

Inductive Synthesis

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joint work with
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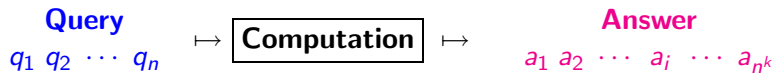
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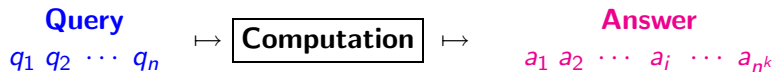
Example 1: Given **FO** equations $C = f(x, y)$ to be maintained given small changes to variables, x, y . Derive finite differencing code in **T₀**, performing updates to **C** in constant time.

Example 2: Given graph properties, e.g., “is connected”, “is a tree”, in **FO(TC)**, derive implementations in **T₁** with guaranteed linear runtime.

Descriptive Complexity



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How rich a language do we need to **express** property a ?

There is a **constructive isomorphism** between these two approaches.

Encode Input via Relations

Graph

$$G = (\{v_1, \dots, v_n\}, E, s, t)$$



Binary
String

$$\mathcal{A}_w = (\{p_1, \dots, p_8\}, S)$$

$$S = \{p_2, p_5, p_7, p_8\}$$

$$w = 01001011$$

Vocabularies: $\tau_g = (E^2, s, t)$, $\tau_s = (S^1)$

First-Order Logic

input symbols:	from τ
variables:	x, y, z, \dots
boolean connectives:	\wedge, \vee, \neg
quantifiers:	\forall, \exists
numeric symbols:	$=, \leq, +, \times, \min, \max$

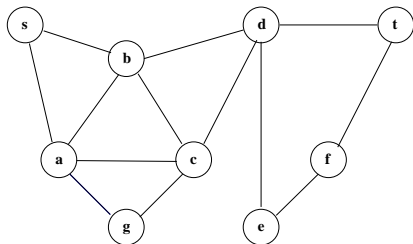
$$\alpha \equiv \forall x \exists y (E(x, y)) \quad \in \mathcal{L}(\tau_g)$$

$$\beta \equiv \exists x \forall y (x \leq y \wedge S(x)) \quad \in \mathcal{L}(\tau_s)$$

$$\beta \equiv S(\min) \quad \in \mathcal{L}(\tau_s)$$

Second-Order Logic

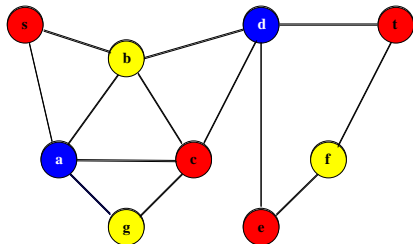
$$\begin{aligned}\Phi_{3\text{-color}} \equiv & \exists R^1 Y^1 B^1 \forall x y ((R(x) \vee Y(x) \vee B(x)) \wedge \\ & (E(x, y) \rightarrow (\neg(R(x) \wedge R(y)) \wedge \neg(Y(x) \wedge Y(y)) \\ & \wedge \neg(B(x) \wedge B(y))))))\end{aligned}$$



Second-Order Logic

Fagin's Theorem: NP = SO \exists

$$\begin{aligned}\Phi_{3\text{-color}} \equiv & \exists R^1 Y^1 B^1 \forall x y ((R(x) \vee Y(x) \vee B(x)) \wedge \\ & (E(x,y) \rightarrow (\neg(R(x) \wedge R(y)) \wedge \neg(Y(x) \wedge Y(y)) \\ & \wedge \neg(B(x) \wedge B(y))))))\end{aligned}$$



Logic as Specification Language

Model Checking rather than Satisfiability

co-r.e. complete	Arithmetic Hierarchy		r.e. complete
	co-r.e.	FO(N)	r.e.
FOV(N)	Recursive		FOE(N)
Primitive Recursive			
	SO[2 ⁿ ^{O(1)}]	EXPTIME	SO(LFP)
FO[2 ⁿ ^{O(1)}]	SO[n ^{O(1)}]	PSPACE	FO(PFP) SO(TC)
co-NP complete	Polynomial-Time Hierarchy		NP complete
	co-NP	SO	NP
SOV	NP ∩ co-NP		SOE
FO[n ^{O(1)}]	P	SO-Horn	
FO(LFP)	"truly feasible"		
	FO[(log n) ^{O(1)}]	NC	
		NC ²	
	FO(CFL)	sAC ¹	
	FO(TC)	NSPACE[log n]	SO-Krom
	FO(DTC)	DSPACE[log n]	
	FO(REGULAR)	NC ¹	
	FO(M)	ThC ⁰	
FO	Logarithmic-Time Hierarchy		AC ⁰

Inductive Synthesis: Goal

Write specification, φ , in high level logical language, e.g., **SO**.

