# COMPSCI 690RA: Randomized Algorithms and Probabilistic Data Analysis

Prof. Cameron Musco University of Massachusetts Amherst. Spring 2022. Lecture 11

# Logistics

- Problem Set 4 is due next Tuesday 5/2-at 8pm.
- The final exam is next Friday 5/5 at 10:30am for those that are taking it.
- I will hold extended office hours Wed. 5/3 from 2-4pm and Thurs. 5/4 from 4-6pm.
- I will accept final project submissions up until Sunday 5/8 at 11:59pm.
- SRTI's are open for this course. It would be very helpful to me if you can fill them out!
  - This was my first time teaching this course, so feedback on what worked and what didn't is really useful to me.

## Summary

#### Last Week: More Advanced Markov Chains.

- The gambler's ruin problem.
- · Start on Markov chains and their analysis.
- · Aperiodicity and stationary distribution of a Markov chain.
- · Start on mixing time.

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#### Today: Finish up Markov Chains

- Mixing time analysis via coupling.
- Markov Chain Monte Carlo (MCMC) methods.
- · Sampling to country , advetions

#### Fundamental Theorem of Markov Chains

#### Theorem (The Fundamental Theorem of Markov Chains)

Let  $X_0, X_1, \ldots$  be a Markov chain with a finite state space and transition matrix  $P \in [0,1]^{m \times m}$ . If the chain is both irreducible and aperiodic,

- 1. There exists a unique stationary distribution  $\pi \in [0,1]^m$  with  $\pi = \pi P$ .
- 2. For any states i, j,  $\lim_{t\to\infty}\Pr[\mathbf{X}_t=i|X_0=j]=\pi(i)$ . I.e., for any initial distribution  $q_0$ ,  $\lim_{t\to\infty}q_t=\lim_{t\to\infty}q_0P^t=\pi$ .

Question for today: How long does it take us to converge close to this stationary distribution?



remarke T.

# **Mixing Time**

#### Definition (Mixing Time)

Consider a Markov chain  $X_0, X_1, \ldots$  with unique stationary distribution  $\pi$ . Let  $q_{i,t}$  be the distribution over states at time t assuming  $X_0 = i$ . The mixing time is defined as:

$$\tau(\epsilon) = \min \left\{ t : \max_{i \in [m]} \| \underline{q_{i,t}} - \underline{\pi} \|_{\text{TV}} \le \epsilon \right\}.$$

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Note: If 
$$\|q_{i,t} - \pi\|_{TV} \le \epsilon$$
 then for any  $t' \ge t$ ,  $\|q_{i,t'} - \pi\|_{TV} \le \epsilon$ .

Q: 1+ - 1 + e q: 1+ P = P + e P = 1 + e P | ||e|| ||

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Coupling Motivation: Last time we showed that

$$\max_{i \in [m]} \|q_{i,t} - \pi\|_{\text{TV}} \le \max_{i,j \in [m]} \|q_{i,t} - q_{j,t}\|_{\text{TV}}.$$

By Kontorovich-Rubinstein duality, for  $X_t$ ,  $Y_t$  distributed by evolving the chain for t steps starting from state, i or j respectively, we have:

$$\max_{i,j\in[m]} \|q_{i,t} - q_{j,t}\|_{\text{TV}} \leq \max_{i,j\in[m]} \Pr[X_t \neq Y_t].$$

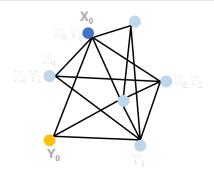
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## Definition (Coupling)

- 1.  $X_0 = i$  and  $Y_0 = j$  for some  $i, j \in [m]$ .
- $\underline{2.} Pr[X_t = j | X_{t-1} = i] = Pr[Y_t = j | Y_{t-1} = i] = P_{i,j}$
- 3. If  $X_t = Y_t$ , then  $X_{t+1} = Y_{t+1}$ .

