
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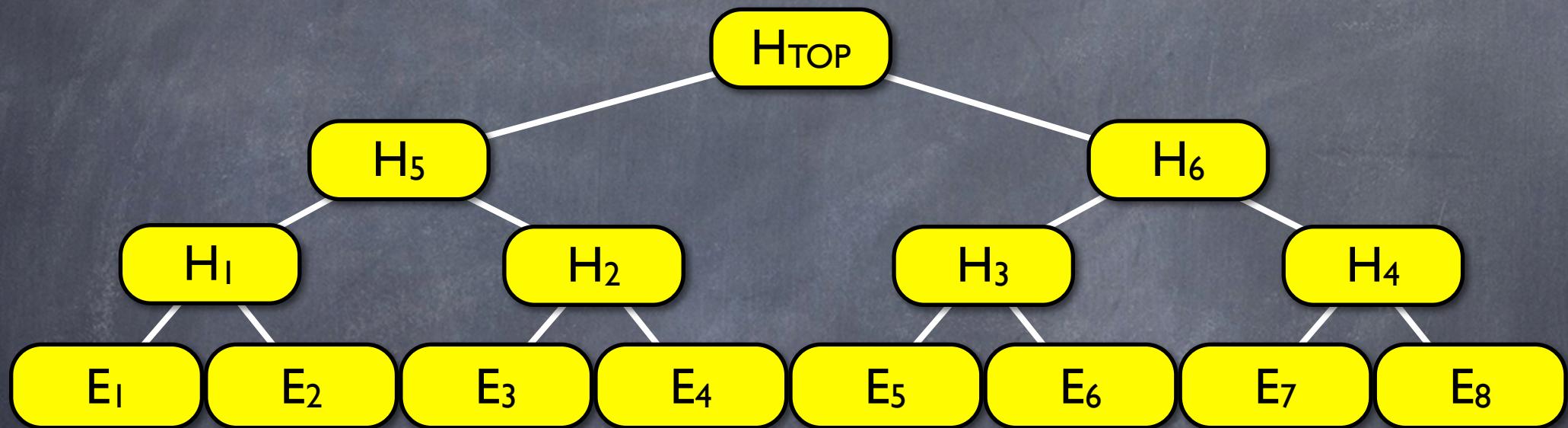
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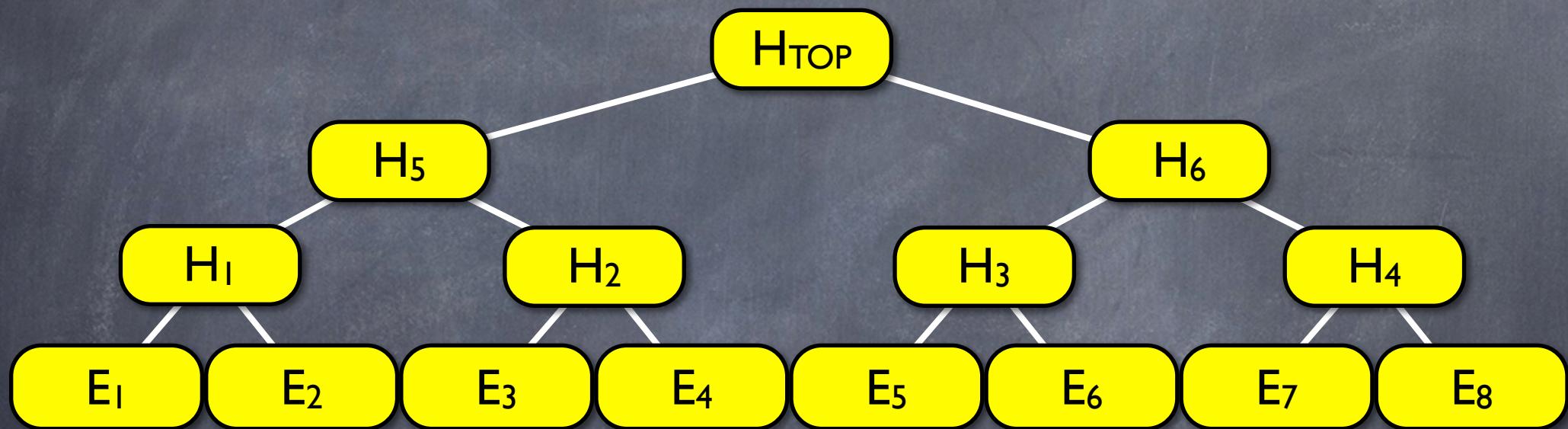
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- **Lemma:** H_{TOP} is a $(1+\gamma)^d$ sparsifier for $d=O(\log n)$. Setting $\gamma = O(\varepsilon/\log n)$ yields a $(1+\varepsilon)$ sparsifier.

