

Divide and Couple: Using Monte Carlo Variational Objectives for Posterior Approximation

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Overview

- Variational inference gives both a *lower-bound* on the log-likelihood and an *approximate posterior*.
- Easy to get other lower-bounds. Do they also give approximate posteriors?
- This work: A general theory connecting likelihood bounds to posterior approximations.



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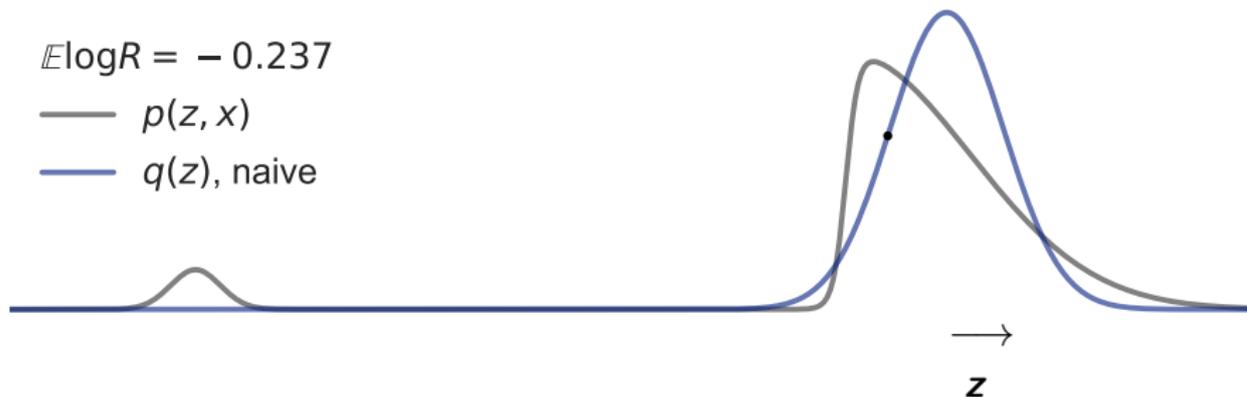
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Example: Take $R = \frac{p(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})}$ for $\mathbf{z} \sim q$ Gaussian, optimize q .

$$\mathbb{E} \log R = -0.237$$

— $p(z, \mathbf{x})$

— $q(z)$, naive



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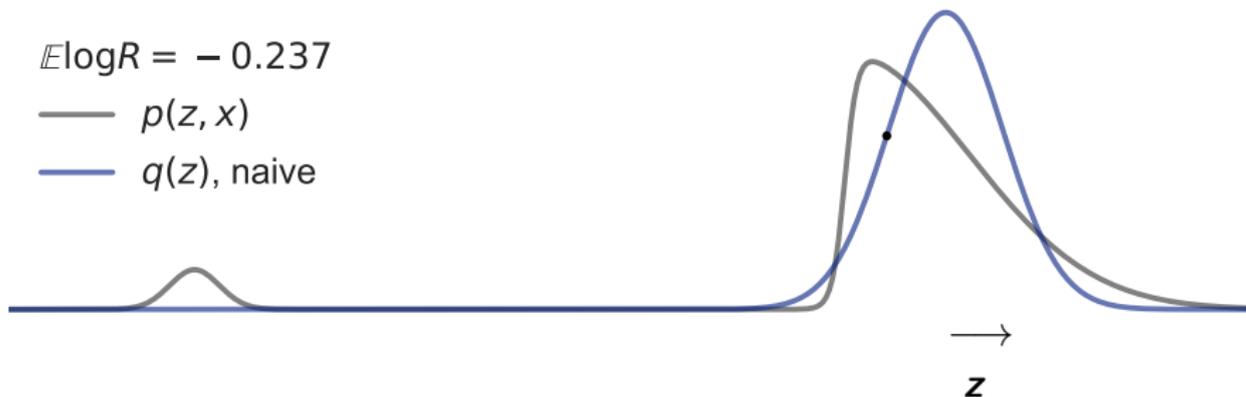
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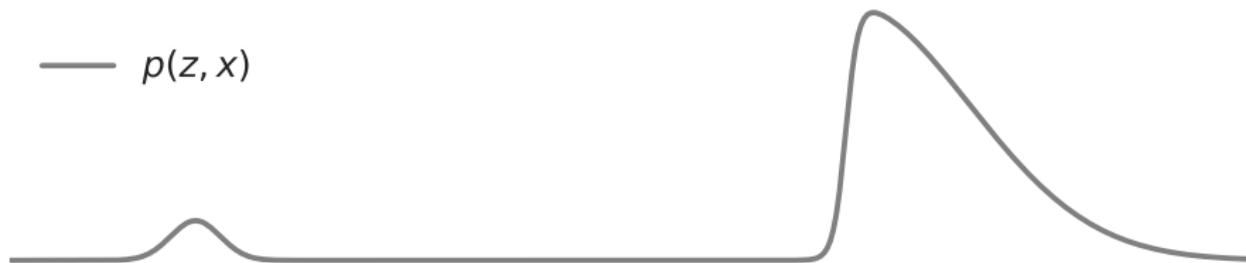
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Decomposition: $KL(q(z) \| p(z | \mathbf{x})) = \log p(\mathbf{x}) - \mathbb{E} \log R$.