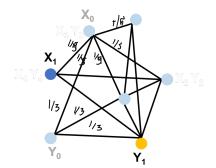
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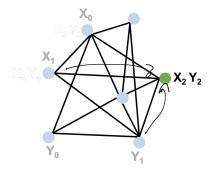
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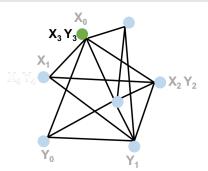
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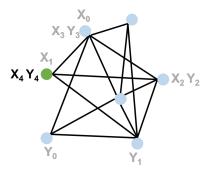
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### Definition (Coupling)

For a finite Markov chain  $X_0, X_1, ...$  with transition matrix  $P \in \mathbb{R}^{m \times m}$ , a coupling is a joint process  $(X_0, Y_0), (X_1, Y_1), ...$  such that:

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### Theorem (Mixing Time Bound via Coupling)

For a finite, irreducible, and aperiodic Markov chain  $X_0, X_1, \ldots$  and any valid coupling  $(X_0, Y_0), (X_1, Y_1), \ldots$  letting

$$\begin{split} \underline{\mathbf{T}_{i,j}} &= \min\{t: \mathbf{X}_t = \mathbf{Y}_t | \mathbf{X}_0 = i, \mathbf{Y}_0 = j\}, \\ &\qquad \qquad \underbrace{\mathbf{G}_{i \in [m]}}_{i \in [m]} \|q_{i,t} - \pi\|_{\mathsf{TV}} \leq \max_{i,j \in [m]} \|q_{i,t} - q_{j,t}\|_{\mathsf{TV}} \leq \max_{i,j \in [m]} \mathsf{Pr}[\mathbf{T}_{i,j} > t]. \end{split}$$

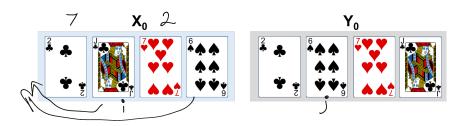
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- Let  $Y_0, Y_1$  be a correlated Markov chain. When card S is swapped to the top in the X chain, swap S to the top in the Y chain as well.

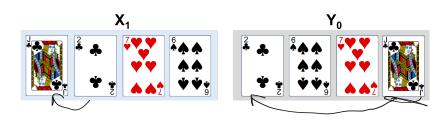
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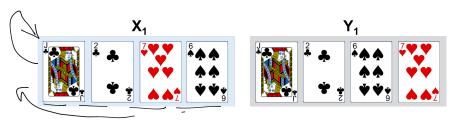
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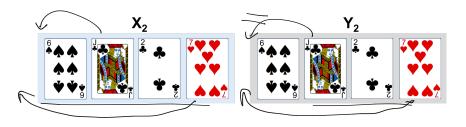
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• Observe that  $X_t = Y_t$  as soon as all c unique cards have been swapped at least once. How many swaps does this take?

$$\begin{split} \max_{i \in [m]} \|q_{i,t} - \pi\|_{\text{TV}} &\leq \max_{i,j \in [m]} \Pr[\mathbf{T}_{i,j} > t] \\ &\leq \Pr[< \underline{c} \text{ unique cards are swapped in } t \text{ swaps}] \end{split}$$

$$\label{eq:linear_problem} \begin{split} \max_{i \in [m]} \|q_{i,t} - \pi\|_{\mathcal{T}V} &\leq \max_{i,j \in [m]} \Pr[\mathsf{T}_{i,j} > t] \\ &\leq \Pr[< c \text{ unique cards are swapped in } t \text{ swaps}] \end{split}$$

By coupon collector analysis for  $\underline{t} \geq c \ln(\underline{c/\epsilon})$ , this probability is bounded by  $\epsilon$ . In particular, by the fact that  $(1-\frac{1}{c})^{c \ln c/\epsilon} \leq \frac{\epsilon}{c}$  plus a union bound over c cards.

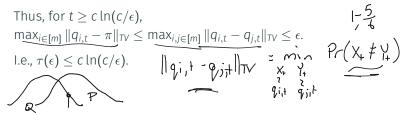
$$Q = \begin{bmatrix} \frac{1}{6} & \frac{1}{6} & \cdots & \frac{1}{6} \end{bmatrix}$$

$$P = \begin{bmatrix} \frac{1}{6} & \frac{1}{5} & \cdots & \frac{1}{6} \end{bmatrix}$$

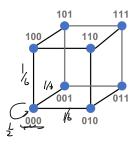
$$\max_{i \in [m]} \|q_{i,t} - \pi\|_{TV} \le \max_{i,j \in [m]} \Pr[T_{i,j} > t]$$

 $\leq$  Pr[< c unique cards are swapped in t swaps]

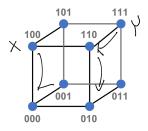
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Let  $X_0, X_1$  be a Markov chain over state space  $\{0, 1\}^n$ . In each step, pick a random position  $i \in [n]$  and set  $X_t(i) = 0$  with probability 1/2 and  $X_t(i) = 1$  with probability 1/2.

