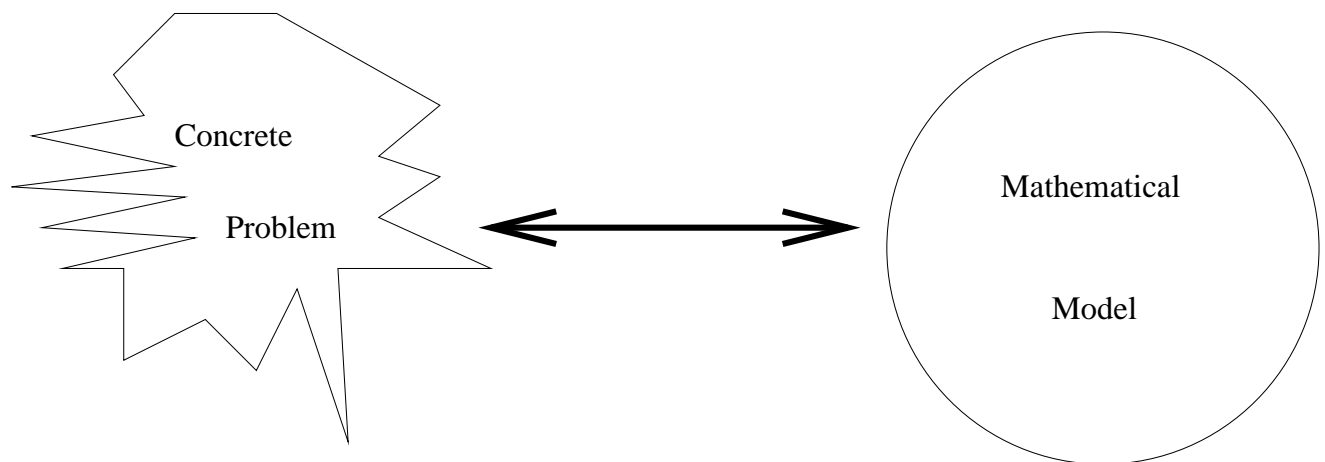


We've studied the main models and concepts of the theory of computation:

- **Computability:** what can be computed in principle
- **Logic:** how can we express our requirements
- **Complexity:** what can be computed in practice



Formal Models of Computation:

- $\text{FA} \cong \text{Regular Expression}$
- $\text{PDA} \cong \text{CFG}$
- $\text{TM} \cong \text{Recursive Function} \cong \text{Boolean Circuits} \dots$
- logical formula

Kleene's Theorem: Let $A \subseteq \Sigma^*$ be any language. Then the following are equivalent:

1. $A = \mathcal{L}(D)$, for some DFA D .
2. $A = \mathcal{L}(N)$, for some NFA N wo ϵ transitions
3. $A = \mathcal{L}(N)$, for some NFA N .
4. $A = \mathcal{L}(e)$, for some regular expression e .

Myhill-Nerode Theorem: The language A is regular iff \sim_A has a finite number of equivalence classes. Furthermore, this number of equivalence classes is equal to the number of states in the minimum-state DFA that accepts A .

Pumping Lemma for Regular Sets: Let $D = (Q, \Sigma, \delta, q_0, F)$ be a DFA. Let $n = |Q|$. Let $w \in \mathcal{L}(D)$ s.t. $|w| \geq n$. Then $\exists x, y, z \in \Sigma^*$ s.t. the following all hold:

- $xyz = w$
- $|xy| \leq n$
- $|y| > 0$, and
- $(\forall k \geq 0)xy^kz \in \mathcal{L}(D)$

Closure Theorem for Context Free Languages: Let $A, B \subseteq \Sigma^*$ be context-free languages, let $R \subseteq \Sigma^*$ be a regular language, and let $h : \Sigma^* \rightarrow \Gamma^*$ and $g : \Gamma^* \rightarrow \Sigma^*$ be homomorphisms. Then the following languages are context-free:

1. $A \cup B$
2. AB
3. $A \cap R$
4. $h(A)$
5. $g^{-1}(A)$

CFL Pumping Lemma: Let A be a CFL. Then there is a constant n , depending only on A such that if $z \in A$ and $|z| \geq n$, then there exist strings u, v, w, x, y such that $z = uvwxy$, and,

- $|vx| \geq 1$,
- $|vwx| \leq n$, and
- for all $k \in \mathbf{N}$, $uv^kwx^ky \in A$

A (partial) function is *recursive* iff it is computed by some TM M .

