
CMPSCI 311: Introduction to Algorithms

Practice Final Exam

Name: _____ ID: _____

Instructions:

- Answer the questions directly on the exam pages.
- Show all your work for each question. Providing more detail including comments and explanations can help with assignment of partial credit.
- If the answer to a question is a number, *unless the problem says otherwise*, you may give your answer using arithmetic operations, such as addition, multiplication, “choose” notation and factorials (e.g., “ $9 \times 35! + 2$ ” or “ $0.5 \times 0.3 / (0.2 \times 0.5 + 0.9 \times 0.1)$ ” is fine).
- If you need extra space, use the back of a page.
- No books, notes, calculators or other electronic devices are allowed. Any cheating will result in a grade of 0.
- If you have questions during the exam, raise your hand.

Question	Value	Points Earned
1	10	
2	20	
3	30	
4	10	
5	20	
6	10	
Total	100	

Question 1. (10 points) **True or False?** Indicate whether each of the following statements is TRUE or FALSE. No justification required.

1.1 (2 points): 3-COLORING can be solved by breadth first search and therefore is in P .

False

1.2 (2 points): $\sum_{i=1}^n 2^i = \Theta(2^n)$.

True

1.3 (2 points): A dynamic program that implements the following recursive form can be used to solve the subset sum problem, which asks to find a subset S of numbers from x_1, \dots, x_n (all non-negative) with maximum weight subject to not exceeding a given number W .

$$Val(i, w) = \max\{Val(i-1, w), x_i + Val(i-1, w-x_i)\}$$

True

1.4 (2 points): For any flow network, and any two vertices s, t there is always a flow of at least 1 from source s to target t .

False

1.5 (2 points): The recurrence $T(n) = 2T(n-1) + O(1)$ solves to $\Theta(n^2)$.

False

Question 2. (20 points) **Short Answer.** Answer each of the following questions in at most two sentences.

2.1 (4 points): *In a weighted graph G where all edges have weight 1, how can we use Dijkstra's algorithm to find a minimum spanning tree?*

All trees are minimum spanning trees when the edges have weight 1. So as you run Dijkstra's just record the parent of each node, and this is an MST.

2.2 (4 points): *Solve the recurrence $T(n) = 3T(n/2) + O(n)$.*

$$T(n) = \sum_{i=0}^{\log_2 n - 1} 3^i \frac{n}{2^i} = O(n \times (3/2)^{\log_2 n - 1}) = O(n^{\log_2 3}).$$

2.3 (4 points): *Suppose a dynamic programming algorithm creates an $n \times m$ table and to compute each entry of the table it takes a minimum over at most m (previously computed) other entries. What would the running time of this algorithm be, assuming there is no other computations.*

We compute $n \times m$ numbers and each computation requires $O(m)$ time, so the total is $O(nm^2)$.

2.4 (4 points): Why is MAXFLOW in $\mathcal{NP} \cap \text{co-}\mathcal{NP}$?

We can verify both positive and negative instances via the Max-Flow Min-Cut theorem.

2.5 (4 points): Suppose \mathcal{A} is a randomized algorithm that finds the optimal solution to some minimization problem with probability at least $p \in (0, 1)$. More precisely, if we run \mathcal{A} on some input, it returns a candidate solution O along with the cost of O , and with probability at least p , we are guaranteed that O minimizes the cost function. For another parameter $\delta > 0$, how can we use \mathcal{A} to find an optimal solution with probability at least $1 - \delta$ and what is the running time of this new algorithm?

If we run the algorithm m times, then the probability that all m runs fail to find the optimum is at most $(1 - p)^m = [(1 - p)^{1/p}]^{pm} \leq [(1 - \frac{1}{1/p})^{1/p}]^{pm} \leq e^{-pm}$. We want this to be at most δ , which requires we set $m = p^{-1} \log(1/\delta)$ so our running time is $O(p^{-1} \log(1/\delta) \times \text{runtime for } \mathcal{A})$.

Question 3. (20 points) Consider the longest increasing subsequence problem defined as follows. Given a list of numbers a_1, \dots, a_n an increasing subsequence is a list of indices $i_1, \dots, i_k \in \{1, \dots, n\}$ such that $i_1 < i_2 < \dots, i_k$ and $a_{i_1} \leq a_{i_2} \leq \dots, \leq a_{i_k}$. The longest increasing subsequence is the longest list of indices with this property.

3.1 (2 points): What is the longest increasing subsequence of the list 5, 3, 4, 8, 7, 10?
There are two, 3, 4, 8, 10 or 3, 4, 7, 10.

3.2 (4 points): Consider the greedy algorithm that chooses the first element of the list, and then repeatedly chooses the next element that is larger. Is this a correct algorithm? Either prove its correctness or provide a counter example.

The above input is a counter example as the greedy algorithm would choose 5, but 5 is not in either of the optimal solutions.

3.3 (4 points): Consider the greedy algorithm that chooses the smallest element of the list, and then repeatedly chooses the smallest element that comes after this chosen one. Is this a correct algorithm? Either prove its correctness or provide a counterexample.