Synthesize efficient implementation, $\alpha \equiv \varphi$, in target language, **T**.

Could have a range of target languages: T_0 , guaranteed constant runtime, T_1 , guaranteed linear runtime, T_2 , guaranteed $O(n^2)$ runtime, etc.

Example 1: Given **FO** equations $C = f(x, y)$ to be maintained given small changes to variables, x, y . Derive finite differencing code in T_0 , performing updates to C in constant time.

Example 2: Given graph properties, e.g., “is connected”, “is a tree”, in **FO(TC)**, derive implementations in T_1 with guaranteed linear runtime.

Sketch of Method

1. Input: $\varphi \in \text{SO}$; vocabularies: $\sigma \subseteq \sigma'$; target language: L
2. Generate instances $\mathcal{M} = \{\mathcal{A}_1, \dots, \mathcal{A}_k\} \models \varphi$
3. Find minimum size formula $\alpha \in L$ s.t. α covers* \mathcal{M}
4. **If** (exists small instance $\mathcal{A} \models \varphi$ not covered by α)

Then $\mathcal{M}_+ = \{\mathcal{A}\}$; **Goto** 3.

5. **Return** α

* α covers \mathcal{M} iff $\mathcal{M} \models \alpha$ and
 α determines the correct output bits on each $\mathcal{A} \in \mathcal{M}$,

$$\alpha \wedge \Delta_\sigma(\mathcal{A}) \vdash \Delta_{\sigma'}(\mathcal{A})$$

Maintain $C == f(x_1, \dots, x_k)$ where $x_i += \delta$

Example:

Expression: $C = T + S$

Change: $T += \{a\}$

Derived Code: $C += \{a\}$

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Synthesized $v = a \rightarrow c'(v) = 1$

Formula: $v \neq a \rightarrow c'(v) = c(v)$

Expression	Change	Synthesized Derivative	Code
$C = T + S$	$T += \{a\}$	$v = a \rightarrow c'(v) = 1$ $v \neq a \rightarrow c'(v) = c(v)$	$C += \{a\}$

$$\sigma = (s, t, c, a; \text{suc}, 0, 1, =)$$

$$\sigma' = \sigma \cup (t', c')$$

$$B_0(\sigma) = \{\forall v(l_1), \forall v(l_1 \rightarrow l_2) \mid l_1, l_2 \text{ literals}\}$$

$$B_0(\sigma) = s(a) = 0, s(a) = 1 \rightarrow c'(a) = 1, \dots$$

$$T_0(\sigma) = \text{conjunctions of base formulas from } B_0(\sigma)$$

Expression	Change	Synthesized Derivative	Code
$C = T + S$	$T += \{a\}$	$v = a \rightarrow c'(v) = 1$ $v \neq a \rightarrow c'(v) = c(v)$	$C += \{a\}$

T	S	a	T'	C	C'	$c'(1)$	$c'(2)$	$c'(3)$
{1}	{2}	1	{1}	{1,2}	{1,2}	1	1	0
{1}	{2}	2	{1,2}	{1,2}	{1,2}	1	1	0
{1}	{2}	3	{1,3}	{1,2}	{1,2,3}	1	1	1

$$v = a \rightarrow c'(v) = 1$$

$$v \neq a \rightarrow c'(v) = c(v)$$

Expression	Change	Synthesized Derivative	Code
$C = T + S$	$T += \{a\}$	$v = a \rightarrow c'(v) = 1$ $v \neq a \rightarrow c'(v) = c(v)$	$C += \{a\}$
$C = T + S$	$T -= \{a\}$	$v \neq a \rightarrow c'(v) = c(v)$ $\neg T(a) \rightarrow c'(a) = 0$ $T(a) \rightarrow c'(a) = c(a)$	if $a \notin S : C -= \{a\}$
$C = T - S$	$T += \{a\}$	$v \neq a \rightarrow c'(v) = c(v)$ $\neg S(a) \rightarrow c'(a) = 1$ $S(a) \rightarrow c'(a) = 0$	if $a \notin S : C += \{a\}$
$C = T - S$	$T -= \{a\}$	$c(v) = 0 \rightarrow c'(v) = 0$ $v \neq a \rightarrow c'(v) = c(v)$ $v = a \rightarrow c'(a) = 0$	$C -= \{a\}$