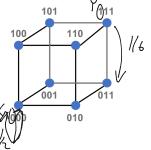


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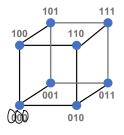


What is a coupling  $(X_0, Y_0), (X_1, Y_1), \ldots$  on this chain that we can use to bound the mixing time of this walk?

In each step, pick a single random position  $i \in [n]$  and let  $X_t(i) = Y_t(i) = 0$  with probability 1/2 and  $X_t(i) = Y_t(i) = 1$  with probability 1/2.



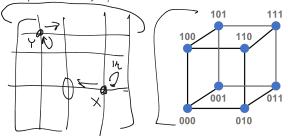
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How large must we set t so that  $\Pr[\mathbf{X}_t \neq \mathbf{Y}_t] \leq \epsilon$ ?

**Upshot:** The mixing time of the *n*-dimensional hypercube is  $\tau(\epsilon) = O(n \log(n/\epsilon))$ .

Markov Chain Monte Carlo

#### Markov Chain Monte Carlo

Many applications in computational biology, machine learning, theoretical computer science, etc. require sampling from complex distributions, which are difficult to write down in closed form, and difficult to directly sample from.

A very common approach is to design a Markov chain whose stationary distribution  $\pi$  is equal to the distribution of interest.

By running this Markov chain for at least  $\tau(\epsilon)$  steps (burn-in time), one can draw a sample which is nearly from the distribution of interest.

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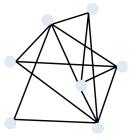
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**Note:** A major focus is on designing and analyzing Markov chains where  $\tau(\epsilon)$  is small. For today, we'll just focus on getting the stationary distribution right, and mostly ignore runtime.

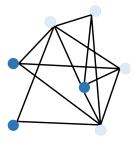
# Sampling Independent Sets

Suppose we would like to sample a uniformly random independent set from a graph *G*.



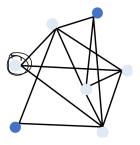
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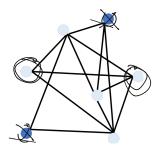
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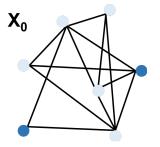


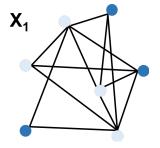
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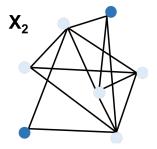
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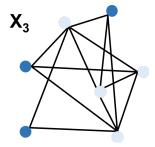


Very non-obvious how to sample from this distribution. Exactly counting the number of independent sets, which is closely related to sampling, is #P-bard.

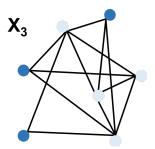








Design a Markov chain  $X_0, X_1, \ldots$  whose states are exactly the independent sets. E.g., let  $X_{t+1}$  be chosen uniformly at random from  $\mathcal{N}(X_t) = \{Y: \text{independent set formed by adding/removing a node from } X_t\}.$ 



Unfortunately, the stationary distribution of this chain may not be uniform. It places higher probability on independent sets with lots of neighboring independent sets.

Define a Markov chain  $X_0, X_1, \ldots$  over independent sets with transition function:

- · Pick a random vertex v.
- · If  $\underline{v} \in X_t$ , set  $X_{t+1} = X_t \setminus \{v\}$ .
- $\cdot \ \ \mathsf{l} \underline{f \ v \notin X_t} \ \text{and} \ X_t \cup \{v\} \ \text{is independent, set} \ X_{\underline{t+1}} = X_t \cup \{v\}.$
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For any two independent sets i, j, what is  $P_{i,j}$ ?  $P_{i,j} = P_{j,i} = 1/|V|$  if i, j differ by one vertex,  $P_{i,j} = P_{j,i} = 0$  otherwise.

