# COMPSCI 514: Algorithms for Data Science

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University of Massachusetts Amherst. Fall 2024.

Lecture 11

- Problem Set 2 is due Friday at 11:59pm.
- My office hours today are in LGRC A104A.
- The midterm exam is next Thursday 7-9pm.
- I will hold review sessions on Tuesday, Wednesday, and Thursday in class. See Piazza for details on times and on midterm review material.
- If you need extended time on the exam, you should have received an email from me. Reach out if you have not.

### Summary

#### Last Class: Similarity Search and LSH

- Fast similarity search via locality sensitive hashing.
- Jaccard similarity and MinHashing for Jaccard LSH.

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This Class:

- Finish up LSH SimHash for cosine similarity.
- Start on randomized methods for compressing high dimensional data.
- Low-distortion embeddings and the Johnson-Lindenstraus (JL) Lemma.

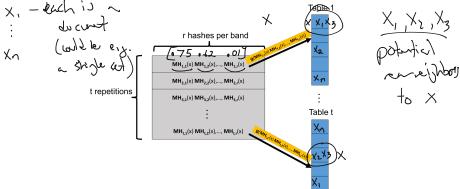
## Hashing for Duplicate Detection

GoalCheck if x is a duplicate of any y in database and return y.Check if x is a duplicate of y in database.Check if x is a duplicate of any y in database and return y.Count iter aduplicate of any y in database and return y.Space $O(n)$ items $O(n)$ bits $O(n \cdot t)$ items (when t tables used) $O\left(\frac{\log n}{d}\right)$	ns,
<b>Space</b> $O(n)$ items $O(n)$ bits $O(n \cdot t)$ items $O\left(\frac{\log n}{2}\right)$	cates.
	$\left(\frac{\log n}{\varepsilon^2}\right)$
Query Time $0(1)$ $0(1)$ Potentially $o(n)$ N	A
Approximate Duplicates? X X V	<

All different variants of detecting duplicates/finding matches in large datasets. An important problem in many contexts.

# Balancing LSH Hit Rate and Query Time

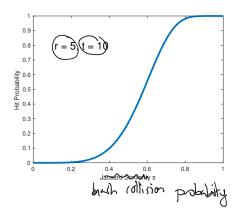
In similarity search with LSH, we use repetition to balance a small probability of false negatives (a high hit rate) with a small probability of false positives (a small query time.)



Create *t* hash tables. Each is indexed into not with a single MinHash value, but with a length-*r* signature of values, appended together.

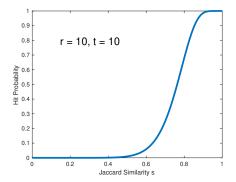
### The s-curve

Using *t* repetitions each with a signature of *r* hash values, the probability that *x* and *y* with collision probability  $\Pr[h(x) = h(y)] = s$  match in at least one repetition is:  $1 - (1 - s^r)^t$ .



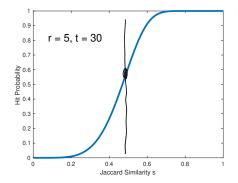
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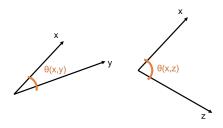
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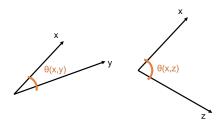
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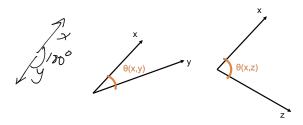
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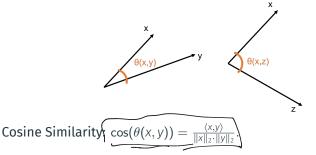


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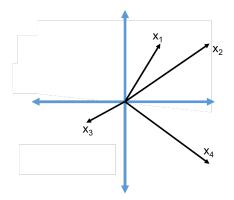
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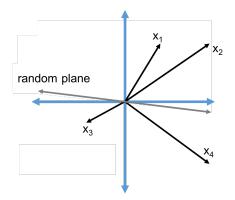
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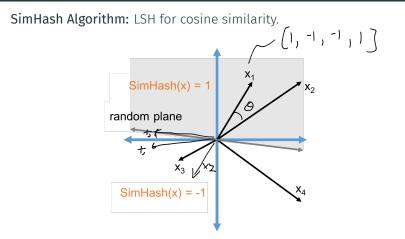
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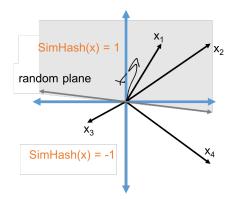


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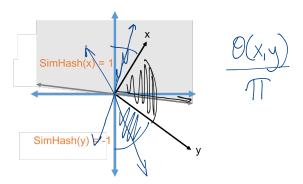


 $\int SimHash(x) = sign(\langle x, t \rangle)$  for a random vector t.

What is  $\Pr[SimHash(x) = SimHash(y)]$ ?