Let $S \subseteq \{0, 1\}^*$ or $S \subseteq \mathbf{N}$.

S is a *recursive set* iff the function χ_S is a (total) recursive function,

$$\chi_S(x) = \begin{cases} 1 & \text{if } x \in S \\ 0 & \text{otherwise} \end{cases}$$

S is a *recursively enumerable set* (S is r.e.) iff the function p_S is a (partial) recursive function,

$$p_S(x) = \begin{cases} 1 & \text{if } x \in S \\ \nearrow & \text{otherwise} \end{cases}$$

Th: **Recursive = r.e. \cap co-r.e.**

Define the *primitive recursive functions* to be the smallest class of functions that

- contains the Initial functions: ζ , σ , and π_i^n , $n = 1, 2, \dots$, $1 \leq i \leq n$, and
- is closed under **Composition**, and
- is closed under **Primitive Recursion**

Define the *Gödel recursive functions* to be the smallest class of functions that

- contains the Initial functions, and
- is closed under **Composition**, and
- is closed under **Primitive Recursion**, and
- is closed under **Unbounded Minimalization**

Th: [Kleene] $\text{COMP}(n, x, c, y)$ is a primitive recursive predicate.

Theorem: A (partial) function is recursive iff it is Gödel recursive.

Cantor's Theorem: $\wp(\mathbf{N})$ is not countable!

Proof: Suppose it were. Let $f : \mathbf{N} \xrightarrow[onto]{1:1} \wp(\mathbf{N})$. Define the diagonal set,

$$D = \{n \mid n \notin f(n)\}$$

Thus $D = f(k)$ for some $k \in \mathbf{N}$.

$$k \in D \Leftrightarrow k \notin f(k) \Leftrightarrow k \notin D$$

$\Rightarrow \Leftarrow$ Therefore, $\wp(\mathbf{N})$ is not countable!



n	0	1	2	3	4	5	6	7	8	\dots	$f(n)$
0	0	0	0	0	0	0	0	0	0	\dots	$f(0)$
1	1	1	1	1	1	1	1	1	1	\dots	$f(1)$
2	1	0	1	0	1	0	1	0	1	\dots	$f(2)$
3	0	1	0	1	0	1	0	1	0	\dots	$f(3)$
4	1	0	0	0	0	0	0	0	0	\dots	$f(4)$
5	0	1	1	0	1	0	0	0	1	\dots	$f(5)$
6	1	0	0	1	0	0	1	0	0	\dots	$f(6)$
7	1	1	0	0	0	0	0	0	0	\dots	$f(7)$
8	0	1	0	0	0	0	0	0	0	\dots	$f(8)$
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\dots	\vdots
	1	0	0	0	1	1	0	1	1	\dots	D

$$K = \{n \mid M_n(n) = 1\}$$

Theorem: \overline{K} is not r.e.

Hierarchy Theorems: Let $f(n)$ be a well behaved function, and \mathcal{C} one of DSPACE, NSPACE, DTIME, NTIME.

If $g(n)$ is sufficiently smaller than $f(n)$ then $\mathcal{C}[g(n)]$ is strictly contained in $\mathcal{C}[f(n)]$.

“ $g(n)$ sufficiently smaller than $f(n)$ ” means

$$\lim_{n \rightarrow \infty} \frac{g(n)}{f(n)} = 0$$

$$\lim_{n \rightarrow \infty} \frac{g(n) \log(g(n))}{f(n)} = 0$$

$\mathcal{C} = \mathbf{DSPACE}, \mathbf{NSPACE}, \mathbf{NTIME}$

$\mathcal{C} = \mathbf{DTIME}$

Hence $\mathbf{P} \neq \mathbf{EXPTIME}$, $\mathbf{L} \neq \mathbf{PSPACE}$.

But these are the *only* separations of classes we know! (Except at the p.r. and above level, and for **REG** and **CFL**).

Th: The busy beaver function is eventually larger than any total, recursive function.

Th: Let $S \subseteq \mathbf{N}$. T.F.A.E.

1. S is the domain of a partial, recursive function.
2. $S = \emptyset$ or S is the range of a total, recursive function.
3. S is the range of a partial, recursive function.
4. $S = W_n$, some $n = 0, 1, 2, \dots$ where

$$W_n = \{m \mid M_n(m) = 1\}$$

Definitions of **Formula**, **Structure**, and **Truth**

Axioms and Proof Rules

Modus Ponens (M.P.): From φ , $\varphi \rightarrow \psi$, conclude ψ .