Sparsifier: Algorithm

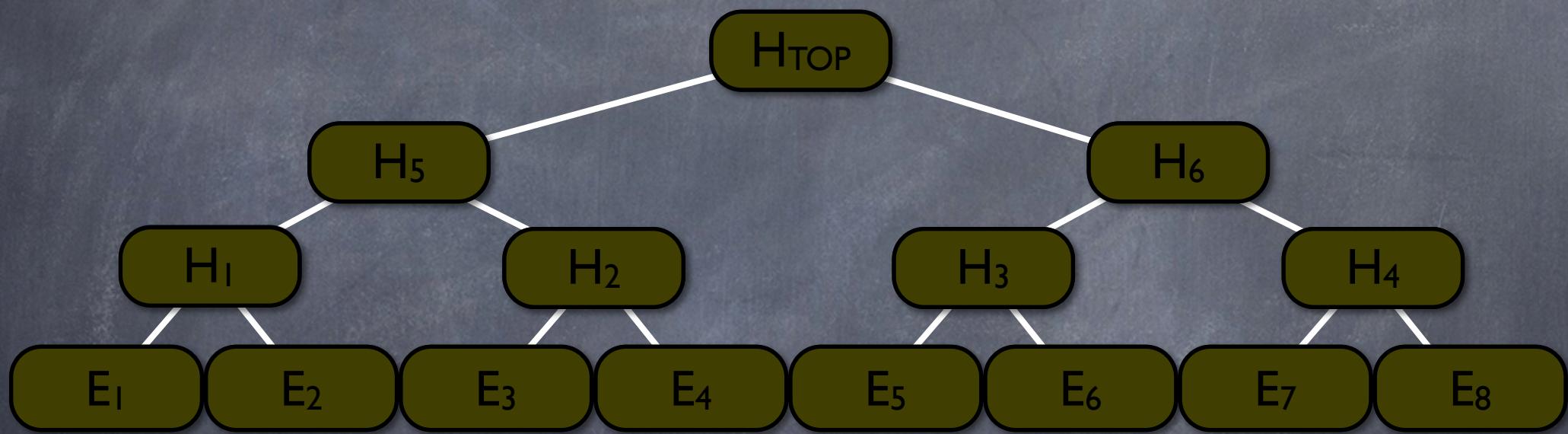
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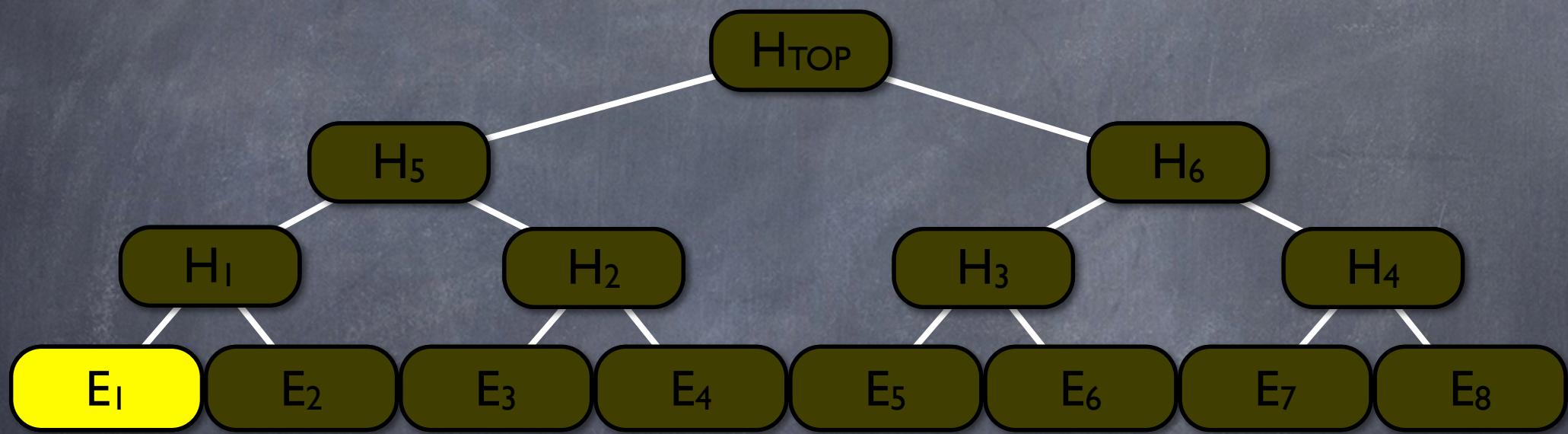
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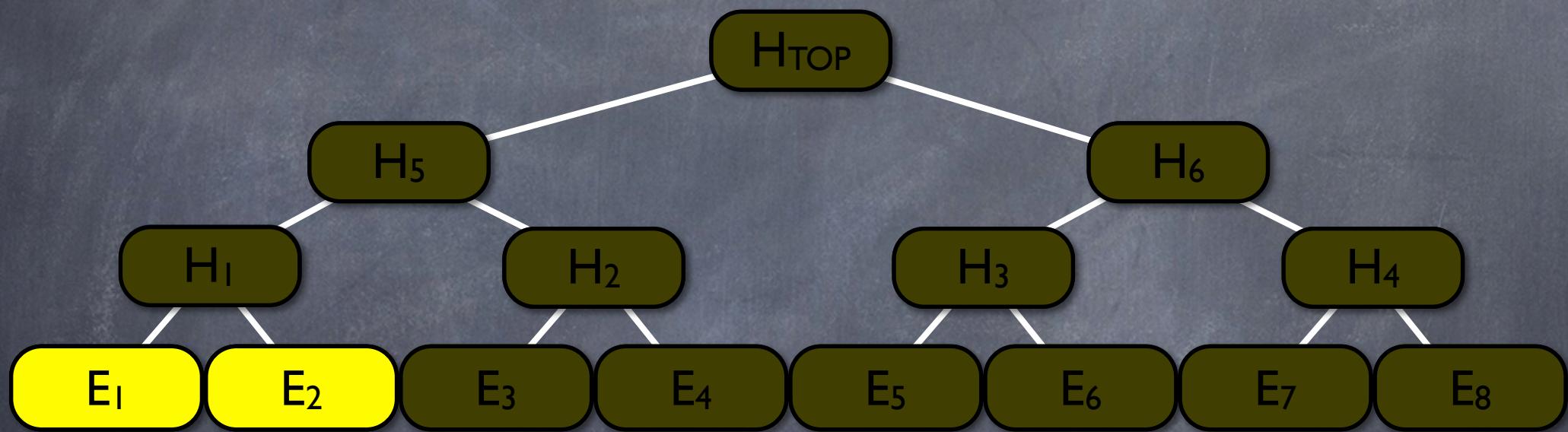
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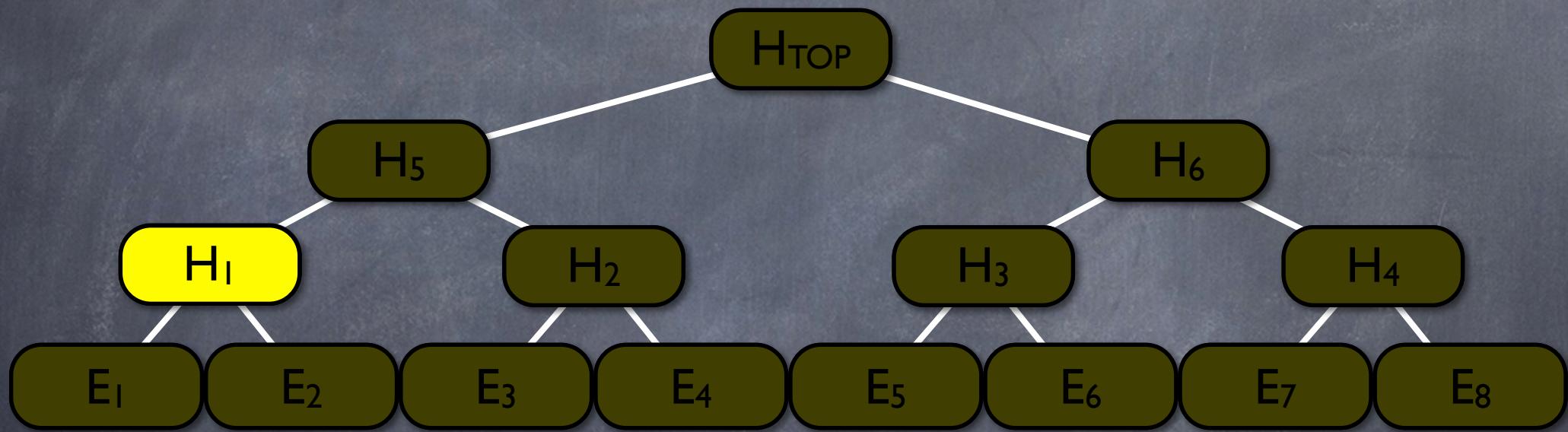
