# COMPSCI 514: Algorithms for Data Science 

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University of Massachusetts Amherst. Fall 2022.
Lecture 11

Logistics
4.1 tables of site $O(m)$
tables of size $n=O(k)$

- Problem Set 2 is due on Friday at 11:59pm.
- Midterm is in class next Thursday, 10/20.
- I have posted a study guide and practice questions on the course schedule.



## Summary

## Last Class:

- Introduced the $k$-frequent elements problem - identify all elements of a stream of $n$ elements that occur $\geq n / k$ times.
- Saw how to solve approximately in $O(k \log n / \epsilon)$ space using the Count-min sketch algorithm. $\quad d k / \Sigma$
- SSimple analysis based on Markov's inequality and repeated random hashing.


## This Class:

- Recap and finish up Count-min sketch
- Randomized methods for dimensionality reduction.
- The Johnson-Lindenstrauss Lemma.


## Count-Min Sketch

( $\varepsilon$ ) K) -Fres Thens Froblem at least $n / k$. Don't return any with frequency $\leq(1-\epsilon) \cdot \frac{n}{k}$.

$f\left(x_{1}\right)$

## Count-Min Sketch

Goal: Return all items in a stream of $n$ elements with frequency at least $n / k$. Don't return any with frequency $\leq(1-\epsilon) \cdot \frac{n}{k}$.


- $\frac{A[h(x)]}{\mathbb{E}\left[\sum_{y \neq x: h}=\underline{f(x)=h(x)}+\sum_{y \neq x: h(y)=h(x)} f(y)\right] \leq \frac{11}{m} .}$ where


## Count-Min Sketch

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$f(x)=t s v^{e}$ fred.


- $\begin{array}{ll} & A[h(x)]=f(x)+\sum_{y \neq x: h(y)=h(x)} f(y) \text { where } \\ & \mathbb{E}\left[\sum_{y \neq x: h(y)=h(x)} f(y)\right] \leq \frac{n}{m} .\end{array} \operatorname{Pr}\left(f(x) \geq f(x)+\frac{2 n}{m}\right) \leq \frac{1}{2}$
- If we let $\tilde{f}(x)$ be the minimum of $t=\log _{2}(1 / \delta)$ estimates, $\xrightarrow{f(x) \leq \tilde{f}(x) \leq f(x)+\frac{2 n}{m}}$ with probability at least $1-\delta$.


## Count-Min Sketch

Goal: Return all items in a stream of $n$ elements with frequency


$$
\begin{aligned}
& \operatorname{pr}\left\{\hat{f}(x) \cdot \Delta+\cdots[h(x)]=f(x)+\sum_{y \neq x: h(y)=h(x)} f(y)\right. \text { where } \\
& \frac{2 n}{m} \leqq \frac{\varepsilon n}{k} \\
& \mathbb{E}\left[\sum_{y \neq x: h(y)=h(x)} f(y)\right] \leq \frac{n}{m} .
\end{aligned}
$$

- If we let $\tilde{f}(x)$ be the minimum of $t=\log _{2}(1 / \delta)$ estimates, $f(x) \leq \tilde{f}(x) \leq f(x)+\frac{2 n}{m}$ with probability at least $1-\delta$.
- Setting $\underline{m=O(k / \epsilon)}, \delta=O(\underline{\delta} / n)$, and applying a union bound, we have a good estimate for all $f(x)$ with
probability at least $1-\delta^{\prime}$.
$m \cdot t=O\left(\frac{\log \left(\Lambda / \alpha^{\prime}\right)}{\varepsilon} \cdot k\right)$


## Identifying Frequent Elements

Count-min sketch gives an accurate frequency estimate for every item in the stream. But how do we identify the frequent items without having to store/look up the estimated frequency for all elements in the stream?

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One approach:

$$
\frac{1}{1-s} \cdot k
$$



- When a new item comes in at step $i$, check if its estimated frequency is $\geq i / k$ and store it if so.
$\sqrt{\text { At step } i \text { remo any stored items whose estimated }}$ frequency drops below $i / k$.
- Store at most $\underline{O(k)}$ items at once and have all items with frequency $\geq n / k$ stored at the end of the stream, no items with frequency $<(1-\epsilon) \cdot \frac{n}{R}$.
$O\left(\log n s \frac{\hbar}{\varepsilon}\right)$
$O\left(k^{*}\right)$
$O(m \circ t+k)$


## High Dimensional Data

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- A 3 minute Youtube clip with a resolution of $500 \times 500$ pixels at 15 frames/second with 3 color channels is a recording of $\geq 2$ billion pixel values. Even a $500 \times 500$ pixel color image has 750, 000 pixel values.