- Likelihood bound: ✓
- Posterior approximation: ✓

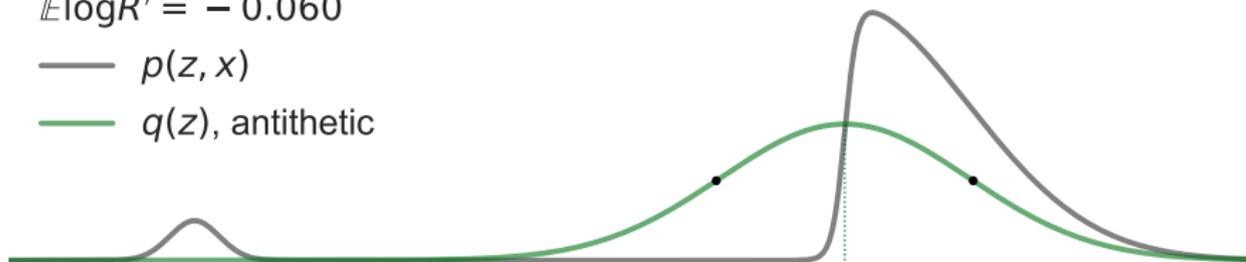


Recent work: Better Monte Carlo estimators R .

$$\mathbb{E} \log R' = -0.060$$

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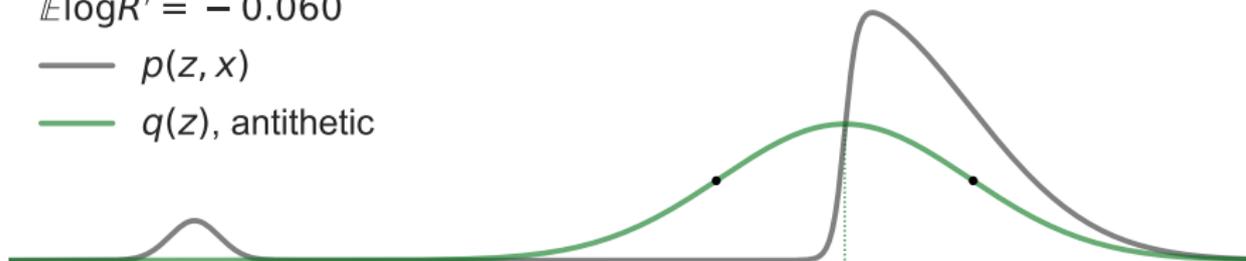
Antithetic Sampling: Let $T(z)$ “flip” z around mean of q .