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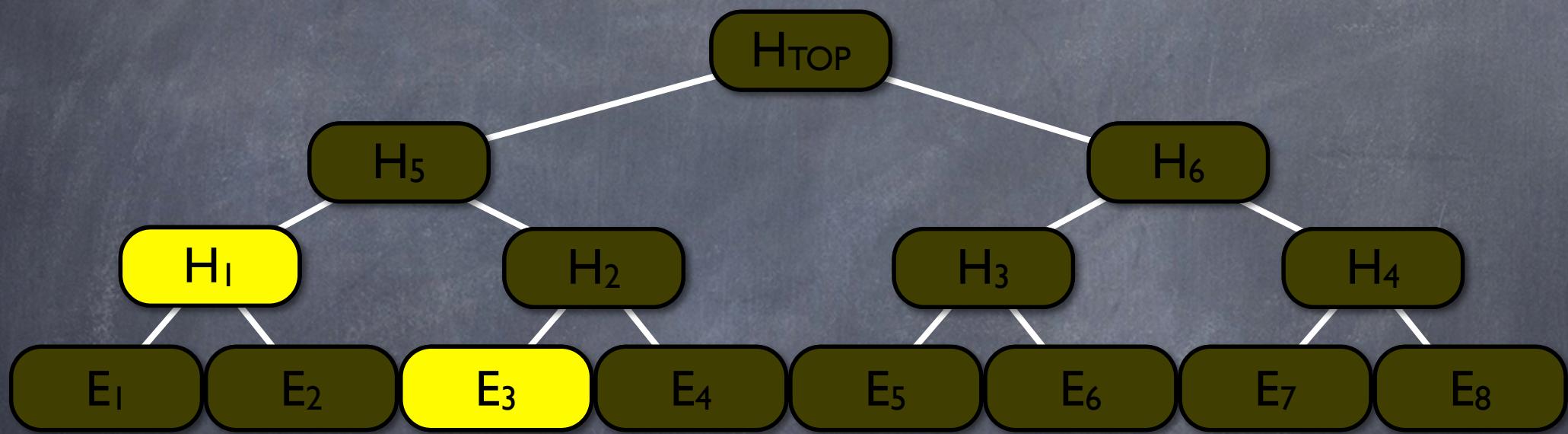
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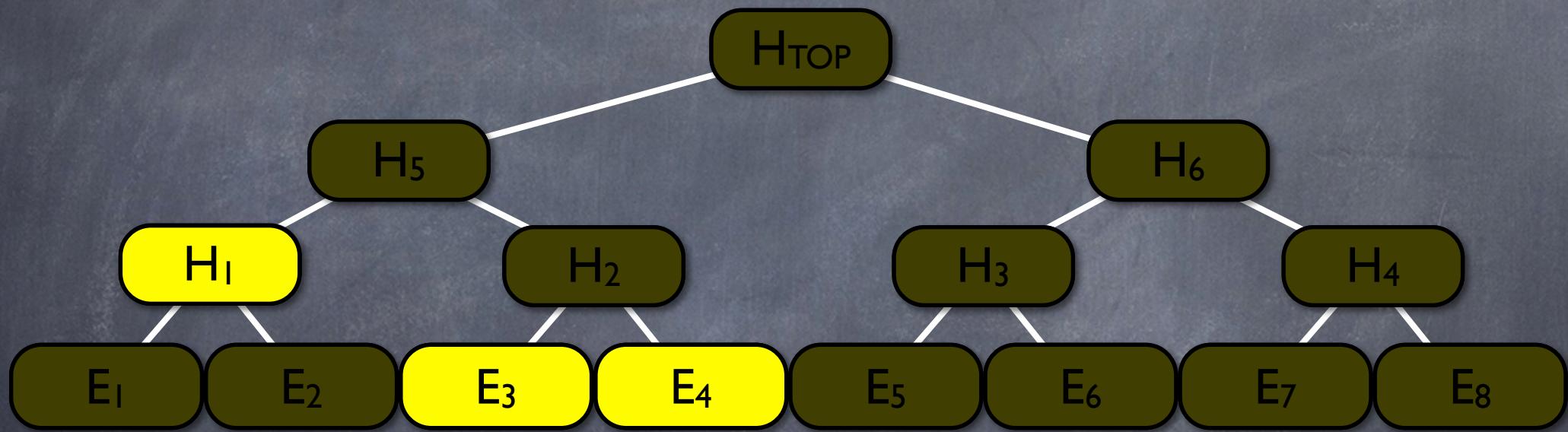
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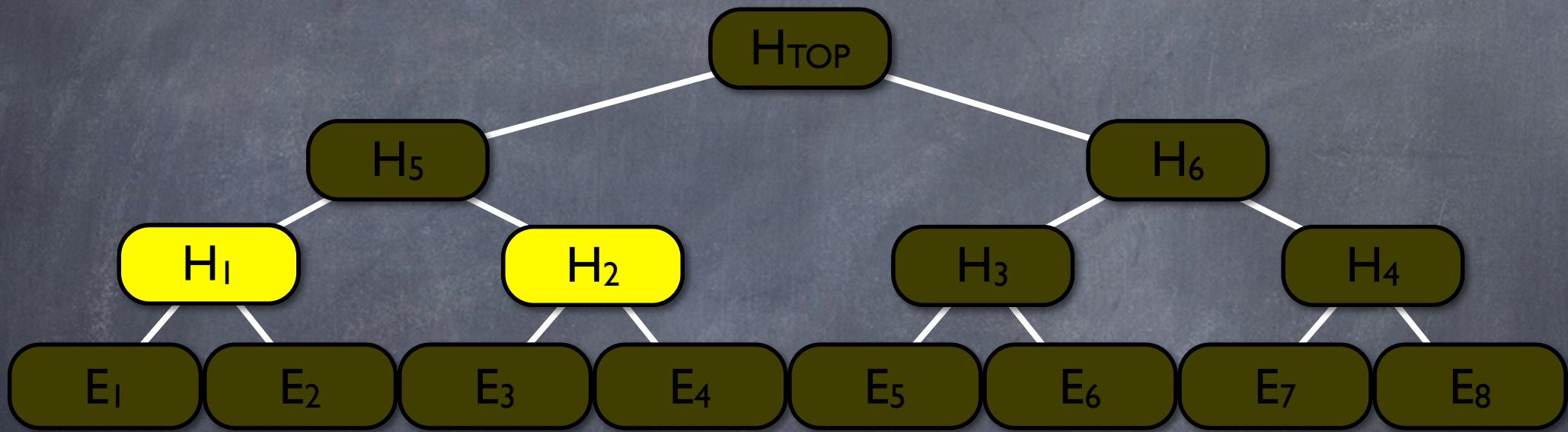
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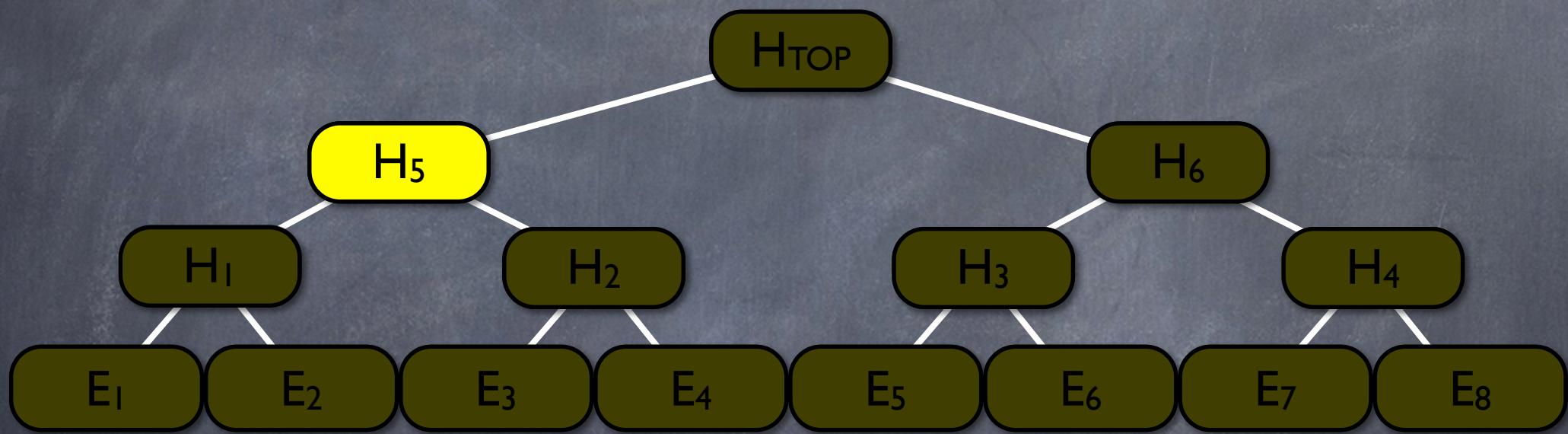
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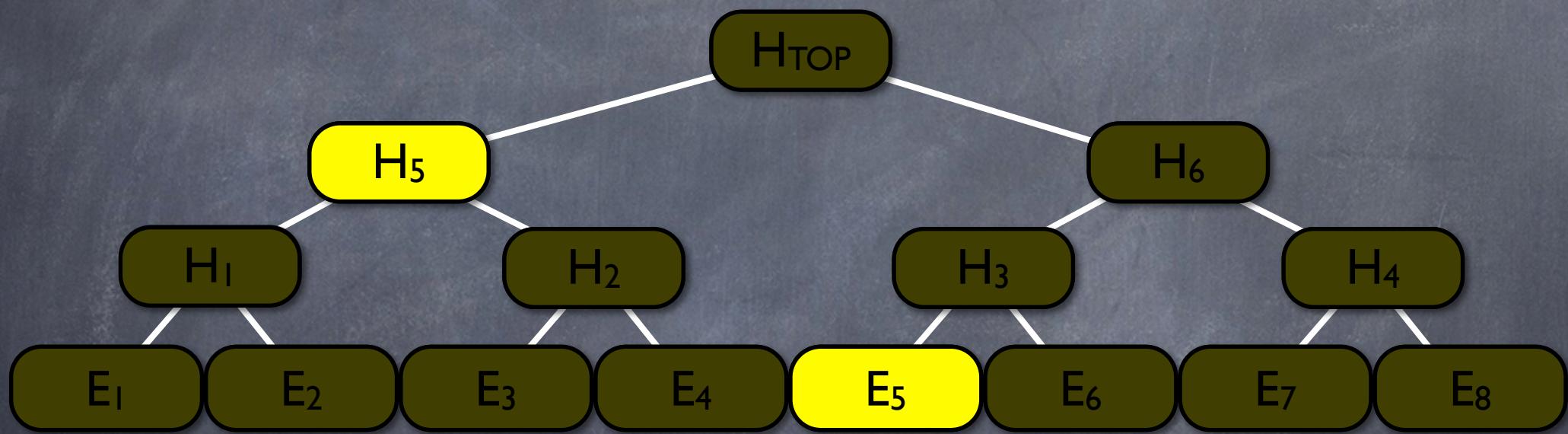