Expression	Change	Synthesized Derivative	Code
$C = f(S)$	$S += \{a\}$	$v \neq f(a) \rightarrow c'(v) = c(v)$ $v = a \rightarrow c'(f(a)) = 1$	$C += \{f(a)\}$
$C = f^{-1}(S)$	$f(a) = b$	$v \neq a \rightarrow c'(v) = c(v)$ $S(b) \rightarrow c'(a) = 1$ $\neg S(b) \rightarrow c'(a) = 0$	if $b \notin S : C -= \{a\}$ else $C += \{a\}$
$c_S = \#S$	$S += \{a\}$	$S(a) \rightarrow c'_S = c_S$ $\neg S(a) \rightarrow c_S + 1 = c'_S$	if $a \notin S : c_S += 1$
$c_S = \#S$	$S -= \{a\}$	$\neg S(a) \rightarrow c'_S = c_S$ $S(a) \rightarrow c'_S + 1 = c_S$	if $a \in S : c_S -= 1$
$c = (\#S == 0)$	$S += \{a\}$	$v = a \rightarrow c' = 0$	$c = \mathbf{false}$
$c = (\#S == 0)$	$S -= \{a\}$	$c_S \neq 1 \rightarrow c' = c$ $c'_S = c_S \rightarrow c = c'$ $c'_S = 0 \rightarrow c' = 1$	if $a \in S : c_S -= 1$ $c = (c_S == 0)$

Deriving Graph Classifiers

Name	Example	Input Spec. (+Integrity Const.)	Synthesized Formula
SLL		$1:1 N \wedge$ $\forall u(\neg N^+(u, u))$ $\left(\begin{array}{l} \text{root } r \text{ via } N \\ \text{functional } N \end{array} \right)$	$\#p_N(r) = 0 \wedge$ $\forall v(\#p_N(v) \leq 1)$

Abbreviation	Meaning
self-loop-free N	$\forall u(\neg N(u, u))$
root r via N	$\forall u(N^*(r, u))$
functional N	$\forall u, v, x(N(x, u) \wedge N(x, v) \rightarrow u = v)$
$1:1 N$	$\forall u, v, x(N(u, x) \wedge N(v, x) \rightarrow u = v)$

$$s_e(i) = \{j \mid i \xrightarrow{e} j\}$$

$$p_e(i) = \{j \mid j \xrightarrow{e} i\}$$

Target Language T_1

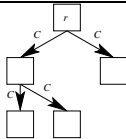
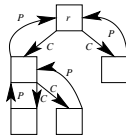
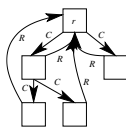
$$R(\sigma) = \{e \mid e \text{ a reg exp over } \sigma\}; \quad S(\sigma) = \{A \mid A \in \sigma\}$$

$$s_e(i) = \{j \mid i \xrightarrow{e} j\}; \quad p_e(i) = \{j \mid j \xrightarrow{e} i\}$$

$\langle \text{base} \rangle ::= \langle \text{clause} \rangle \rightarrow d \mid \langle \text{clause} \rangle \rightarrow \neg d \mid$ $\neg \langle \text{clause} \rangle \rightarrow d \mid \neg \langle \text{clause} \rangle \rightarrow \neg d$	
$\langle \text{clause} \rangle ::= \langle \text{atom} \rangle \mid \forall v \langle \text{atom} \rangle \mid$ $\forall v (v \neq r \rightarrow \langle \text{atom} \rangle)$	
$\langle \text{atom} \rangle ::= \langle \text{int} \rangle = \langle \text{const} \rangle \mid$ $\langle \text{int} \rangle \leq \langle \text{const} \rangle \mid \langle \text{set} \rangle = \langle \text{set} \rangle$	
$\langle \text{int} \rangle ::= \langle \text{const} \rangle \mid \# \langle \text{set} \rangle$	
$\langle \text{const} \rangle ::= 0 \mid 1$	
$\langle \text{set} \rangle ::= \{r\} \mid s_e(r) \mid p_e(r) \mid$ $s_\ell(v) \mid p_\ell(v)$	$e \in R(\sigma)$ $\ell \in S(\sigma)$

Thm: Every element of the language T_1 runs in expected linear time in the worst case.

