CMPSCI 240: Reasoning about Uncertainty Lecture 15: Steady-State Theorem

Andrew McGregor

University of Massachusetts

Last Compiled: March 23, 2017

Outline

1 Markov Chains

2 Steady State Theorem

Analyzing the Queue at Earth Foods Cafe

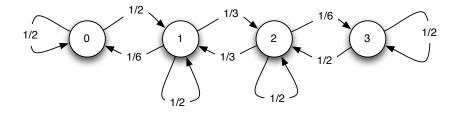
- Consider a queue at Earth Foods Cafe
- Every minute, someone joins the queue...
 - With probability 1 if the queue has length 0
 - With probability 2/3 if the queue has length 1
 - With probability 1/3 if the queue has length 2
 - With probability 0 if the queue has length 3.
- Every minute, the server serves a customer with probability 1/2.

Suppose 1 person in line at noon. How many people in line at 12:10pm?

States with Transition Probabilities

Markov Chains

Weight p_{ij} on arrow from state i to state j indicates the probability of transitioning to state j given we're in state i.



Can work out things like "what's the probability we're in state 2 after two steps if we're currently in state 3."

Markov Chain

A Markov Chain consists:

- A set of states: $\{s_1, \ldots, s_k\}$
- A matrix *P* of transition probabilities $\{p_{ij} : 1 \le i, j \le k\}$
- An initial state *s_i*.

A Markov Chain defines a series of random variables X_0, X_1, X_2, \ldots where

For all
$$t = 1, 2, 3, ...$$

$$P(X_t = j | X_{t-1} = i) = p_{ij}$$

• Write the distribution of each X_t as

$$v_t = (P(X_t = 1), P(X_t = 2), \dots, P(X_t = k))$$

Note: The value of X_t only depends on the value of X_{t-1} , e.g.,

$$P(X_t = j | X_{t-1} = i, X_{t-2} = h) = P(X_t = j | X_{t-1} = i) = p_{ij}$$

Analyzing Markov Chains via Matrices

Define transition probability matrix:

$$A = \begin{pmatrix} p_{0,0} & p_{0,1} & p_{0,2} & p_{0,3} \\ p_{1,0} & p_{1,1} & p_{1,2} & p_{1,3} \\ p_{2,0} & p_{2,1} & p_{2,2} & p_{2,3} \\ p_{3,0} & p_{3,1} & p_{3,2} & p_{3,3} \end{pmatrix} = \begin{pmatrix} 1/2 & 1/2 & 0 & 0 \\ 1/6 & 1/2 & 1/3 & 0 \\ 0 & 1/3 & 1/2 & 1/6 \\ 0 & 0 & 1/2 & 1/2 \end{pmatrix}$$

Markov Chain Theorem Given v_{t-1} , we can compute

$$v_t = v_{t-1}A$$

and so $v_t = v_{t-1}A = v_{t-2}AA = v_{t-3}AAA = \ldots = v_0A^t$.

Proof: By the law of total probability

$$v_t[j] = P(X_t = j) = \sum_i P(X_t = j | X_{t-1} = i) P(X_{t-1} = i) = \sum_i p_{i,j} v_{t-1}[i]$$

and so $v_t = v_{t-1}A$ as claimed.

Simulation of the queue if there is initially one person

$$v_0 = \langle 0.000, 1.000, 0.000, 0.000 \rangle$$

$$v_1 = \langle 0.167, 0.500, 0.333, 0.000 \rangle$$

$$v_2 = \langle 0.167, 0.444, 0.333, 0.056 \rangle$$

$$v_3 = \langle 0.158, 0.416, 0.342, 0.084 \rangle$$

$$v_4 = \langle 0.148, 0.401, 0.352, 0.099 \rangle$$

$$v_5 = \langle 0.142, 0.391, 0.359, 0.109 \rangle$$

$$v_6 = \langle 0.136, 0.386, 0.364, 0.114 \rangle$$

$$v_7 = \langle 0.133, 0.382, 0.368, 0.118 \rangle$$

$$v_8 \ = \ \langle 0.130, 0.380, 0.370, 0.120 \rangle$$

$$\vdots \quad \vdots \quad \vdots \\ v_{\infty} = \langle 0.125, 0.375, 0.375, 0.125 \rangle$$

Simulation of the queue if there is initially three people

- $v_0 = \langle 0.000, 0.000, 0.000, 1.000 \rangle$
- $v_1 = \langle 0.000, 0.000, 0.500, 0.500 \rangle$
- $v_2 = \langle 0.000, 0.167, 0.500, 0.333 \rangle$
- $v_3 \hspace{.1in} = \hspace{.1in} \langle 0.028, 0.250, 0.472, 0.251 \rangle$
- $v_4 \hspace{.1in} = \hspace{.1in} \langle 0.056, 0.296, 0.404, 0.204 \rangle$
- $v_5 = \langle 0.078, 0.324, 0.423, 0.177 \rangle$
- $v_{6} \hspace{.1 in} = \hspace{.1 in} \langle 0.093, 0.341, 0.407, 0.159 \rangle$
- $v_7 = \langle 0.104, 0.353, 0.397, 0.148 \rangle$
- $v_8 = \langle 0.111, 0.360, 0.389, 0.140 \rangle$
- : : :
- $v_{\infty} = \langle 0.125, 0.375, 0.375, 0.125 \rangle$

Outline



2 Steady State Theorem

Question

Do all Markov chains have the property that eventually the distribution settles to the "same steady" state regardless of the initial state?