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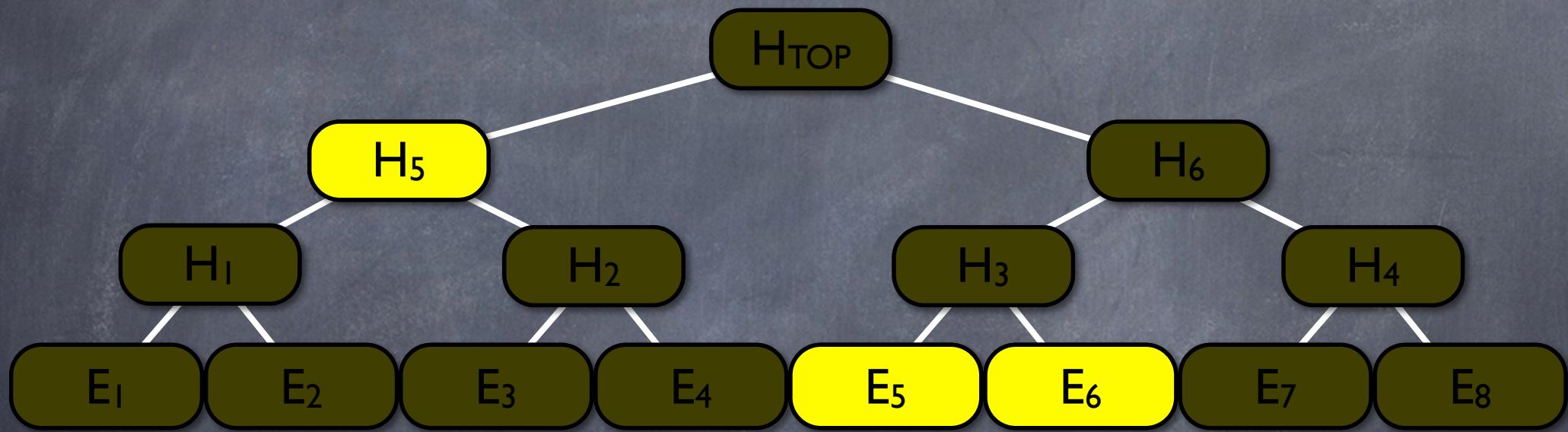
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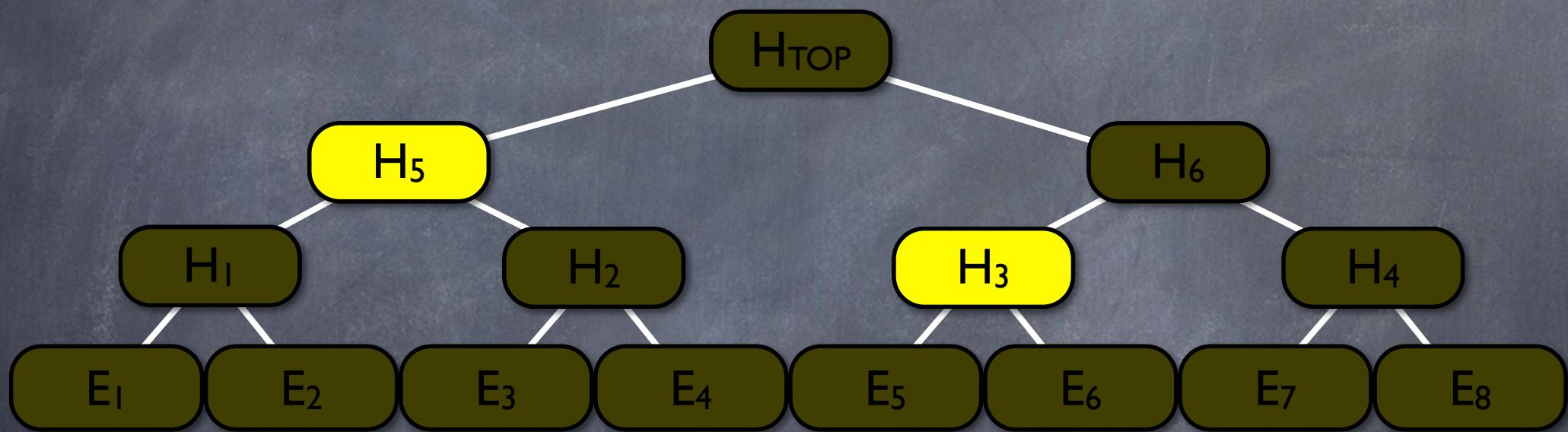
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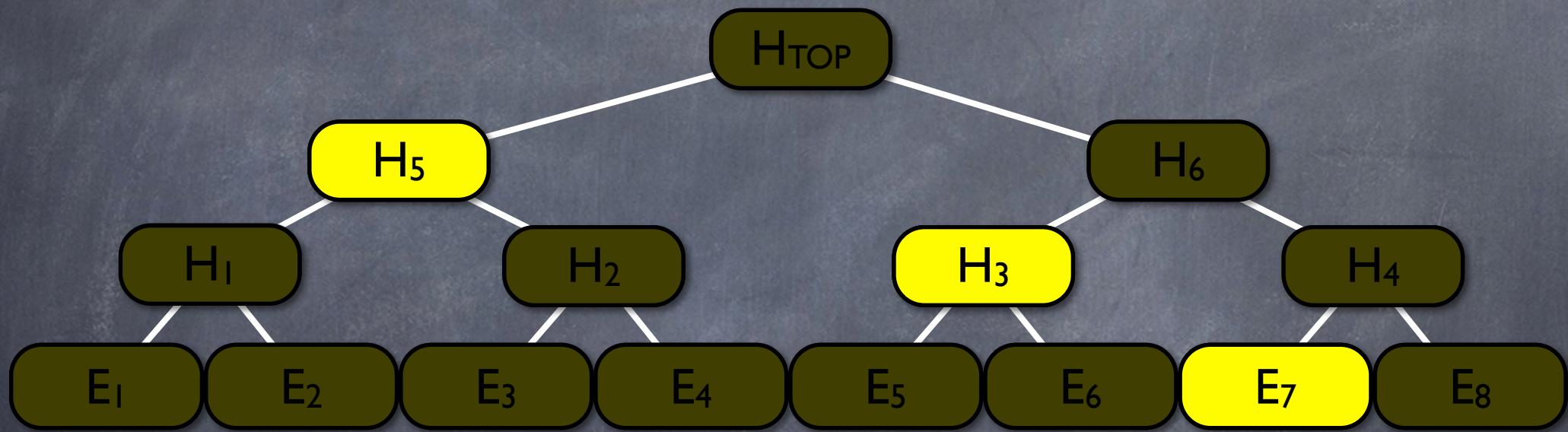
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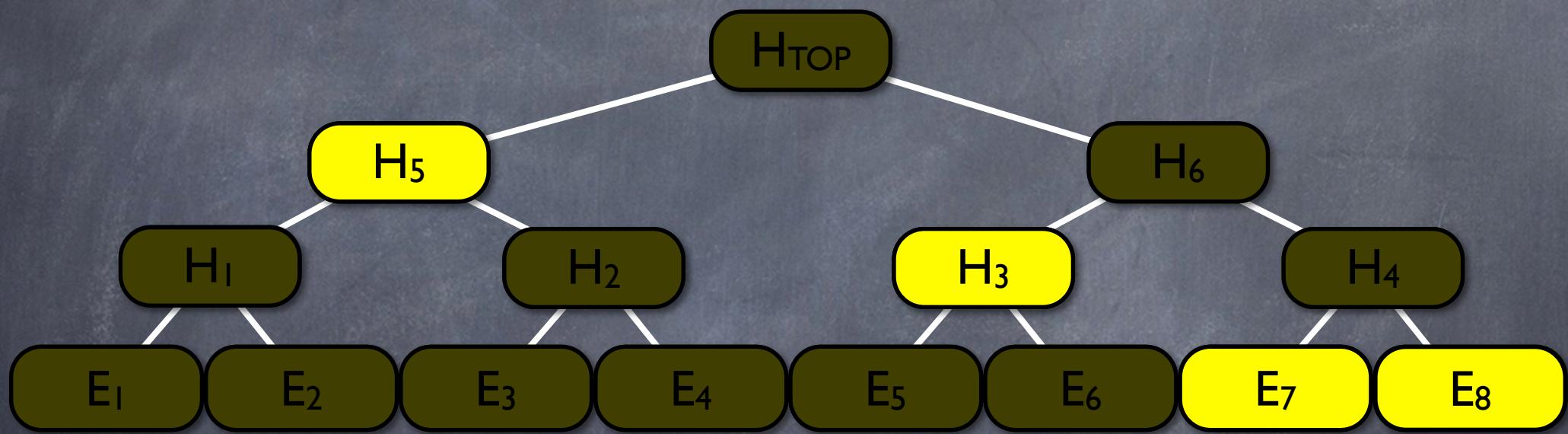