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The human genome contains 3 billion+ base pairs. Genetic datasets often contain information on 100s of thousands+ mutations and genetic markers.

## Data as Vectors and Matrices

In data analysis and machine learning, data points with many attributes are often stored, processed, and interpreted as high dimensional vectors, with real valued entries.

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Similarities/distances between vectors (e.g., $\langle x, y\rangle,\|x-y\|_{2}$ ) have meaning for underlying data points.

## Datasets as Vectors and Matrices

Data points are interpreted as high dimensional vectors, with real valued entries. Data set is interpreted as a matrix.

Data Points: $\vec{x}_{1}, \vec{x}_{2}, \ldots, \vec{x}_{n} \in \mathbb{R}^{d}$.
Data Set: $X \in \mathbb{R}^{n \times d}$ with $i^{\text {th }}$ row equal to $\vec{x}_{i}$.

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Many data points $n \Longrightarrow$ tall. Many dimensions $d \Longrightarrow$ wide.

## Dimensionality Reduction

Dimensionality Reduction: Compress data points so that they lie in many fewer dimensions.

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$$
\underline{\underline{\vec{x}_{1}, \ldots, \vec{x}_{n} \in \mathbb{R}^{d}}} \rightarrow \xlongequal{\tilde{x}_{1}, \ldots, \tilde{x}_{n}} \in \mathbb{R}^{m} \text { for } m \ll d
$$

$$
5 \longrightarrow x=[00000100110111 \cdots] \longrightarrow \tilde{x}=[-5.543 .2-1]
$$

## Dimensionality Reduction

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\begin{gathered}
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'Lossy compression that still preserves important information about the relationships between $\vec{x}_{1}, \ldots, \vec{x}_{n}$.


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Generally will not consider directly how well $\tilde{x}_{i}$ approximates $\vec{x}_{i}$.

Dimensionality Reduction
Dimensionality reduction is one of the most important techniques in data science. What methods have you heard of?

$$
\frac{P G A}{T-S N E} \rightarrow L A
$$

Auto encoders, Neat networks
Self-argarizing maps
clustering
OREG, MPG

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- Principal component analysis
- Latent semantic analysis (LSA)

- Linear discriminant analysis
- Autoencoders


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Raw Text


Term Document Representation

$$
\left.\begin{array}{rl}
x_{1} & =\left[\begin{array}{lllllllllllll}
0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 0 & 1
\end{array}\right] \\
x_{2} & =\left[\begin{array}{lllllllll}
0 & 1 & 1 & 1 & 0 & 1 & 0 & 1 & 1
\end{array} 1\right. \\
& \ldots
\end{array}\right]
$$

Latent Representation

```
                                \mp@subsup{\tilde{x}}{1}{}}=[\begin{array}{lll}{1.1 2.4 0-5]}
                                    \tilde{x}
\[
\tilde{x}_{n}=\left[\begin{array}{llll}
10.6-1 & -1 & 2.2
\end{array}\right]
\]
```

- Linear discriminant analysis
- Autoencoders

Compressing data makes it more efficient to work with. May also remove extraneous information/noise.

Embeddings for Euclidean Space
Euclidean Low Distortion Embedding: Given $\vec{x}_{1}, \ldots, \vec{x}_{n} \in \mathbb{R}^{d}$ and error parameter $\epsilon \geq 0$, find $\tilde{x}_{1}, \ldots, \tilde{x}_{n} \in \mathbb{R}^{m}$ (where $m \ll d$ ) such that for all $i, j \in[n]:$

$$
(1-\epsilon)\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2} \leq \underbrace{\left\|\tilde{x}_{i}-\tilde{x}_{j}\right\|_{2}}_{m-d^{2}-n^{2}} \leq(1+\epsilon)\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2} .
$$

## Embeddings for Euclidean Space

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$$

Recall that for $\vec{z} \in \mathbb{R}^{n},\|\vec{z}\|_{2}=\sqrt{\sum_{i=1}^{n} \vec{z}(i)^{2}}$.