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- Pick a random vertex v.
  If v ∈ X<sub>t</sub>, set X<sub>t+1</sub> = X<sub>t</sub> \ {v}.
  If v ∉ X<sub>t</sub> and X<sub>t</sub> ∪ {v} is independent, set X<sub>t+1</sub> = X<sub>t</sub> ∪ {v}.
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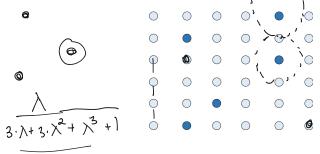
For any two independent sets i, j, what is  $P_{i,j}$ ?  $P_{i,j} = P_{i,j} = 1/|V|$ if i, j differ by one vertex,  $P_{i,j} = P_{j,j} = 0$  otherwise.

Thus, the Markov chain is symmetric, so by our claim from last class, the stationary distribution is uniform.

Suppose we want to sample an independent set X from our graph with probability:  $P(X) = X^{|X|}$ 



Known as the 'hard-core model' in statistical physics.



## Metropolis-Hastings Algorithm

A very generic way of designing a Markov chain over state space [m] with stationary distribution  $\pi \in [0,1]^m$ .

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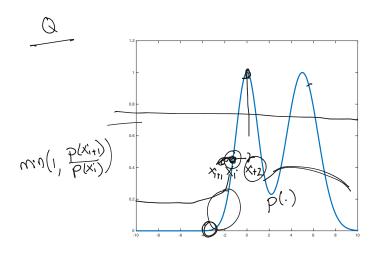
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# Metropolis-Hastings Algorithm

A very generic way of designing a Markov chain over state space [m] with stationary distribution  $\pi \in [0,1]^m$ .

- Assume the ability to efficiently compute a density  $p(X) \propto \pi(X)$ .
- Assume access to some symmetric transition function with transition probability matrix  $Q \in [0, 1]^{m \times m}$ .
- At step t, generate a 'candidate' state  $X_{t+1}$  from  $X_t$  according to Q.
- With probability min  $\left(1, \frac{\rho(X_{t+1})}{\rho(X_t)}\right)$ , 'accept' the candidate. Else 'reject' the candidate, setting  $X_{t+1} = X_t$ .

# Metropolis-Hastings Intuition



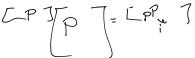
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$$\underbrace{[pP](i)}_{aceptances} = \underbrace{\sum_{j} p(j) \cdot Q_{j,i} \cdot \min\left(1, \frac{p(i)}{p(j)}\right)}_{aceptances} + \underbrace{p(i) \cdot \sum_{j} Q_{i,j}\left(1 - \min\left(1, \frac{p(j)}{p(i)}\right)\right)}_{rejections}$$

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Want to sample an independent set X with probability

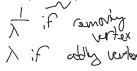
$$\underline{\pi(X)} = \frac{\lambda^{|X|}}{\sum_{Y \text{ independent }} \lambda^{|Y|}}.$$

- Let  $p(X) = \lambda^{|X|}$  and let the transition function Q be given by:
  - · Pick a random vertex v.
  - If  $v \in X_t$ , set  $X_{t+1} = X_t \setminus \{v\}$
  - If  $v \notin X_t$  and  $X_t \cup \{v\}$  is independent, set  $X_{t+1} = X_t \cup \{v\}$ .
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The key challenge then becomes to analyze the mixing time.

For the related Glauber dynamics, Luby and Vigoda showed that for graphs with maximum degree  $\Delta$ , when  $\lambda < \frac{2}{\Delta - 2}$ , the mixing time is  $O(n \log n)$ . But when  $\lambda > \frac{c}{\Delta}$  for large enough constant c, it is NP-hard to approximately sample from the hard-core model

# **Counting to Sampling Reductions**

Often if one can efficiently sample from the distribution  $\underline{\pi(X)} = \underbrace{\frac{p(X)}{y \cdot p(Y)}}_{Y \cdot P(Y)}$  one can efficiently approximate the normalizing constant  $Z = \sum_{Y} p(Y)$  (often called the partition function).

- If Z is hard to approximate, then this can give a proof that sampling is hard, and thus it is unlikely that any simple MCMC method for sampling from  $\pi$  mixes rapidly.
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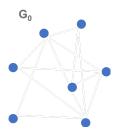
This is e.g., how one can show that sampling from the hard-core model is hard when  $Y = O(1/\Lambda)$ model is hard when  $\lambda = \Omega(1/\Delta)$ .

- Let's consider the simple case of  $\lambda = 1$ , i.e., we want to sample a uniformly random independent set.
- In this case, Z = |S(G)|, the number of independent sets in G. It is known that approximating |S(G)| even up to a poly(n) factor is NP-Hard.