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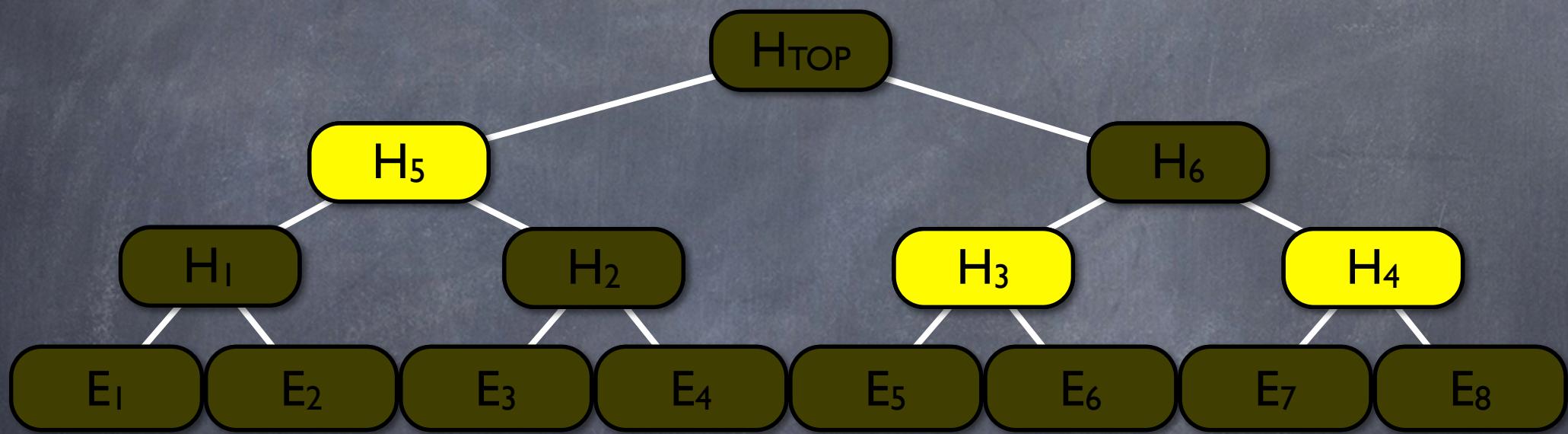
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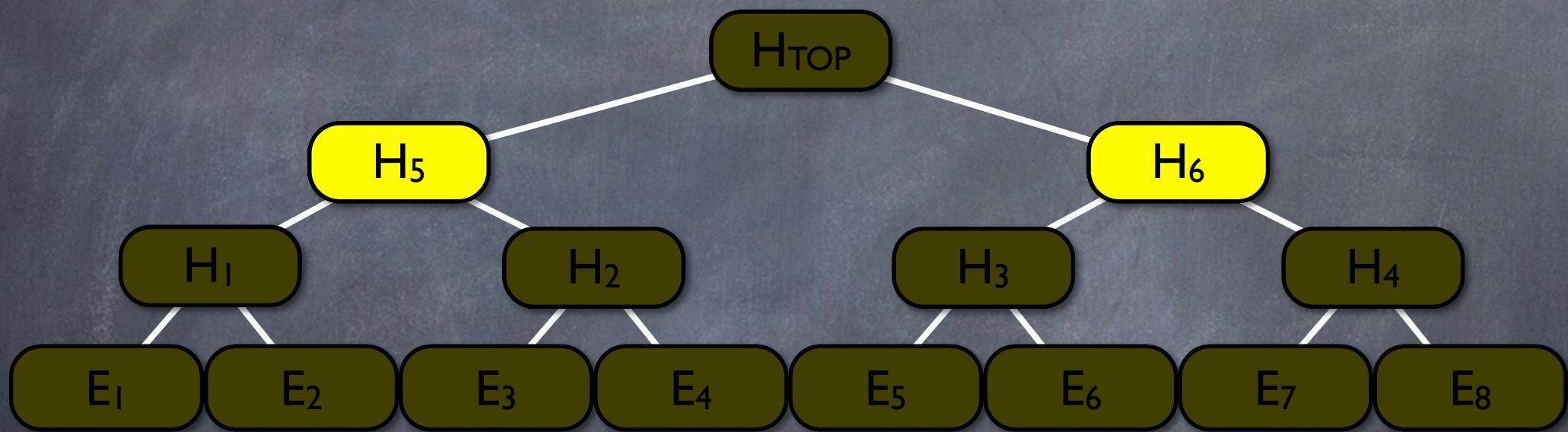
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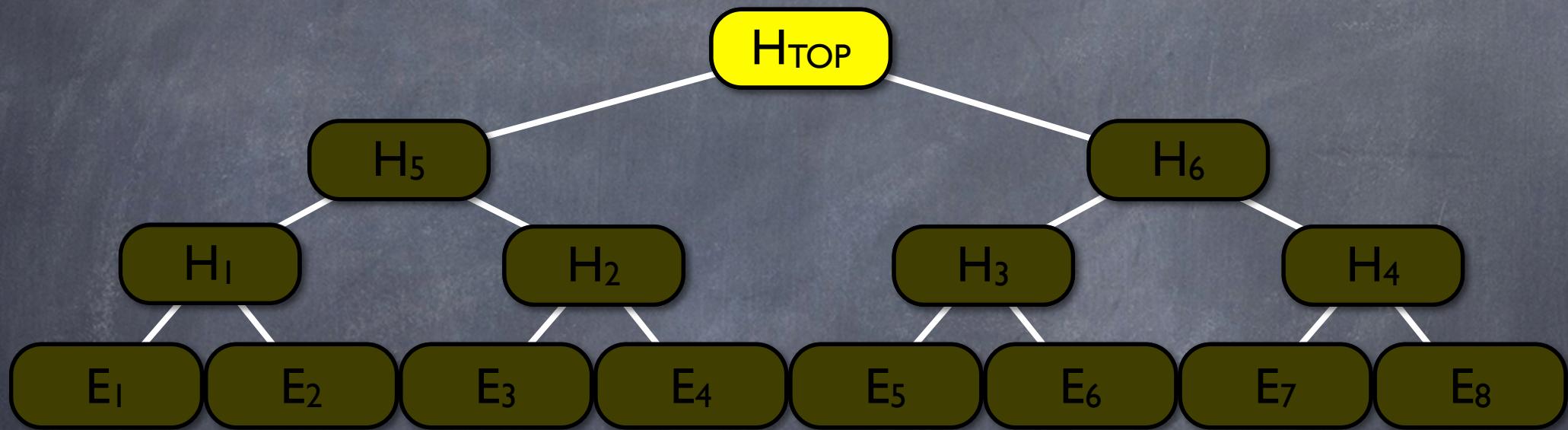
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Sparsifier Summary