## Embeddings for Euclidean Space

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m-dimensional space
(for $m \ll d$ )


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$$


m-dimensional space
(for $\mathrm{m} \ll \mathrm{d}$ )


Can use $\tilde{x}_{1}, \ldots, \tilde{x}_{n}$ in place of $\vec{x}_{1}, \ldots, \vec{x}_{n}$ in clustering, SVM, linear classification, near neighbor search, etc.

## Embedding with Assumptions

A very easy case: Assume that $\vec{x}_{1}, \ldots, \vec{x}_{n}$ all lie on the $1^{\text {st }}$ axis in $\mathbb{R}^{d}$.


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$$
\tilde{x}_{1}=[-5] \quad \hat{x}_{2}=[3]
$$



Set $\underline{m=1}$ and $\underline{\tilde{x}_{i}}=\underline{\left.\vec{x}_{i}(1)\right]}$ (i.e., $\tilde{x}_{i}$ contains just a single number).

$$
\underline{\left\|\tilde{x}_{i}-\tilde{x}_{j}\right\|_{2}}=\sqrt{\left[\vec{x}_{i}(1)-\vec{x}_{j}(1)\right]^{2}}=\left|\vec{x}_{i}(1)-\vec{x}_{j}(1)\right|=\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2} .
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- $\left\|\tilde{x}_{i}-\tilde{x}_{j}\right\|_{2}=\sqrt{\left[\vec{x}_{i}(1)-\vec{x}_{j}(1)\right]^{2}}=\left|\vec{x}_{i}(1)-\vec{x}_{j}(1)\right|=\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2}$.
- An embedding with no distortion from any $d$ into $m=1$.


## Embedding with Assumptions

Assume that $\vec{x}_{1}, \ldots \vec{x}_{n}$ lie in ayk-dimensional subspace $\mathcal{V}$ of $\mathbb{R}^{d}$.


## Embedding with Assumptions

Assume that $\vec{x}_{1}, \ldots \vec{x}_{n}$ lie in any $k$-dimensional subspace $\mathcal{V}$ of $\mathbb{R}^{d}$.


- Let $\vec{v}_{1}, \vec{V}_{2} \ldots \vec{V}_{k}$ be an orthonormal basis for $\mathcal{V}$ and let $\mathcal{V} \in \mathbb{R}^{d \times k}$ be the matrix with these vectors as its columns.


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- For all $i, j$ we have $\vec{x}_{i}-\vec{x}_{j} \in \mathcal{V}$ and (a good exercise!):

$$
\| \underline{\vec{x}_{i}-\vec{x}_{j} \|_{2}}=\sqrt{\sum_{\ell=1}^{k} \underline{\left\langle v_{\ell}\right.}, \underline{\left.\vec{x}_{i}-\vec{x}_{j}\right\rangle^{2}}}
$$

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\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2}=\sqrt{\sum_{\ell=1}^{k}\left(\underline{v_{\ell}}, \vec{x}_{i}-\vec{x}_{j}\right\rangle^{2}}
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- For all $i, j$ we have $\vec{x}_{i}-\vec{x}_{j} \in \mathcal{V}$ and (a good exercise!):

$$
\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2}=\sqrt{\sum_{\ell=1}^{k}\left\langle\vec{v}_{\ell}, \vec{x}_{i}-\vec{x}_{j}\right\rangle^{2}}=\| \mathbf{V}^{\top} \underline{\left(\vec{x}_{i}-\vec{x}_{j}\right) \|_{2}} .
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\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2}=\sqrt{\sum_{\ell=1}^{k}\left\langle v_{\ell}, \vec{x}_{i}-\vec{x}_{j}\right\rangle^{2}}=\left\|\mathbf{V}^{\top}\left(\vec{x}_{i}-\vec{x}_{j}\right)\right\|_{2} .
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$$

- If we set $\tilde{x}_{i} \in \mathbb{R}^{k}$ to $\tilde{x}_{i}=\mathrm{V}^{\top} \vec{x}_{i}$ we have:

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\left\|\tilde{x}_{i}-\tilde{x}_{j}\right\|_{2}=\left\|\mathbf{V}^{\top} \vec{x}_{i}-\mathbf{V}^{\top} \vec{x}_{j}\right\|_{2}
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Embedding with Assumptions
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- Let $\vec{V}_{1}, \vec{V}_{2}, \ldots \vec{V}_{k}$ be an orthonormal basis for $\mathcal{V}$ and let $V \in \mathbb{R}^{d \times k}$ be the matrix with these vectors as its columns.
- For all $i, j$ we have $\vec{x}_{i}-\vec{x}_{j} \in \mathcal{V}$ and (a good exercise!):
- If we set $\tilde{x}_{i} \in \mathbb{R}^{k}$ to $\tilde{x}_{i}=\overline{\bar{d}}^{\top} \overrightarrow{\underline{x}}_{i}$ we have:

\[

\]

$$
\widetilde{x}_{1}=\left[v^{\top}\right]\left[x_{i}\right]=\left[\tilde{x}_{1}\right]
$$

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- An embedding with no distortion from any $d$ into $m=k$.


## Embedding with Assumptions

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$$

- An embedding with no distortion from any $d$ into $m=k$.
$\left[{ }_{2} \mathrm{~V}^{\top}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{k}\right.$ is a linear map giving our embedding.


## Embedding with No Assumptions

What about when we don't make any assumptions on $\vec{x}_{1}, \ldots, \vec{x}_{n}$. I.e., they can be scattered arbitrarily around d-dimensional space?

- Can we find a no-distortion embedding into $m \ll d$ dimensions?


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## Embedding with No Assumptions

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- Can we find a no-distortion embedding into $m \ll d$ dimensions? No. Require $m=d$.
- Can we find an $\epsilon$-distortion embedding into $m \ll d$ dimensions for $\epsilon>0$ ?

$$
\text { For all } i, j:(1-\epsilon)\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2} \leq \underbrace{\left\|\tilde{x}_{i}-\tilde{x}_{j}\right\|_{2} \leq(1+\epsilon)\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2} .}
$$

## Embedding with No Assumptions

What about when we don't make any assumptions on $\vec{x}_{1}, \ldots, \vec{x}_{n}$. I.e., they can be scattered arbitrarily around d-dimensional space?

- Can we find a no-distortion embedding into $m \ll d$ dimensions? No. Require $m=d$.
- Can we find an $\epsilon$-distortion embedding into $m \ll d$ dimensions for $\epsilon>0$ ? Yes! Always, with $m$ depending on $\epsilon$.

For all $i, j:(1-\epsilon)\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2} \leq\left\|\tilde{x}_{i}-\tilde{x}_{j}\right\|_{2} \leq(1+\epsilon)\left\|\vec{x}_{i}-\vec{x}_{j}\right\|_{2}$.

## The Johnson-Lindenstrauss Lemma

Johnson-Lindenstrauss Lemma: For any set of points $\vec{x}_{1}, \ldots, \vec{x}_{n} \in \mathbb{R}^{d}$ and $\epsilon>0$ there exists a linear map $\boldsymbol{\Pi}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{m}$ such that $\underline{m}=O\left(\frac{\log n}{\epsilon^{2}}\right)$ and letting $\tilde{x}_{i}=\overrightarrow{\boldsymbol{n}}_{i}$ :

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Further, if $\Pi \in \mathbb{R}^{m \times d}$ has each entry chosen i.i.d. from $\mathcal{N}(0,1 / m)$, it satisfies the guarantee with high probability.

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For $d=1$ trillion, $\epsilon=.05$, and $n=100,000, m \approx 6600$.

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Very surprising! Powerful result with a simple construction: applying a random linear transformation to a set of points preserves distances between all those points with high probability.

## Random Projection

For any $\vec{x}_{1}, \ldots, \vec{x}_{n}$ and $\boldsymbol{\Pi} \in \mathbb{R}^{m \times d}$ with each entry chosen i.i.d. from $\mathcal{N}(0,1 / m)$, with high probability, letting $\tilde{\mathbf{x}}_{i}=\boldsymbol{\Pi} \overrightarrow{\mathrm{x}}_{i}$ :

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- $\boldsymbol{\Pi}$ is known as a random projection. It is a random linear function, mapping length $d$ vectors to length $m$ vectors.
- $\boldsymbol{\Pi}$ is data oblivious. Stark contrast to methods like PCA.