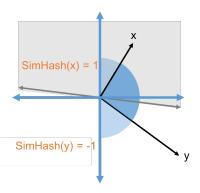
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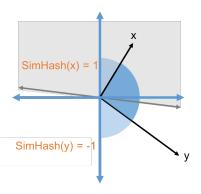
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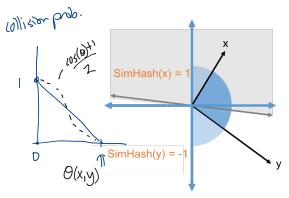
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- Pr [SimHash(x)  $\neq$  SimHash(y)] =  $\frac{\theta(x,y)}{\pi}$
- $\Pr[SimHash(x) = SimHash(y)] = 1 \frac{\theta(x,y)}{\pi} \approx \frac{\cos(\theta(x,y)) + 1}{2}$

## Questions on MinHash and Locality Sensitive Hashing?

'Big Data' means not just many data points, but many measurements per data point. I.e., very high dimensional data.

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- The human genome contains 3 billion+ base pairs. Genetic datasets often contain information on 100s of thousands+ mutations and genetic markers.

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## Data as Vectors and Matrices

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ATAGCCGTAGT >> x = [1 2 1 3 4 4 3 2 1 3 4]

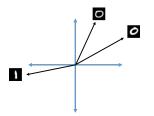


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Similarities/distances between vectors (e.g.,  $\langle x, y \rangle$ ,  $||x - y||_2$ ) have meaning for underlying data points.

### Datasets as Vectors and Matrices

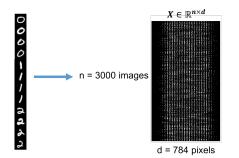
Data points are interpreted as high dimensional vectors, with real valued entries. Data set is interpreted as a matrix. Data Points:  $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n \in \mathbb{R}^d$ . **Data Set:**  $X \in \mathbb{R}^{n \times d}$  with *i*<sup>th</sup> row equal to  $\vec{x}_i^T$ .  $n \left[ \begin{array}{c} -X_{1}^{T} \\ -X_{2}^{T} \end{array} \right]$ 

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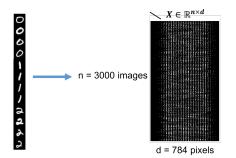


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Many data points  $n \implies$  tall. Many dimensions  $d \implies$  wide.

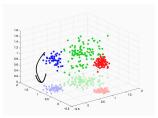
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 for  $m \ll d$ .

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'Lossy compression' that still preserves important information about the relationships between  $\vec{x}_1, \ldots, \vec{x}_n$ .

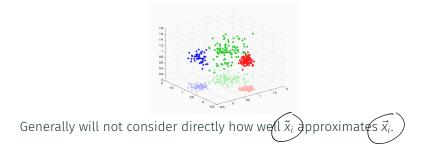


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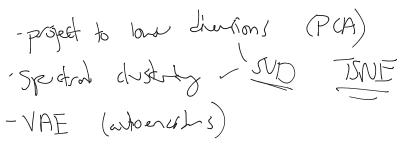
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**5** 
$$\longrightarrow$$
  $x = [0 0 0 0 0 1 0 0 1 1 0 1 1 1...]  $\longrightarrow \tilde{x} = [-5.5 4 3.2 - 1]$$ 

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Dimensionality reduction is one of the most important techniques in data science. What methods have you heard of?



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- Latent semantic analysis (LSA)

PIA



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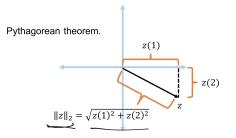
Compressing data makes it more efficient to work with. May also remove extraneous information/noise.

**Euclidean Low Distortion Embedding:** Given  $\vec{x}_1, \ldots, \vec{x}_n \in \mathbb{R}^d$  and error parameter  $\epsilon \ge 0$ , find  $\tilde{x}_1, \ldots, \tilde{x}_n \in \mathbb{R}^m$  (where  $m \ll d$ ) such that for all  $i, j \in [n]$ :

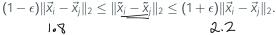
 $(1-\epsilon)\|\vec{x}_i - \vec{x}_j\|_2 \le \|\tilde{x}_i - \tilde{x}_j\|_2 \le (1+\epsilon)\|\vec{x}_i - \vec{x}_j\|_2.$ 

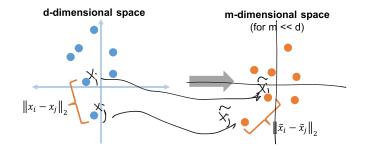
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Recall that for  $\vec{z} \in \mathbb{R}^n$ ,  $\|\vec{z}\|_2 = \sqrt{\sum_{i=1}^n \vec{z}(i)^2}$ .



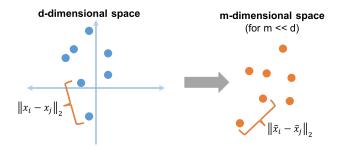
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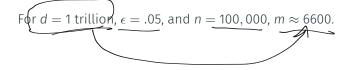


Can use  $\tilde{x}_1, \ldots, \tilde{x}_n$  in place of  $\vec{x}_1, \ldots, \vec{x}_n$  in clustering, SVM, linear classification, near neighbor search, etc.

