# COMPSCI 514: ALGORITHMS FOR DATA SCIENCE

Cameron Musco University of Massachusetts Amherst. Fall 2019. Lecture 24 (Final Lecture!)

- Problem Set 4 due Sunday 12/15 at 8pm.
- Exam prep materials (including practice problems) posted under the 'Schedule' tab of the course page.
- I will hold office hours on both Tuesday and Wednesday next week from **10am to 12pm** to prep for final.
- SRTI survey is open until 12/22. Your feedback this semester has been very helpful to me, so please fill out the survey!
- https://owl.umass.edu/partners/ courseEvalSurvey/uma/

## Last Class:

- Compressed sensing and sparse recovery.
- Applications to sparse regression, frequent elements problem, sparse Fourier transform.

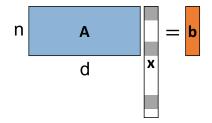
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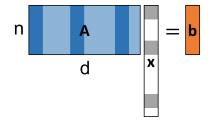
# This Class:

- Finish up sparse recovery.
- Solution via basis pursuit. Idea of convex relaxation.
- Wrap up.

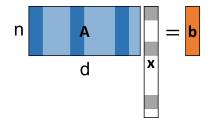
**Problem Set Up:** Given data matrix  $\mathbf{A} \in \mathbb{R}^{n \times d}$  with n < d and measurements  $\mathbf{b} = \mathbf{A}\mathbf{x}$ . Recover  $\mathbf{x}$  under the assumption that it is *k*-sparse, i.e., has at most  $k \ll d$  nonzero entries.



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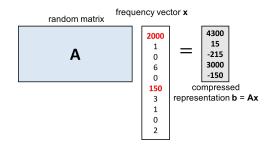


**Last Time:** Proved this is possible (i.e., the solution **x** is unique) when **A** has Kruskal rank  $\geq 2k$ .

$$\label{eq:constraint} \begin{split} \mathbf{x} &= \underset{\mathbf{z} \in \mathbb{R}^d: \mathbf{A} \mathbf{z} = \mathbf{b}}{\text{argmin}} \, \| \mathbf{z} \|_0, \end{split}$$

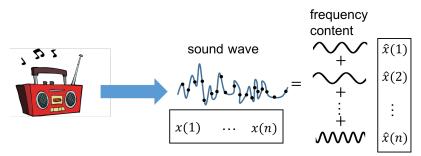
Kruskal rank condition can be satisfied with *n* as small as 2*k* 

## FREQUENT ITEMS COUNTING

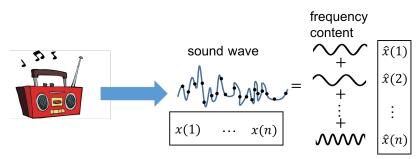


- A frequency vector with *k* out of *n* very frequent items is approximately *k*-sparse.
- Can be approximately recovered from its multiplication with a random matrix **A** with just  $m = \tilde{O}(k)$  rows.
- $\mathbf{b} = \mathbf{A}\mathbf{x}$  can be maintained in a stream using just O(m) space.
- Exactly the set up of Count-min sketch in linear algebraic notation.

**Discrete Fourier Transform:** For a discrete signal (aka a vector)  $\mathbf{x} \in \mathbb{R}^n$ , its discrete Fourier transform is denoted  $\hat{\mathbf{x}} \in \mathbb{C}^n$  and given by  $\hat{\mathbf{x}} = \mathbf{F}\mathbf{x}$ , where  $\mathbf{F} \in \mathbb{C}^{n \times n}$  is the discrete Fourier transform matrix.



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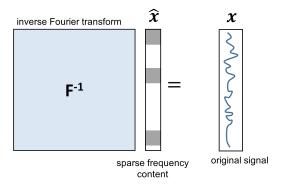


For many natural signals  $\hat{\mathbf{x}}$  is approximately sparse: a few dominant frequencies in a recording, superposition of a few radio transmitters sending at different frequencies, etc.

When the Fourier transform  $\widehat{x}$  is sparse, can recover it from few measurements of x using sparse recovery.

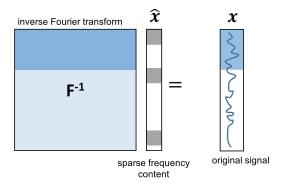
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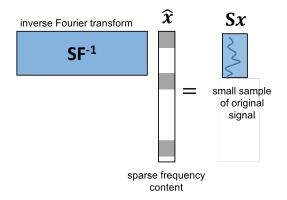
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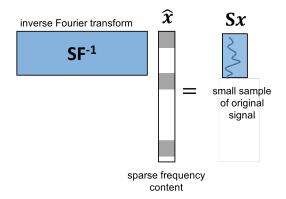
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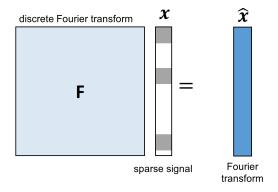
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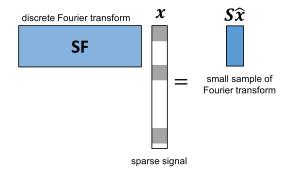
Translates to big savings in acquisition costs and number of sensors. 6

Other Direction: When x itself is sparse, can recover it from few measurements of the Fourier transform  $\hat{x}$  using sparse recovery.