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SLL		$1:1 N \wedge$ $\forall u(\neg N^+(u, u))$ $\left(\begin{array}{l} \text{root } r \text{ via } N \\ \text{functional } N \end{array} \right)$	$\#p_N(r) = 0 \wedge$ $\forall v(\#p_N(v) \leq 1)$
CYCLE		$\forall u, v(N^*(u, v))$ $\left(\begin{array}{l} \text{root } r \text{ via } N \\ \text{functional } N \end{array} \right)$	$\#p_N(r) = 1$
DLL		$1:1 F \wedge 1:1 B \wedge$ $\forall u, v((F(u, v) \leftrightarrow B(v, u))$ $\wedge \neg F^+(u, u))$ $\left(\begin{array}{l} \text{root } r \text{ via } F \\ \text{functional } F, B \end{array} \right)$	$\#p_F(r) = 0 \wedge$ $\forall v(s_F(v) = p_B(v))$

Name	Example	Input Spec. (+Integrity Const.)	Synthesized Formula
TREE		$1:1 C \wedge$ $\forall u(\neg C(u, r))$ (root r via C)	$\#p_C(r) = 0 \wedge$ $\forall v(\#p_C(v) \leq 1)$
TREEPP		$1:1 C \wedge$ $\forall u, v((C(u, v) \leftrightarrow P(v, u))$ $\wedge \neg C(u, r))$ (root r via C) (functional P)	$\#s_P(r) = 0 \wedge$ $\forall v(s_P(v) = p_C(v))$
TREERP		$1:1 C \wedge$ $\forall u, v(\neg C(u, s) \wedge \neg R(r, u)$ $\wedge (u \neq s \rightarrow R(u, r)))$ (root r via C) (functional R)	$\#p_C(r) = 0 \wedge$ $p_R(r) = s_{C^+}(r) \wedge$ $\forall v(\#p_C(v) \leq 1)$

Example: Testing If a Graph is Bipartite

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Maintain Invariant: $\beta \equiv \forall xy (E(x, y) \rightarrow (S(x) \leftrightarrow \neg S(y)))$
incrementally as we add edges to an initially empty graph.

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Base Case: $G_0 = (V, \emptyset, \emptyset) \models \beta$

Inductively Assume: $G = (V, E, S) \models \beta$ and add add an edge
 (a, b) : $E' := E \cup \{(a, b)\}$

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Case 1: $(V, E', S) \models \beta$ so we're fine.

Case 2: $(V, E', S) \models \neg\beta$

$$(G, a/x, b/y) \models (S(x) \leftrightarrow S(y))$$

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WLOG to reestablish β we must change the value of $S(a)$.

Case 2: $(V, E', S) \models \neg\beta$

$$(G, a/x, b/y) \models (S(x) \leftrightarrow S(y))$$

WLOG to reestablish β we must change the value of $S(a)$.

Naive Incremental Algorithm: If b is in this connected component, report failure

Else: change the value of $S(c)$ for all c in the connected component of a .

Naive Algorithm takes time $O(nm)$.

Better Incremental Algorithm

Keep track of connected component of a in two disjoint parts:

$$S(a) = C(a) \cap S \qquad \bar{S}(a) = C(a) \cap \bar{S}$$

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With the sets S, \bar{S} instantiated using Union/Find, the complexity of this incremental algorithm is then essentially linear, i.e., $O(m)$.

- ▶ Apply this simple methodology to many more settings.
- ▶ Use to program by example.
- ▶ Use to automatically take care of the tedious part of programming and maintaining software.
- ▶ Use to translate back and forth between different formalisms and levels.
- ▶ Use to generate distributed algorithms, reactive systems, incremental algorithms.
- ▶ Build in composition to make this approach scale.
- ▶ Increase the sophistication of our learning/synthesis approach.