The Johnson-Lindenstrauss Lemma tells us that for any set of points  $\vec{x}_1, \ldots, \vec{x}_n \in \mathbb{R}^d$  and any  $\epsilon > 0$ , we can find an  $\epsilon$ -distortion embedding into  $\vec{m}$  dimensions, where m depends only on the error parameter  $\epsilon$  and the number of points n, but not the original dimension d.

Johnson-Lindenstrauss Lemma: For any set of points  $\vec{x}_1, \ldots, \vec{x}_n \in \mathbb{R}^d$  and  $\epsilon > 0$  there exists a linear map  $\mathbf{\Pi} : \mathbb{R}^d \to \mathbb{R}^m$ such that  $m = O\left(\frac{\log n}{\epsilon^2}\right)$  and letting  $\tilde{x}_i = \mathbf{\Pi} \vec{x}_i$ : For all i, j:  $(1 - \epsilon) \|\vec{x}_i - \vec{x}_i\|_2 \le \|\tilde{x}_i - \tilde{x}_i\|_2 \le (1 + \epsilon) \|\vec{x}_i - \vec{x}_i\|_2$ . Further, if  $\mathbf{\Pi} \in \mathbb{R}^{m \times d}$  has each entry chosen i.i.d. from  $\mathcal{N}(0, 1/m)$ , it satisfies the guarantee with high probability. mxl  $\mathcal{N}(\mathbf{N}_{i},\mathbf{M})$   $\mathcal{T}$   $\uparrow$   $\uparrow$   $\uparrow$ embeddy sim 18 **Johnson-Lindenstrauss Lemma:** For any set of points  $\vec{x}_1, \ldots, \vec{x}_n \in \mathbb{R}^d$  and  $\epsilon > 0$  there exists a linear map  $\Pi : \mathbb{R}^d \to \mathbb{R}^m$  such that  $m = O\left(\frac{\log n}{\epsilon^2}\right)$  and letting  $\tilde{x}_i = \Pi \vec{x}_i$ : For all  $i, j : (1 - \epsilon) \|\vec{x}_i - \vec{x}_i\|_2 \le \|\tilde{x}_i - \tilde{x}_i\|_2 \le (1 + \epsilon) \|\vec{x}_i - \vec{x}_i\|_2$ .

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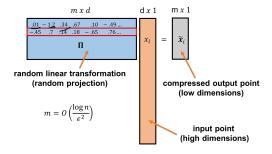
For d = 1 trillion,  $\epsilon = .05$ , and n = 100,000,  $m \approx 6600$ .

Very surprising! Powerful result with a simple construction: applying a random linear transformation to a set of points preserves distances between all those points with high probability.

#### **Random Projection**

For any  $\vec{x}_1, \ldots, \vec{x}_n$  and  $\mathbf{\Pi} \in \mathbb{R}^{m \times d}$  with each entry chosen i.i.d. from  $\mathcal{N}(0, 1/m)$ , with high probability, letting  $\tilde{\mathbf{x}}_i = \mathbf{\Pi} \vec{x}_i$ :

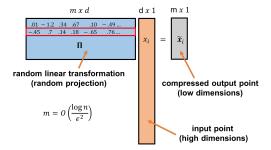
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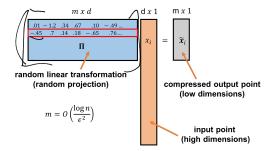


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- is known as a random projection. It is a random linear function, mapping length d vectors to length m vectors.
- **n** is data oblivious. Stark contrast to methods like PCA.

• Many alternative constructions:  $\pm 1$  entries, sparse (most entries 0), Fourier structured, etc.  $\implies$  more efficient computation of  $\tilde{\mathbf{x}}_i = \mathbf{\Pi} \vec{x}_i$ .

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   *x i* = **Π***x i*.
- Data oblivious property means that once  $\Pi$  is chosen,  $\underline{\tilde{x}}_1, \dots, \underline{\tilde{x}}_n$  can be computed in a stream with little memory.
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- Memory needed is just O(d + nm) vs. O(nd) to store the full data set.
- Compression can also be easily performed in parallel on different servers.

- Many alternative constructions: ±1 entries, sparse (most entries 0), Fourier structured, etc. ⇒ more efficient computation of x
  <sub>i</sub> = Πx
  <sub>i</sub>.
- Data oblivious property means that once  $\Pi$  is chosen,  $\tilde{x}_1,\ldots,\tilde{x}_n$  can be computed in a stream with little memory.
- Memory needed is just O(d + nm) vs. O(nd) to store the full data set.
- Compression can also be easily performed in parallel on different servers.
- When new data points are added, can be easily compressed, without updating existing points.

$$\widehat{X}_{1}$$
...  $\widetilde{X}$   $\widehat{T}X_{n+1}$  =  $\widehat{X}_{n+1}$