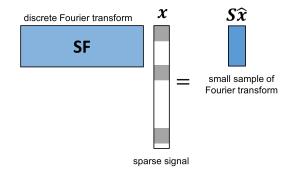
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How do we access/measure entries of  $S\hat{x}$ ?

### GEOSENSING

- In seismology, **x** is an image of the earth's crust, and often sparse (e.g., a few locations of oil deposits).
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• Achieved by inducing vibrations of different frequencies with a vibroseis truck, air guns, explosions, etc and recording the response (more complicated in reality...)

# Back to Algorithms

 $\mathbf{x} = \mathop{\text{arg\,min}}_{\mathbf{z} \in \mathbb{R}^d: A\mathbf{z} = \mathbf{b}} \|\mathbf{z}\|_0$ 

Works if **A** has Kruskal rank  $\geq 2k$ , but very hard computationally.

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- Projected (sub)gradient descent convex objective function and convex constraint set.
- An instance of linear programming, so typically faster to solve with a linear programming algorithm (e.g., simplex, interior point).

Why should we hope that the basis pursuit solution returns the unique *k*-sparse **x** with Ax = b? The minimizer  $z^*$  will have small  $\ell_1$  norm but why would it even be sparse?

 $\begin{array}{ll} \underset{z \in \mathbb{R}^d: Az = b}{\text{arg min }} \| z \|_1 \quad \text{vs.} \quad \underset{z \in \mathbb{R}^d: Az = b}{\text{arg min }} \| z \|_0 \end{array}$ 

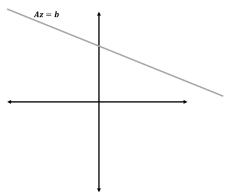
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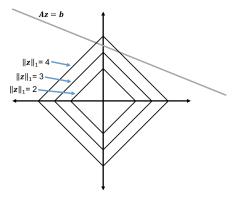
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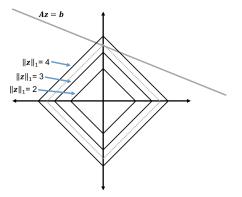
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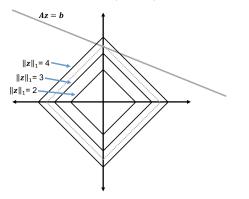
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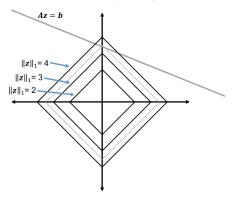


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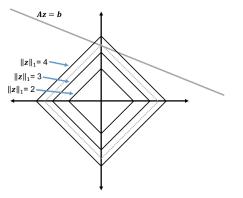
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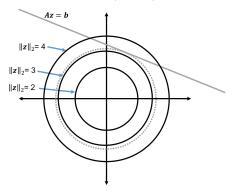
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Can prove that basis pursuit outputs the exact *k*-sparse solution **x** with  $A\mathbf{x} = \mathbf{b}$  (i.e,  $\arg \min_{z \in \mathbb{R}^d: Az = \mathbf{b}} \|z\|_1 = \arg \min_{z \in \mathbb{R}^d: Az = \mathbf{b}} \|z\|_0$ )

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**Theorem:** If **A** is  $(3k, \epsilon)$ -RIP for small enough constant  $\epsilon$ , then  $\mathbf{z}^* = \arg\min_{\mathbf{z} \in \mathbb{R}^d: A\mathbf{z} = \mathbf{b}} \|\mathbf{z}\|_1$  is equal to the unique *k*-sparse **x** with  $A\mathbf{x} = \mathbf{b}$  (i.e., basis pursuit solves the sparse recovery problem).

## Wrap Up

Thanks for a great semester!

 Focus on problems that are easy on small datasets but hard at massive scale – set size estimation, load balancing, distinct elements counting (MinHash), checking set membership (Bloomfilters), frequent items counting (Count-min sketch), near neighbor search (locality sensitive hashing).

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- Just the tip of the iceberg on randomized streaming/sketching/hashing algorithms.
- In the process covered probability/statistics tools that are very useful beyond algorithm design: concentration inequalities, higher moment bounds, law of large numbers, central limit theorem, linearity of expectation and variance, union bound, median as a robust estimator.

• Started with randomized dimensionality reduction and the JL lemma: compression from *any* d-dimensions to  $O(\log n/\epsilon^2)$  dimensions while preserving pairwise distances.

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- Low-rank structure in graphs nonlinear dimensionality reduction and spectral clustering for community detection, stochastic block model, matrix concentration.
- In the process covered linear algebraic tools that are very broadly useful in ML and data science: eigendecomposition, singular value decomposition, projection, norm transformations.

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- Lots that we didn't cover: accelerated methods, adaptive methods, second order methods (quasi-Newton methods), practical considerations. Hopefully gave mathematical tools to understand these methods.

- The weirdness of high-dimensional space and geometry. Connections to randomized methods, dimensionality reduction. Always useful to keep in mind.
- Compressed sensing/sparse recovery a very broad and widely-used framework for working with high-dimensional data. Connection to streaming algorithms (frequent items counting) and convex optimization.

# Thanks!