

# COMPSCI 514: ALGORITHMS FOR DATA SCIENCE

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University of Massachusetts Amherst. Fall 2021.

Lecture 7

- Problem Set 1 due tomorrow at **11:59pm**.
- My office hours are this evening at 5pm.

### Last Class:

- Bloom filters for storing a set with a small false positive rate.
- Space usage of  $O(n)$  bits vs.  $O(n \cdot \text{item size})$  for hash tables.

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## This Class:

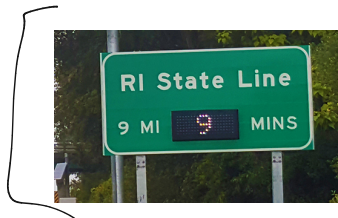
- Start on streaming algorithms
  - The distinct items problem via random hashing.
  - Distinct elements in practice: Flajolet-Martin and HyperLogLog.
-

**Stream Processing:** Have a massive dataset  $X$  with  $n$  items  $x_1, x_2, \dots, x_n$  that arrive in a continuous stream. Not nearly enough space to store all the items (in a single location).

- Still want to analyze and learn from this data.
- Typically must compress the data on the fly, storing a data structure from which you can still learn useful information.
- Often the compression is randomized. E.g., bloom filters.
- Compared to traditional algorithm design, which focuses on minimizing **runtime**, the big question here is how much **space** is needed to answer queries of interest.

## SOME EXAMPLES

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- Distinct IP addresses clicking on an ad or visiting a site.
- Distinct values in a database column (for estimating sizes of joins and group bys).
- Number of distinct search engine queries.
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**Think Pair Share:** Discuss ways you might solve this problem without storing the full list of items seen.

## DISTINCT ELEMENTS IDEAS

- split range of inputs and only remember if you've seen something in a chunk of the range.
- remember element counts
- hash into blocks to avoid collisions
- store some fingerprint of data



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**Min-Hashing for Distinct Elements (variant of Flajolet-Martin):**

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- $s := 1$
- For  $i = 1, \dots, n$ 
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- Return  $\tilde{d} = \frac{1}{s} - 1$

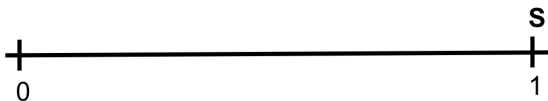
$$1 \quad \mathbf{h}(1) \rightarrow .236$$

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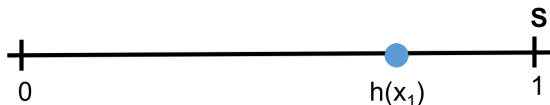
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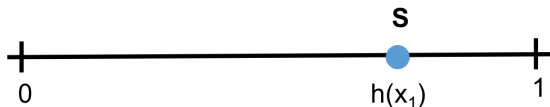
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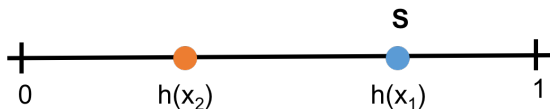
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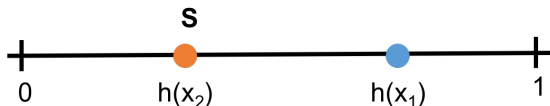
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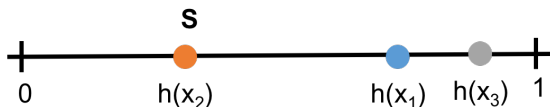
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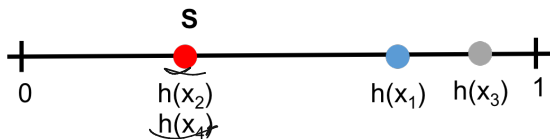