$$R = \frac{1}{2} \left(\frac{p(z, x) + p(T(z), x)}{q(z)} \right)$$

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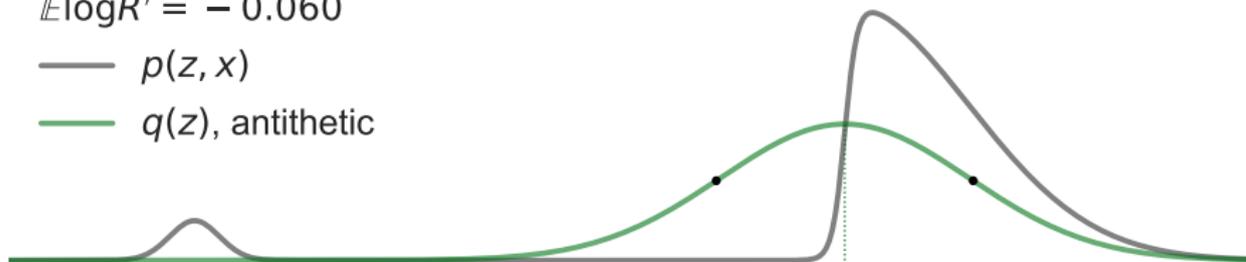
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This paper: Is some *other* distribution close to p ?

Contribution of this paper: Given estimator with $\mathbb{E} R = p(\mathbf{x})$, we show how to construct $Q(\mathbf{z})$ such that

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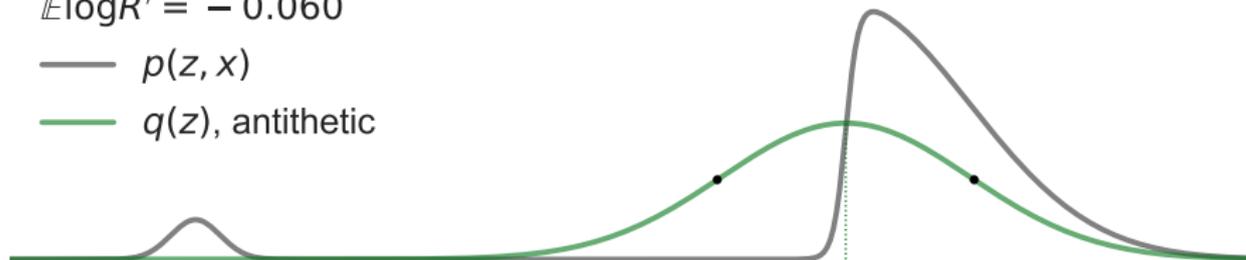
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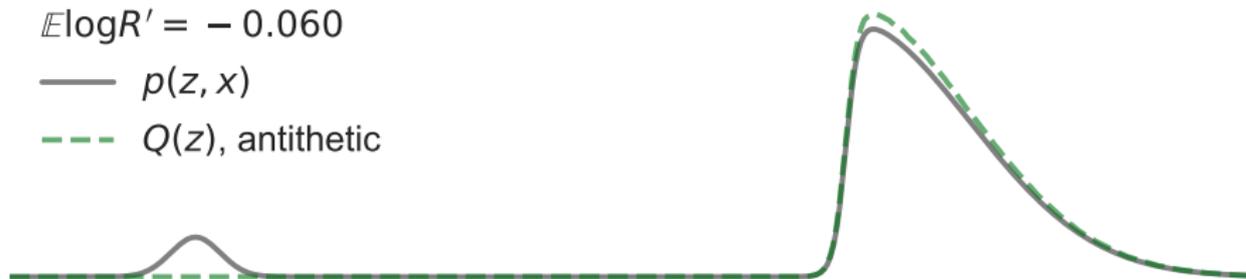
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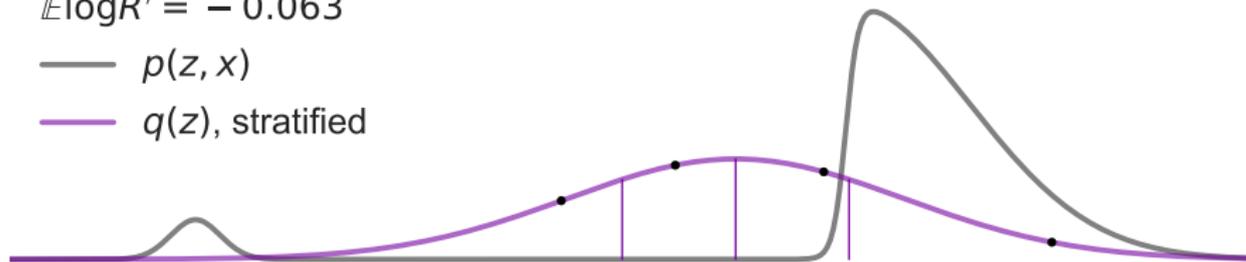
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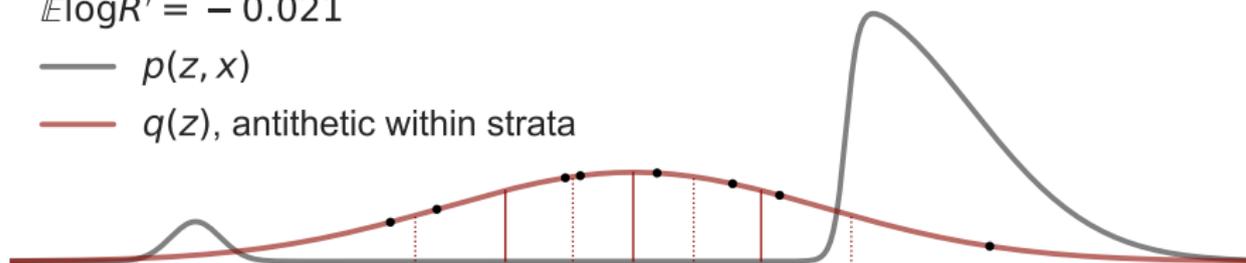
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How?