Definition

If v = vA, we say v is a steady state distribution for the Markov Chain.

For the queueing example, if v = (a, b, c, d) then

$$(a, b, c, d) = (a, b, c, d) \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 & 0\\ \frac{1}{6} & \frac{1}{2} & \frac{1}{3} & 0\\ 0 & \frac{1}{3} & \frac{1}{2} & \frac{1}{6}\\ 0 & 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = (\frac{a}{2} + \frac{b}{6}, \frac{a}{2} + \frac{b}{2} + \frac{c}{3}, \frac{b}{3} + \frac{c}{2} + \frac{d}{2}, \frac{c}{6} + \frac{d}{2})$$

Solving $a = \frac{a}{2} + \frac{b}{6}, b = \frac{a}{2} + \frac{b}{2} + \frac{c}{3}, c = \frac{b}{3} + \frac{c}{2} + \frac{d}{2}$ and $d = \frac{c}{6} + \frac{d}{2}$ gives
 $v = (0.125, 0.375, 0.375, 0.125)$

Question

Theorem

"Most" Markov Chains have a unique steady state distribution regardless of initial state that is approached by successive iterations from any starting distributions.

Irreducible Markov Chains

Example

Consider the Markov Chain with transition matrix:

$${\sf A}=\left(egin{array}{ccccc} 0 & 0.9 & 0.05 & 0.05\ 0.2 & 0.8 & 0 & 0\ 0 & 0 & 1 & 0\ 0 & 0 & 0 & 1 \end{array}
ight)$$

This Markov chain doesn't converge to a unique steady state.

Definition

A Markov chain is irreducible if in the transition graph there exists a path from every state to every other state, i.e., you can't get stuck in a small group of nodes.

Steady State Theorem

Irreducible Markov Chains

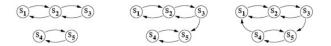


Figure 2.1: Examples of three Markov chains the one to the right is irreducible while the other two are not.

Periodic Markov Chains

Example

Consider the Markov Chain with transition matrix:

1	0	0.5	0	0.5	
	0.75	0	0.25	0	
	0	0.75	0	0.25	
ĺ	0.75	0	0.25	0	

This Markov chain doesn't converge at all!

Definition

An irreducible Markov chain with transition matrix A is called *periodic* if there is some $t \in \{2, 3, ...\}$ such that there exists a state s which can be visited only at time $\{t, 2t, 3t, 4t, ...\}$ steps, that is with a period of t. If A is not periodic (t = 1) we call the chain *aperiodic*.

Steady State Theorem

Periodic/Aperiodic Markov Chains

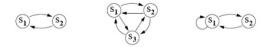


Figure 2.2: Examples of three Markov chains of which the left one has period 2 while the other two both are aperiodic.

Steady State Theorem

Definition

Consider Markov chain with k states and let $v^* = (v^*[1], \ldots, v^*[k])$ be a probability distribution on the states of C. We say that the Markov chain approaches v^* if for any arbitrarily small $\epsilon > 0$, there exists a sufficiently large t such that for any i and any starting distribution, then

$$|P(X_t = i) - v^*[i]| \le \epsilon$$

Theorem

If a Markov Chain is aperiodic and irreducible then there exists a distribution v^* such that v_t approaches v^* .

Steady State Distribution: 2 state case

Consider a Markov chain C with 2 states and transition matrix

$$A = \left(\begin{array}{cc} 1-a & a \\ b & 1-b \end{array}\right)$$

for some $0 \le a, b \le 1$

- Since C is irreducible: a, b > 0
- Since C is aperiodic: a + b < 2
- Let $v^* = (c, 1 c)$ be a steady state distribution, i.e., $v^* = v^* A$
- Solving $v^* = v^*A$ gives:

$$v^* = \left(\frac{b}{a+b}, \frac{a}{a+b}\right)$$

Steady State Distribution: 2 state case (continued)

- We say v_t converges to v^{*} if for any ε > 0, there exists t^{*} such that for all t ≥ t^{*} corresponding entries of v_t and v^{*} differ by at most ε.
- Suppose the start distribution is

$$\mathbf{v} = (\mathbf{c} + \gamma, 1 - \mathbf{c} - \gamma)$$

i.e., entries are $|\gamma|$ away from the corresponding entry in v^*

After one more step the distribution is

$$vA = (c + \gamma(1 - a - b), 1 - c - \gamma(1 - a - b))$$

i.e., entries are now only $|\gamma(1-a-b)| < |\gamma|$ away.

■ Hence if we pick t* such that |1 - a - b|^{t*} < ϵ then after t* or more steps entries will differ by at most</p>

$$|\gamma(1-a-b)^{t^*}| \leq \epsilon |\gamma| \leq \epsilon$$