The input 2, 3, 4, 1 is a counter example, since this greedy algorithm would choose 1 first, but 1 is not in the optimal solution.

3.4 (5 points): Consider a divide and conquer strategy that splits the list into the first half and second half, recursively computes $L = (\ell_1, \dots, \ell_{k_L})$, $R = (r_1, \dots, r_{k_R})$ the longest increasing subsequences in each half, and then, if the last chosen element in the first half is less than the first chosen index in the second half (i.e. $a_{\ell_{k_L}} \leq a_{r_1}$) returns $L \cdot R$, otherwise it returns the longer of L and R . Is this a correct algorithm? either prove its correctness or provide a counterexample.

Consider the input 2, 3, 4, 5, 0, 1. The optimal is 2, 3, 4, 5 but if we do divide and conquer we find 2, 3, 4 and 0, 1 so we output 2, 3, 4.

3.5 (15 points): Design a dynamic programming algorithm for longest increasing subsequence. Prove its correctness and analyze its running time.

Let the input have size n , we build a size n table A by,

$$j^*(i) = \operatorname{argmax}\{A[j] \text{ such that } j < i \text{ and } a_j \leq a_i\}$$

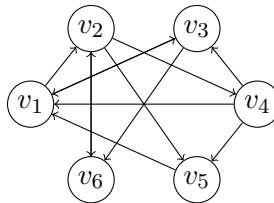
$$A[i] = 1 + A[j^*(i)]$$

$j^*(i)$ is set to zero if no choice for j exists (for example on the first element of the list). The proof is based on the fact that $A[j]$ holds the length of the longest increasing subsequence that ends on a_j . This is proved by induction, where the base case is easy. For the inductive step, consider some index i , we set $A[i] = 1 + A[j^*(i)]$, and we are guaranteed that $j^*(i)$ maximizes $A[j]$ among all possible positions j that could come before i in an increasing subsequence. Thus we are ensured that $A[i]$ holds the proper value. The running time is $O(n^2)$.

Question 4. (10 points) In this problem we investigate the feedback arc-set problem which generalizes the topological ordering. Given a directed graph (which may contain cycles), the goal in feedback arc-set is to find an ordering of the vertices that minimizes the number of back edges. More precisely, if $G = (V, E)$ is a directed graph, and $(a_1, \dots, a_n) \in V$ with $a_i \neq a_j$ is an ordering of the vertices, we define the cost as

$$\text{cost}(a_1, \dots, a_n) = \sum_{i < j} \mathbf{1}[(a_j, a_i) \in E]$$

Here $\mathbf{1}[\cdot]$ is a function that is 1 if the argument is true and zero otherwise. This is the number of edges going from right to left (backward) if we ordered the vertices with a_1 on the left and a_n on the right.



4.1 (1 points): In the above graph, what is the cost of $(v_1, v_2, v_3, v_4, v_5, v_6)$?

$$3 + 1 + 1 + 0 + 0 + 0 = 5$$

4.2 (1 points): In the above graph, what is the cost of $(v_6, v_5, v_4, v_3, v_2, v_1)$?

$$2 + 2 + 1 + 1 + 1 + 0 = 7$$

4.3 (2 points): True or False. a directed acyclic graph always has an ordering O with $\text{cost}(O) = 0$. True, any topological ordering has no feedback arcs.

4.4 (6 points): Prove that the decision version of feedback arc set is NP-complete. That is given a directed graph and an integer k , decide whether the graph has an ordering with at most k back-edges.

The proof is by reduction from vertex cover. Given an instance $G = (V, E)$ of vertex cover, we will define a instance of feedback arc set. Let $G' = (V', E')$ be a new directed graph where for each $v \in V$ we have two vertices $v^{(1)}, v^{(2)} \in V'$ connected with the directed edge $(v^{(1)} \rightarrow v^{(2)})$. For every undirected edge $(u, v) \in E$, define two directed edges $(u^{(2)} \rightarrow v^{(1)})$ and $(v^{(2)} \rightarrow u^{(1)})$. If G has n vertices and m edges, this new graph has $2n$ vertices and $n + 2m$ edges. We claim that G has a vertex cover of size at most k if and only if G' has an ordering with at most k back edges.

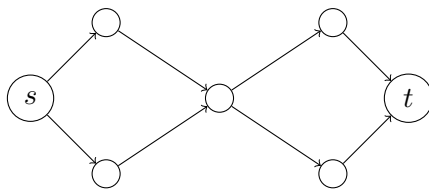
The idea for the proof is that each edge $(u, v) \in E$ forms a 4-cycle in G' . If S is a vertex cover, we can remove the edges $(v^{(1)} \rightarrow v^{(2)})$ for each $v \in S$ and break all of the 4-cycles, since we remove an edge from each cycle.