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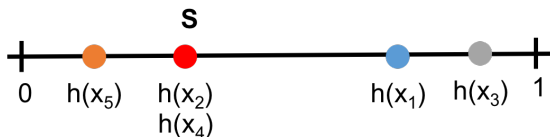
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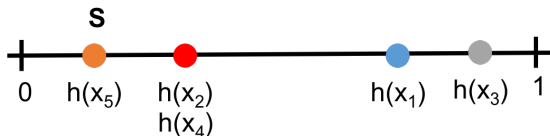
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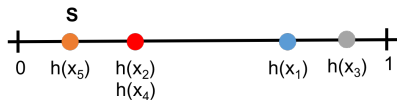
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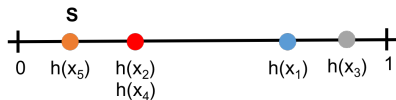
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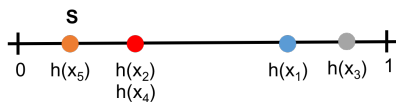
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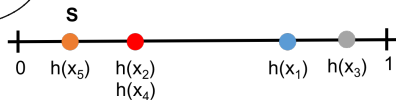


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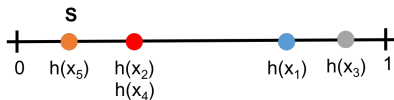
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- Same idea as [Flajolet-Martin algorithm](#) and [HyperLogLog](#), except they use discrete hash functions.

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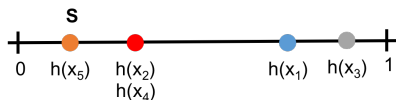


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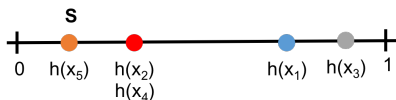
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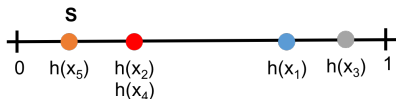
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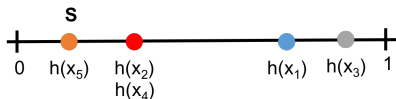
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$$s = \frac{1}{d+1} \quad \tilde{d} = \frac{1}{s} - 1 = d+1 - 1 = d$$

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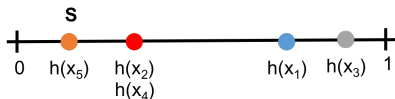
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$$\cancel{\mathbb{E}\left[\frac{1}{Y}\right] = \frac{1}{\mathbb{E}(Y)}}$$

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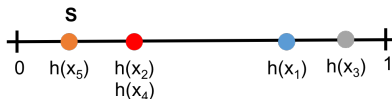
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$$\frac{1}{6} \cdot 1 + \frac{1}{6} \cdot 2 \dots + \frac{1}{6} \cdot 6$$

$$1 + \frac{5}{6} + \frac{4}{6} + \dots + \frac{1}{6}$$

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$\int \sim \frac{1}{d+1}$

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- **Approximation is robust:** if  $|s - \mathbb{E}[s]| \leq \epsilon \cdot \mathbb{E}[s]$  for any  $\epsilon \in (0, 1/2)$  and a small constant  $c \leq 4$ :

$$(1 - c\epsilon)d \leq \hat{d} \leq (1 + c\epsilon)d$$

So question is how well  $\mathbf{s}$  concentrates around its mean.

$$\mathbb{E}[\mathbf{s}] = \frac{1}{d+1}$$

$\mathbf{s}$ : minimum of  $d$  distinct hashes chosen randomly over  $[0, 1]$ , computed by hashing algorithm.  $\hat{\mathbf{d}} = \frac{1}{\mathbf{s}} - 1$ : estimate of # distinct elements  $d$ .

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Chebyshev's Inequality:

$$\Pr [ \underbrace{|\mathbf{s} - \mathbb{E}[\mathbf{s}]|}_{\geq \epsilon \mathbb{E}[\mathbf{s}]} ] \leq \frac{\text{Var}[\mathbf{s}]}{(\underbrace{\epsilon \mathbb{E}[\mathbf{s}]})^2} .$$

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Bound is vacuous for any  $\epsilon < 1$ .

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## INITIAL CONCENTRATION BOUND

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Chebyshev's Inequality:

Handwritten annotations: a box around  $1 + \epsilon$  with a checkmark, and  $E[s]$  crossed out with a diagonal line, with  $(1 + \epsilon)E[s]$  written below it.

$$\Pr[|\mathbf{s} - \mathbb{E}[\mathbf{s}]| \geq \epsilon \mathbb{E}[\mathbf{s}]] \leq \frac{\text{Var}[\mathbf{s}]}{(\epsilon \mathbb{E}[\mathbf{s}])^2} = \frac{1}{\epsilon^2}.$$

Bound is vacuous for any  $\epsilon < 1$ . **How can we improve accuracy?**

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Leverage the law of large numbers: improve accuracy via repeated independent trials.