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Unbiased estimator: **Where is \mathbf{z} ?**

$$\mathbb{E}_{\omega} R(\omega) = p(\mathbf{x})$$

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We suggest: Need a *coupling*:

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Then, exist augmented distributions s.t.

$$KL(Q(\mathbf{z}, \omega)\|p(\mathbf{z}, \omega|\mathbf{x})) = \log p(\mathbf{x}) - \mathbb{E} \log R$$

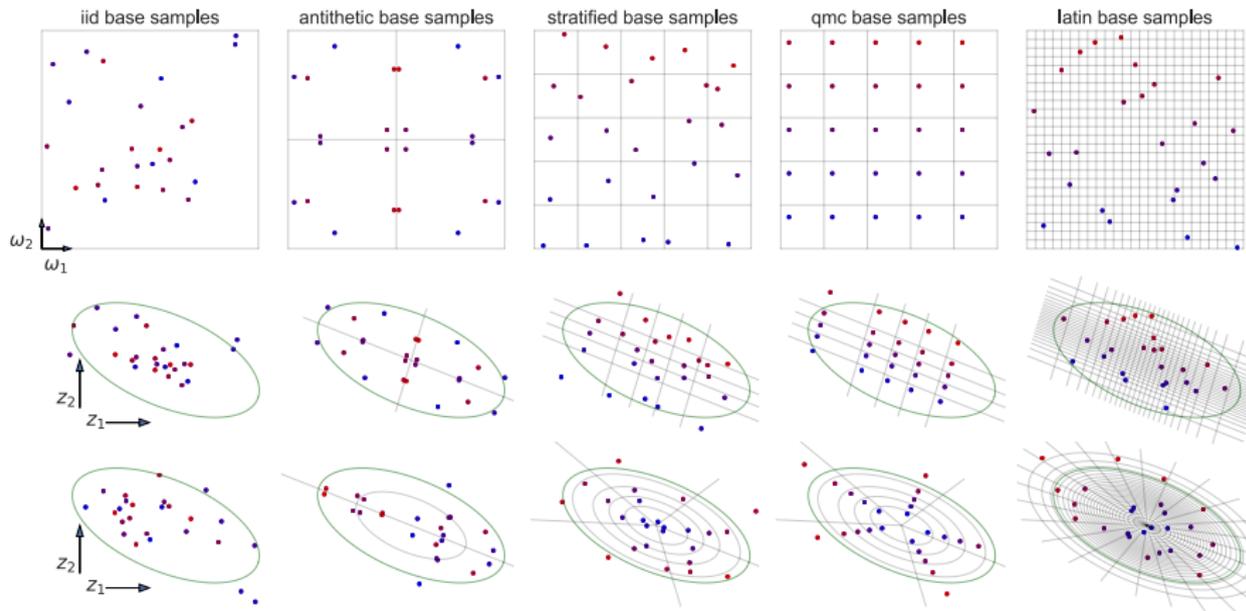
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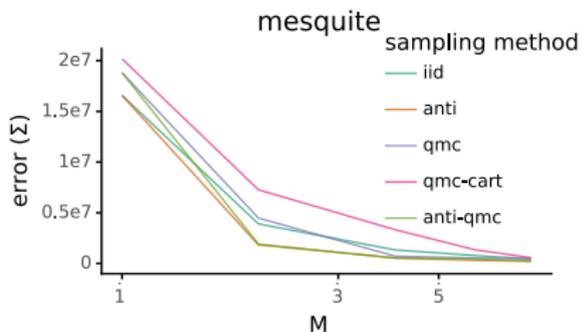
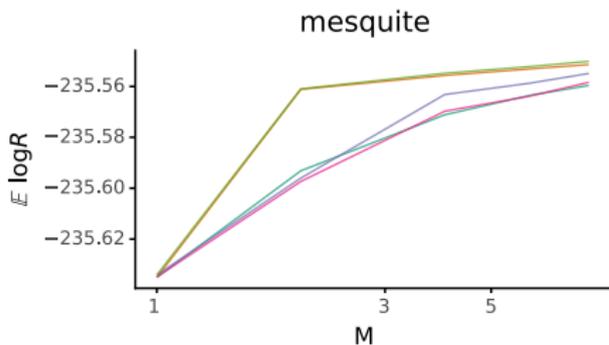
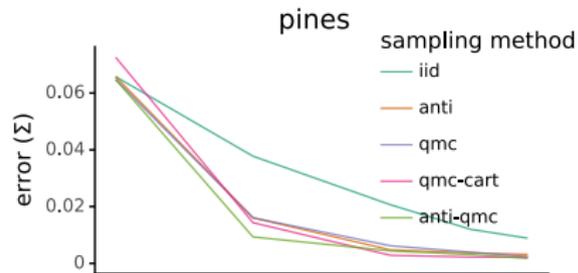
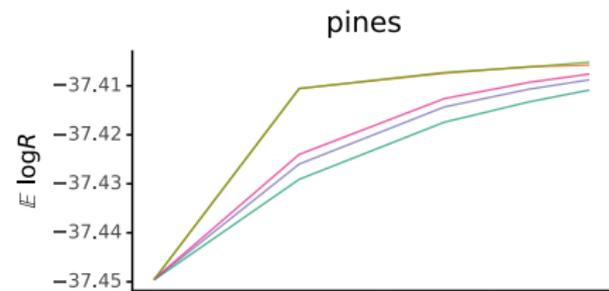
Summary:

- Tightening a bound $\log p(\mathbf{x}) - \mathbb{E} \log R$ is equivalent to VI in an *augmented state space* $(\boldsymbol{\omega}, \mathbf{z})$.
- To sample from $Q(\mathbf{z})$ draw $\boldsymbol{\omega}$ then $\mathbf{z} \sim a(\mathbf{z}|\boldsymbol{\omega})$.
- Paper gives couplings for:
 - ▶ Antithetic sampling
 - ▶ Stratified sampling
 - ▶ Quasi Monte Carlo
 - ▶ Latin hypercube sampling
 - ▶ Arbitrary recursive combinations of above

Implementation: Different sampling methods with Gaussian q .



Experiments confirm: Better likelihood bounds \Leftrightarrow better posteriors



Poster: Tue Dec 10th, 5:30-7:30pm @ East Exhibition Hall B + C #166