How can we count the number of independent sets |S(G)| in a graph, given an oracle for sampling a uniform random independent set?

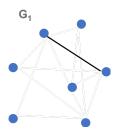
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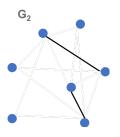
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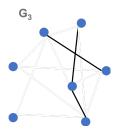
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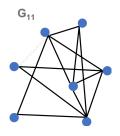
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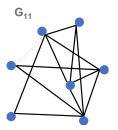
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We can write: 
$$|S(G)| = \frac{|S(G_m)|}{|S(G_{m-1})|} \frac{|S(G_{m-1})|}{|S(G_{m-2})|} \cdot \dots \cdot \frac{|S(G_1)|}{|S(G_0)|} \cdot |S(G_0)|.$$

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where  $r_i = \frac{|S(G_m)|}{|S(G_{m-i})|}$ . If we can estimate each  $r_i$  with  $\tilde{r}_i$  satisfying

$$\left(1-\frac{\epsilon}{2m}\right)\cdot r_i\leq \underline{\tilde{r}_i}\leq \left(1+\frac{\epsilon}{2m}\right)\cdot r_i,$$

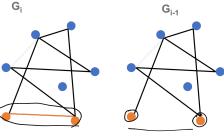
then:

$$\underbrace{(1-\epsilon)\cdot|S(G)|}_{\text{since }} \leq \underbrace{2^n\cdot\Pi_{i=1}^m \tilde{r}_i}_{\text{since }} \leq \underbrace{(1+\epsilon)\cdot|S(G)|}_{\text{since }}$$

$$\underbrace{(1+\frac{\epsilon}{2m})^m}_{\text{m}} \leq 1+\epsilon \text{ and } \underbrace{(1-\frac{\epsilon}{2m})^m}_{\text{m}} \geq 1-\epsilon.$$

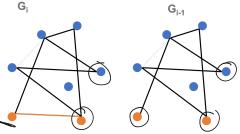
Consider the ratio  $r_i = \frac{|S(G_i)|}{|S(G_{i-1})|}$ . Observe that  $r_i \leq 1$ .

Further,  $r_i \ge 1/2$ . Let (u, v) be the edge removed from  $G_i$  to obtain  $G_{i-1}$ . Then each independent set in  $S(G_{i-1}) \setminus S(G_i)$ , must contain both u and v.



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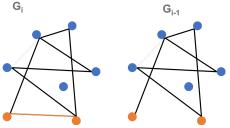
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So, we can map each set in  $S(G_{i-1}) \setminus S(G_i)$  to a unique set in  $S(G_i)$  by simply removing V.  $\left|S(G_i) \setminus S(G_i)\right| \leq \left|S(G_i)\right|$   $A \sim V \text{ and } S \neq S$ 

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$$r_i = \frac{|S(G_i)|}{|S(G_{i-1})|} = \frac{|S(G_i)|}{|S(G_i)| + |S(G_{i-1}) \setminus S(G_i)|} \ge \frac{1}{2}.$$

**So Far:** We have written  $|S(G)| = \underline{2^n \cdot \prod_{i=1}^m r_i}$  where  $r_i = \frac{|S(G_i)|}{|S(G_{i-1})|}$ . Need to get a  $1 \pm \epsilon/m$  estimate to each  $r_i$  to get a  $1 \pm \epsilon$  estimate to |S(G)|.

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Let X be a random variable generated as follows: pick a random independent set from  $G_{i-1}$  and let X = 1 if the set is also independent in  $G_i$ . Otherwise let X = 0.

$$P(X=1) = r$$
  
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#### What is $\mathbb{E}[X]$ ?

How many samples of **X** do we need to take to obtain a  $1 \pm \epsilon/m$  approximation to  $r_i$  with high probability?

**Upshot:** For a graph G with m edges, making  $\tilde{O}(m^2/\epsilon^2)$  calls to a uniform random independent set sampler on G or its subgraphs suffices to approximate the number of independent sets in G up to  $1 \pm \epsilon$  relative error.

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- So a polynomial time algorithm for uniform random independent set sampling, would lead to a polynomial time algorithm for counting independent sets, and hence the collapse of NP to P.
- Observe that near-uniform sampling (as would be obtained e.g., with an MCMC method) would also suffice.