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### Hashing for Distinct Elements (Improved):

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$$\begin{aligned} \left[ \begin{aligned} s &\leq (1+\epsilon) \mathbb{E}[s] \\ s &\leq \frac{1+\epsilon}{d+1} \end{aligned} \right] \end{aligned}$$

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$$\hat{d} \geq$$

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Chebyshev Inequality:  $\epsilon = .01$   $\delta = .01$

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↳

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**The median trick:** Run  $t = O(\log 1/\delta)$  trials each with failure probability  $\delta' = 1/5$  - each using  $k = \frac{1}{\delta' \epsilon^2} = \frac{5}{\epsilon^2}$  hash functions.

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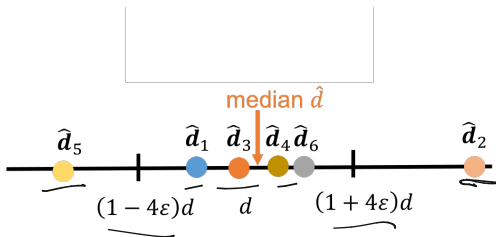
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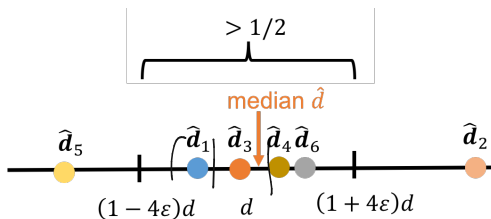
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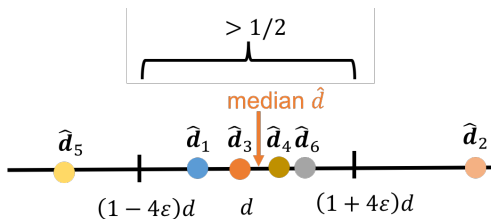
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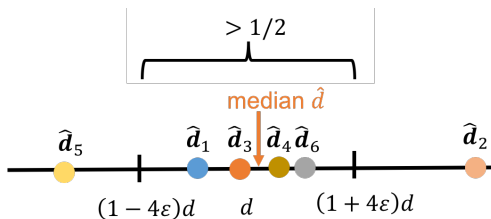
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- If  $> 2/3$  of trials fall in  $[(1-4\epsilon)d, (1+4\epsilon)d]$ , then the median will.
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- $\hat{\mathbf{d}}_1, \dots, \hat{\mathbf{d}}_t$  are the outcomes of the  $t$  trials, each falling in  $[(1 - 4\epsilon)d, (1 + 4\epsilon)d]$  with probability at least  $4/5$ .
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$\leq \frac{4}{6} + \frac{1}{3} = \frac{2}{3} + \frac{1}{3}$

## THE MEDIAN TRICK

- $\hat{\mathbf{d}}_1, \dots, \hat{\mathbf{d}}_t$  are the outcomes of the  $t$  trials, each falling in  $[(1 - 4\epsilon)d, (1 + 4\epsilon)d]$  with probability at least  $4/5$ .
- $\hat{\mathbf{d}} = \text{median}(\hat{\mathbf{d}}_1, \dots, \hat{\mathbf{d}}_t)$ .

What is the probability that the median  $\hat{\mathbf{d}}$  falls in  $[(1 - 4\epsilon)d, (1 + 4\epsilon)d]$ ?

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- Setting  $t = \underline{O(\log(1/\delta))}$  gives failure probability  $\underline{e^{-\log(1/\delta)}} = \delta$ .

**Upshot:** The median of  $t = O(\log(1/\delta))$  independent runs of the hashing algorithm for distinct elements returns  $\hat{d} \in [(1 - 4\epsilon)d, (1 + 4\epsilon)d]$  with probability at least  $1 - \delta$ .

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**A note on the median:** The median is often used as a robust alternative to the mean, when there are outliers (e.g., heavy tailed distributions, corrupted data).