- *Thm:* A $(1+\varepsilon)$ sparsifier of a graph can be constructed in $O(\varepsilon^{-2} n \text{ polylog } n)$ space.
[Ahn, Guha 09], [Goel, Kapralov, Khanna 10], [Sidiropoulos 10]
- Generalizes to spectral sparsification which preserves properties relating to random walks. [Kelner, Levin 11]





I. Spanners



II. Sparsifiers



III. Sketches



III. **Sketches**

*Family of Linear Synopses
Distributed & Supports Deletions
Two Connectivity Examples*

Linear Sketches

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$$\begin{bmatrix} v \end{bmatrix}$$

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- Random linear projection: $M: \mathbb{R}^n \rightarrow \mathbb{R}^k$ (where $k \ll n$) that preserves properties of any $v \in \mathbb{R}^n$ with high probability.

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? Question: What about analyzing massive graphs via sketches?

Distributed Data



...

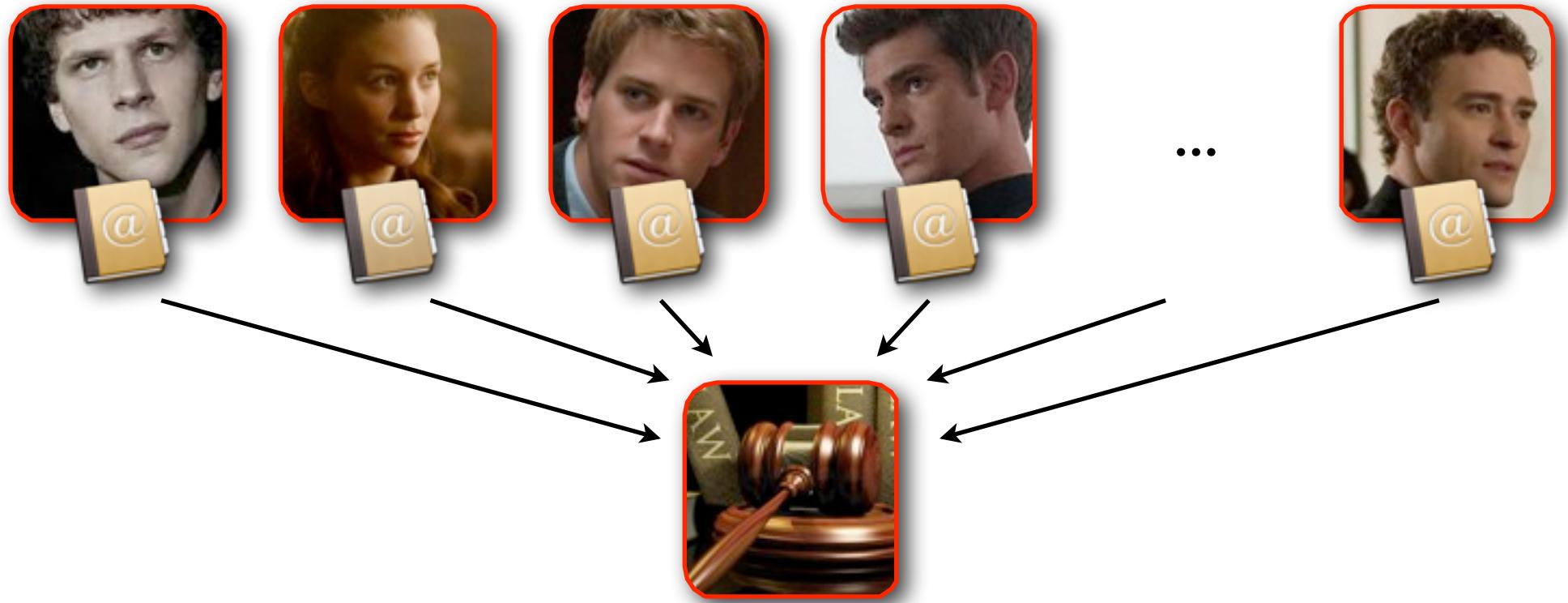


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Distributed Data



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- ***Goal:*** Simultaneously, each player sends $O(\text{polylog } n)$ bits to a central player who then determines if graph is connected.

This can't be possible?!



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 - c) Participants may have $\Omega(n)$ friends.

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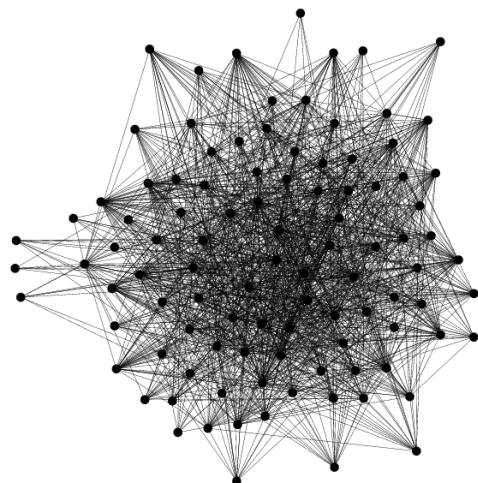
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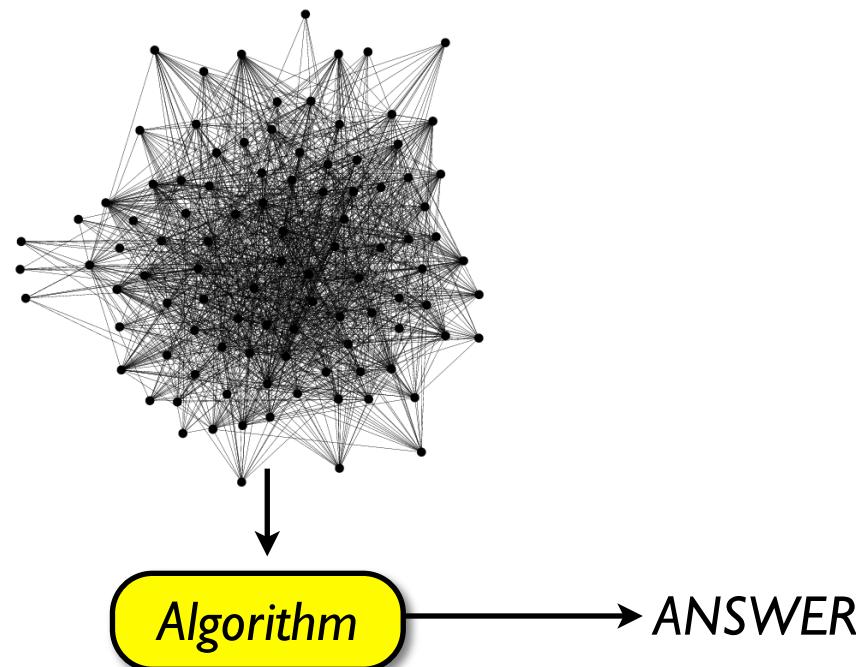
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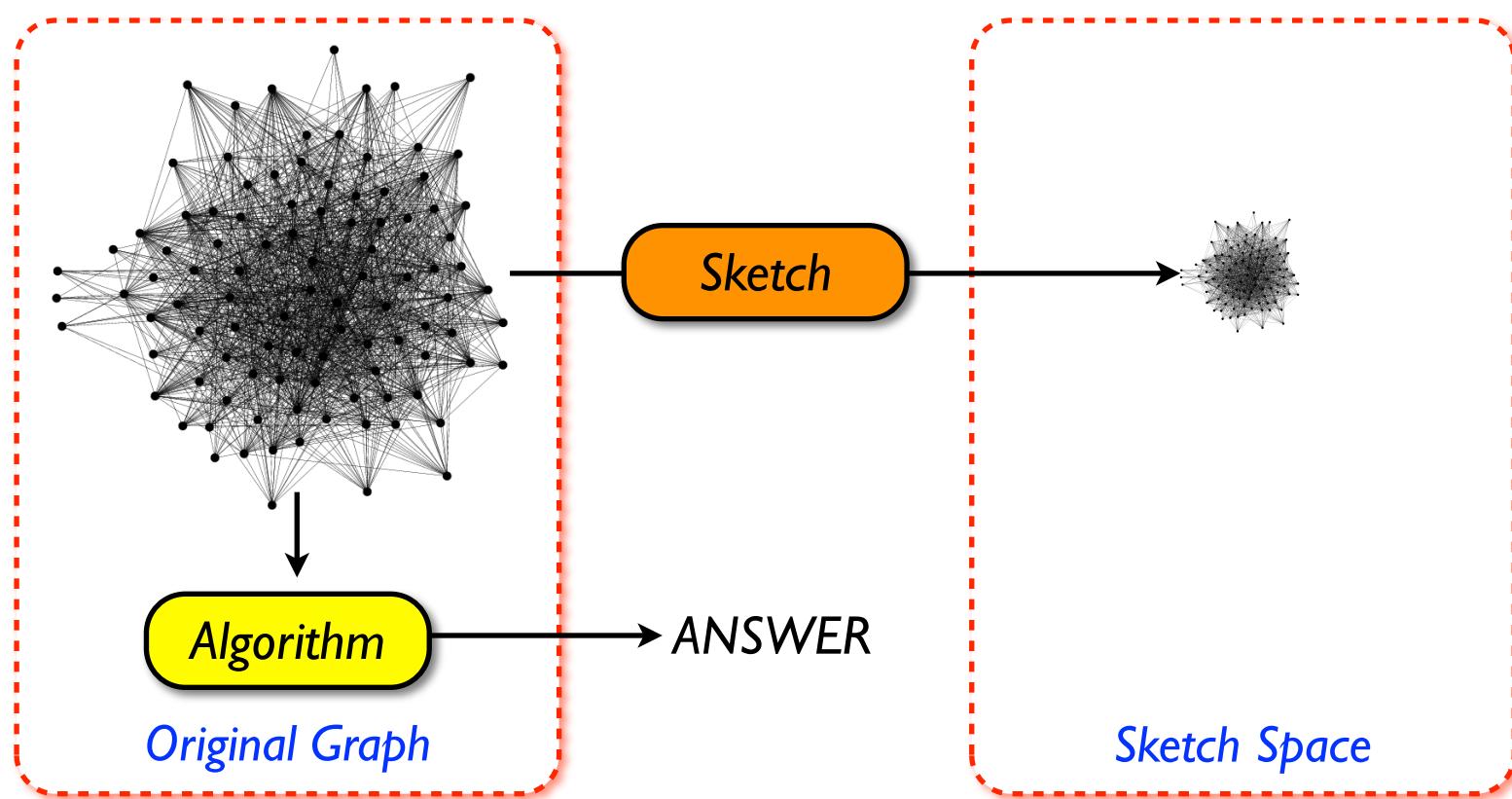
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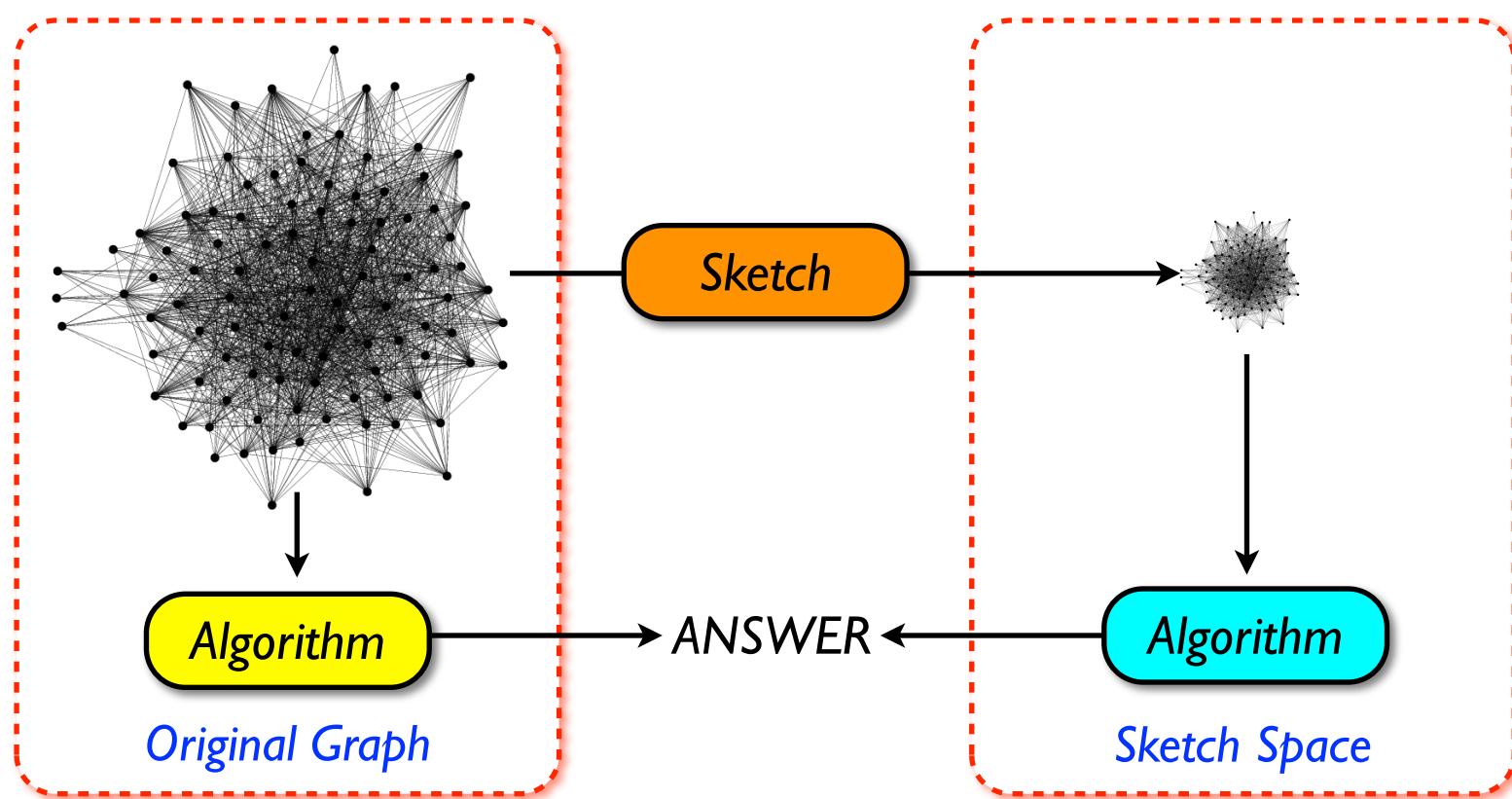
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Two Examples