More precisely, if S is a vertex cover, we construct an ordering as follows: the first $|S|$ nodes are $v^{(2)}$ for each $v \in S$, followed by each $u^{(1)}, u^{(2)}$ pair for $u \notin S$, and finally followed by $v^{(1)}$ for each $v \in S$. The order in each group does not matter. Since S is a vertex cover, all edges from into $u^{(1)}$ for $u \notin S$ originate from some $v^{(2)}$ for $v \in S$ and similarly all edges from $u^{(2)}$ point to $v^{(1)}$ for some $v \in S$. Thus the only back edges in this ordering are from $v^{(1)} \rightarrow v^{(2)}$ for $v \in S$, which is k back edges.

The other direction is by a counting argument. If no subset of k vertices covers all edges, then there is no way to break all m cycles in G' . Observe that if you break an edge of the form $(v^{(2)} \rightarrow u^{(1)})$ you can break at most one cycle, so it is always better to break edges of the form $(v^{(1)} \rightarrow v^{(2)})$. However, since there is no vertex cover of size at most k , choosing k of these edges cannot break all the cycles.

Question 5. (20 points) In this problem we investigate vertex-capacitated flow networks. We are given a directed graph $G = (V, E)$ with source s and sink t and a capacity c_v for each $v \in V$. We want an $s - t$ flow f that satisfies the usual conservation of flow constraints, but instead of satisfying edge-capacity constraints, satisfies the vertex capacity constraints $f(v) \leq c_v$. Here $f(v) = \sum_{(u,v) \in E} f_{u,v}$ is the total flow entering the node v . The goal is to design an algorithm for computing a maximum $s - t$ flow in a vertex-capacitated network.

5.1 (5 points): Draw a directed graph G with clearly labeled source s and sink t , where if we consider the usual edge-capacitated version of the problem (with edge capacities $c_e = 1$) we get a maximum flow with a different value than if we consider the vertex capacitated version of the problem (with vertex capacities $c_v = 1$).



In this graph the maximum flow in the edge-capacitated version has value 2, while the vertex capacitated version has value 1.

5.2 (15 points): Design a polynomial time algorithm for computing the maximum flow in a node-capacitated network. Prove that the algorithm is correct and analyze its running time.

In the flow network, replace each vertex v with two vertices $v^{(1)}$ and $v^{(2)}$ with an edge $e_v = (v^{(1)} \rightarrow v^{(2)})$ of capacity $c(e_v) = c_v$. All incoming edges to v in the original network point to $v^{(1)}$ and have capacity ∞ (no constraint). All outgoing edges from v in the original network now start from $v^{(2)}$ and have capacity ∞ .

The edge capacitated maximum flow in this network is precisely the vertex capacitated maximum flow in the original network. The only capacity constraints are on the e_v edges, and these precisely encode the fact that we must satisfy the vertex capacities. The running time is the same as the max flow problem $O((|V| + |E|)F)$ where F is the value of the maximum flow and $|E|$ is the number of edges in the original network and $|V|$ is the number of vertices.

Additional space.

Question 6. (10 points) Consider a variant of the subset sum problem where we are given a set of numbers x_1, \dots, x_n and need to partition them numbers into sets S_1, \dots, S_K such that for each $k \in \{1, \dots, K\}$, $\sum_{i \in S_k} x_i \leq W$ for some target W . The goal is to minimize K , the number of sets in the partition. We will study a simple approximation algorithm for this problem. The algorithm considers the items in order, and forms the first set S_1 by repeatedly adding the numbers x_1, x_2, \dots until the next number would exceed the target W . Then it proceed to construct the next set.

6.1 (2 points): Give an example input where this algorithm does not use the minimum number of sets.

Let $W = 5$ and consider the sequence 4, 2, 3, 1. The optimal solution uses two sets $\{4, 1\}$ and $\{2, 3\}$ but our approximation algorithm tries to group 2 with 4 and fails, so it forms $\{4\}, \{2, 3\}, \{1\}$.

6.2 (2 points): Derive a lower bound on K^* the smallest possible number of sets in the partition in terms of the target W and the total weight $X = \sum_{i=1}^n x_i$.

$K^* \geq X/W$ since all the weight must be included and at most W can be included in each set.

6.3 (6 points): Use this lower bound to prove that this greedy algorithm always produces a number of sets K that is at most $2K^*$.

Consider sets S_1, S_2 . We claim $\sum_{i \in S_1 \cup S_2} x_i \geq W$. This is clear since S_2 was only formed because adding the next element to S_1 would exceed the weight constraint, and this item was added to S_2 . Similarly, for every adjacent pair of sets $s, s+1$, we have $\sum_{i \in S_s \cup S_{s+1}} x_i \geq W$ by the same argument.

Thus, letting K be the number of sets produced by the algorithm,

$$K^* \geq X/W = \frac{1}{W} \sum_{s=1}^K \sum_{i \in S_s} x_i \geq \frac{1}{W} \sum_{s=1}^{K/2} \sum_{i \in S_{2s-1} \cup S_{2s}} x_i \geq \frac{1}{W} (K/2 \times W) = K/2$$

This proves that $K \leq 2K^*$.