First Theorem: Testing Connectivity

- a) *Dynamic Graph Stream:* $O(n \text{ polylog } n)$ space.
- b) *Distributed Setting:* $O(\text{polylog } n)$ length messages.

Second Theorem: Checking every cut has size $\geq k$

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- b) *Distributed Setting:* $O(k \text{ polylog } n)$ length.

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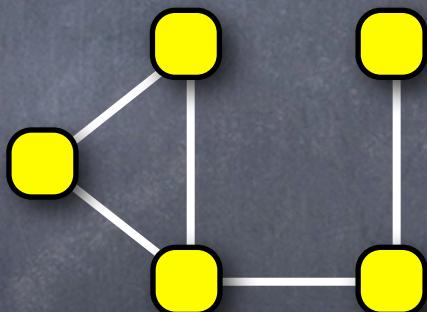
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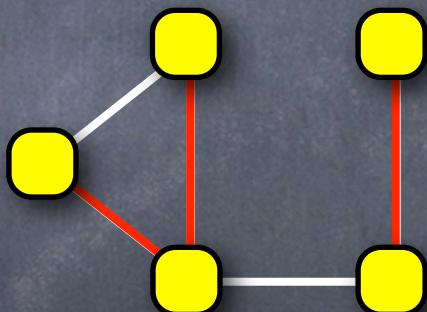
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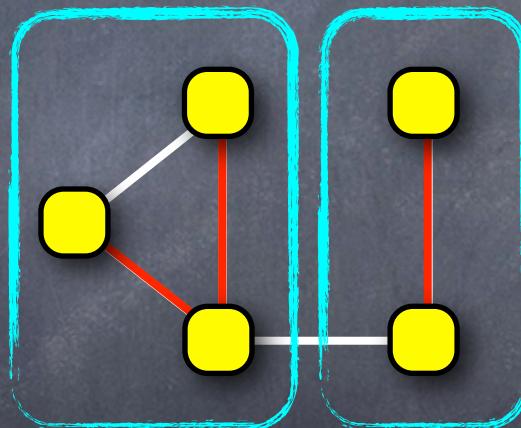
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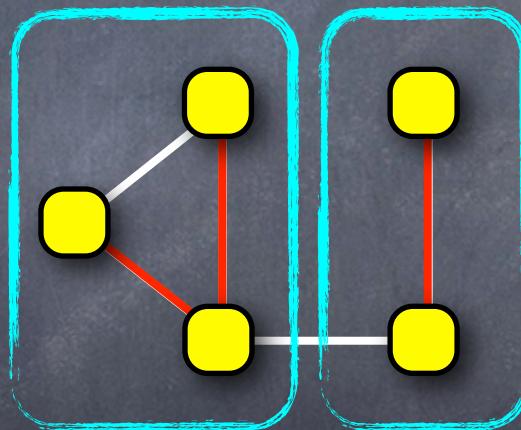
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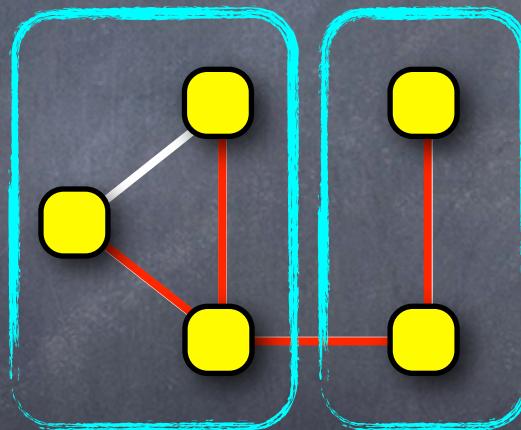
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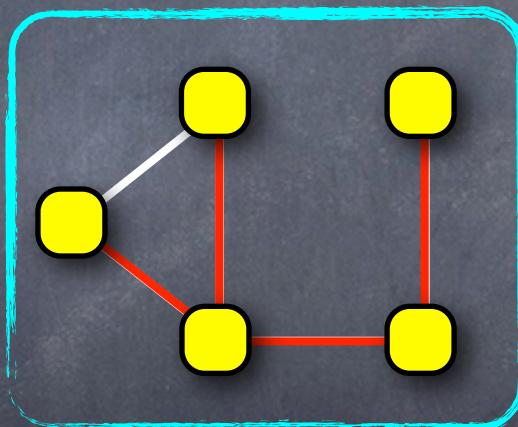
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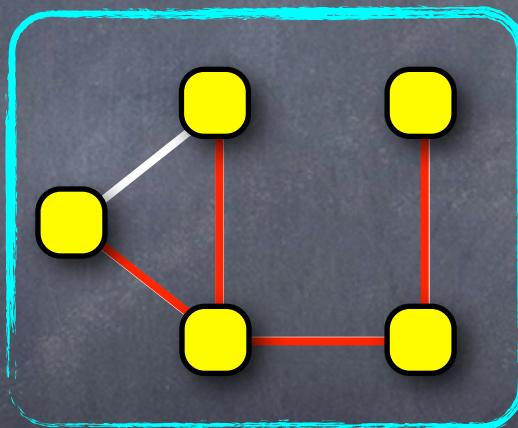
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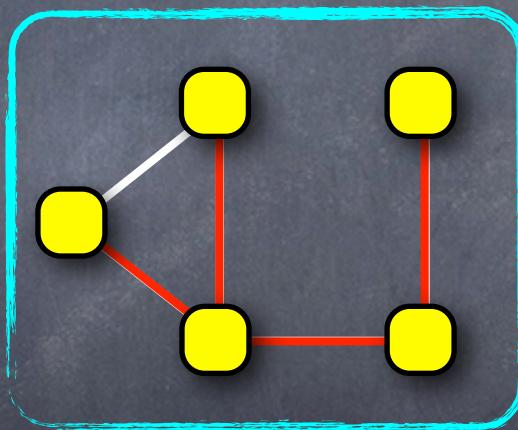
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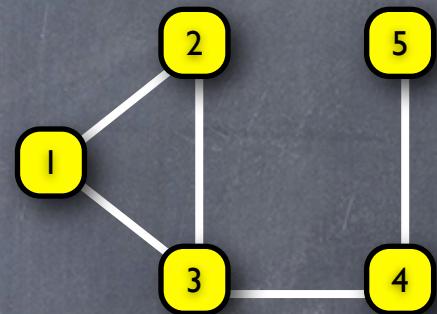
- Lemma: After $O(\log n)$ rounds selected edges include spanning forest.

Ingredient 2: Sketching Neighborhoods

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Non-zero entries: $a_i[i,j]=1$ if $j>i$ and $a_i[i,j]=-1$ if $j<i$.

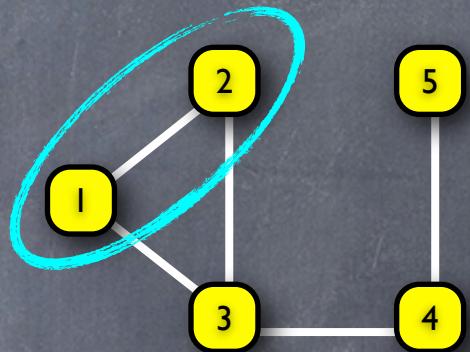
$$\mathbf{a}_1 = \begin{pmatrix} \{1,2\} & \{1,3\} & \{1,4\} & \{1,5\} & \{2,3\} & \{2,4\} & \{2,5\} & \{3,4\} & \{3,5\} & \{4,5\} \\ 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$
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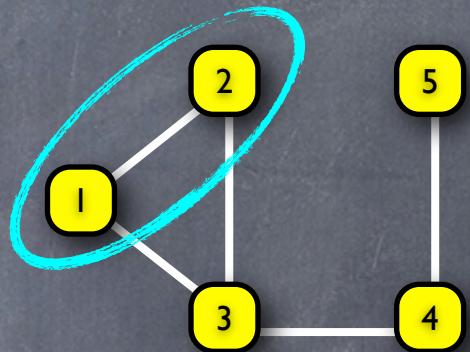
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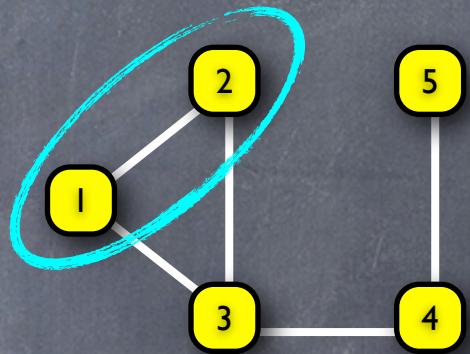
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$$a_2 = \begin{pmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$a_1 + a_2 = \begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$



- Lemma:** For any subset of nodes $S \subset V$,

$$\text{support} \left(\sum_{i \in S} a_i \right) = E(S, V \setminus S)$$

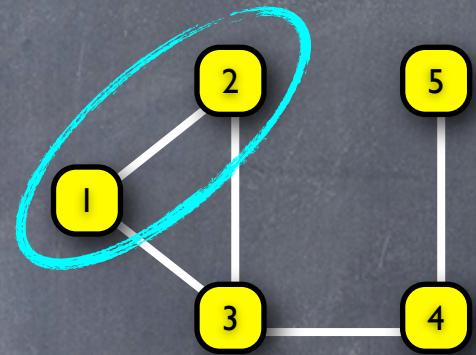
Ingredient 2: Sketching Neighborhoods

- For node i , let a_i be vector indexed by node pairs.
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- Lemma:** \exists random $M: \mathbb{R}^N \rightarrow \mathbb{R}^k$ with $k = O(\text{polylog } N)$ such that for any $a \in \mathbb{R}^N$, with high probability

$$Ma \rightarrow e \in \text{support}(a)$$

Recipe: Sketch & Compute on Sketches

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- Sketch: Each player sends Maj_k
- Central Player Runs Algorithm in Sketch Space:

Recipe: Sketch & Compute on Sketches

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 - Use M_{aj} to get incident edge on each node j

Recipe: Sketch & Compute on Sketches

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Recipe: Sketch & Compute on Sketches

- Sketch: Each player sends Ma_j
- Central Player Runs Algorithm in Sketch Space:
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 - For $i=2$ to $\log n$:
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$$\sum_{j \in S} Ma_j = M \left(\sum_{j \in S} a_j \right)$$

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Detail: Actually each player sends $\log n$ indept sketches $M_1 a_j, M_2 a_j, \dots$ and central player uses $M_i a_j$ when emulating i^{th} iteration of the algorithm.

Two Examples



First Theorem: Testing Connectivity

- a) *Dynamic Graph Stream:* $O(n \text{ polylog } n)$ space.
- b) *Distributed Setting:* $O(\text{polylog } n)$ length messages.



Second Theorem: Checking every cut has size $\geq k$

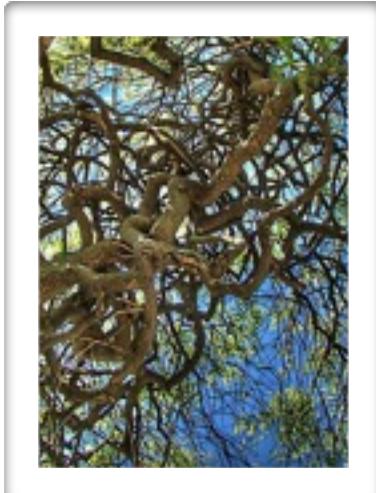
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 2. For $i=2$ to k :
 - 2.1. Let F_i be spanning forest of $G(V, E - F_1 - \dots - F_{i-1})$
- ⦿ **Lemma:** $G(V, F_1 + \dots + F_k)$ is k -connected iff $G(V, E)$ is.

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 - Use $M_3G - M_3F_1 - M_3F_2 = M_3(G - F_1 - F_2)$ to find F_3
 - etc.

Sketches Summary

- Graph Sketches: Linear projections that preserve structural graph properties. Results *parallelizable*, *streamable*, and *support deletions*.
- Talk Results: Projecting $O(n)$ -dimensional neighborhoods to $O(\text{polylog } n)$ dimensions while preserving connectivity and cuts.
- Other Results: Spanners, Bipartiteness, MST, Triangles, Matching, ...



And over to Part II...

Sağ olun!