Proposition: Modus Ponens preserves validity.

Axioms: all generalizations of the following

0	Tautologies on at most three boolean variables
1a	$t = t$
1b	$(t_1 = t'_1 \wedge \cdots \wedge t_k = t'_k) \rightarrow f(t_1, \dots, t_k) = f(t'_1, \dots, t'_k)$
1c	$(t_1 = t'_1 \wedge \cdots \wedge t_k = t'_k) \rightarrow R(t_1, \dots, t_k) \rightarrow R(t'_1, \dots, t'_k)$
2	$(\forall x)(\varphi) \rightarrow \varphi[x \leftarrow t]$
3	$\varphi \rightarrow (\forall x)(\varphi)$, x not free in φ
4	$(\forall x)(\varphi \rightarrow \psi) \rightarrow ((\forall x)(\varphi) \rightarrow (\forall x)(\psi))$

Proposition: Every instance of every axiom is valid.

$$\text{FO-THEOREMS} = \{\varphi \mid \vdash \varphi\}$$

Soundness Theorem: If $\vdash \varphi$ then $\models \varphi$.

$$\text{FO-THEOREMS} \subseteq \text{FO-VALID}$$

Completeness Theorem: If $\models \varphi$ then $\vdash \varphi$.

$$\text{FO-THEOREMS} \supseteq \text{FO-VALID}$$

Corollary:

$$\vdash = \models; \quad \text{FO-THEOREMS} = \text{FO-VALID}$$

Compactness Th: If every finite subset of Γ has a model, then Γ has a model.

Gödel's Incompleteness Theorem:

Theory(\mathbf{N}) is not r.e. and thus not axiomatizable.

Th: For $t(n) \geq n$, $s(n) \geq \log n$,

$$\mathbf{DTIME}[t(n)] \subseteq \mathbf{NTIME}[t(n)] \subseteq \mathbf{DSPACE}[t(n)]$$

$$\mathbf{DSPACE}[s(n)] \subseteq \mathbf{DTIME}[2^{O(s(n))}]$$

Savitch's Theorem:

For $s(n) \geq \log n$,

$$\mathbf{NSPACE}[s(n)] \subseteq \mathbf{ATIME}(s(n))^2 \subseteq \mathbf{DSPACE}[(s(n))^2]$$

Immerman-Szelepcsényi Theorem:

For $s(n) \geq \log n$,

$$\mathbf{NSPACE}[s(n)] = \mathbf{co-NSPACE}[s(n)]$$

Theorem: Let \mathcal{C} be one of the following complexity classes: L, NL, P, NP, co-NP, PSPACE, EXPTIME, Primitive-Recursive, RECURSIVE, r.e., co-r.e.

Suppose $A \leq B$.

If $B \in \mathcal{C}$ Then $A \in \mathcal{C}$

All these complexity classes are **closed under reductions**.

Lower Bounds: If A is hard then B is hard.

Upper Bounds: If B is easy then A is easy.

Complete for NL: REACH, EMPTY-DFA, EMPTY-NFA, 2-SAT

Complete for P: CVP, MCVP, EMPTY-CFL, Horn-SAT, REACH_a

Complete for NP: TSP, SAT, 3-SAT, 3-COLOR, CLIQUE, Subset Sum, Knapsack

Complete for PSPACE: QSAT, GEOGRAPHY, SUCCINT-REACH, REG-EXP- Σ^*

Complete for r.e.: K , HALT, $A_{0,17}$, FO-VALID

Complete for co-r.e.: \overline{K} , Σ^* CFL, EMPTY, FO-SAT

Theorem:

$$\mathbf{r.e.} = \mathbf{FO}\exists(\mathbf{N})$$

$$\mathbf{co-r.e.} = \mathbf{FO}\forall(\mathbf{N})$$

$$\mathbf{PH} = \mathbf{SO}$$

$$\mathbf{NP} = \mathbf{SO}\exists$$

$$\mathbf{P} = \mathbf{SO}\exists\text{-Horn}$$

$$\mathbf{AC}^0 = \mathbf{CRAM}[1] = \mathbf{LH} = \mathbf{FO}$$

One can understand the complexity of a problem as the richness of a logical language that is needed to describe the problem.

Theorem: For $s(n) \geq \log n$, and for $t(n) \geq n$,

$$\bigcup_{k=1}^{\infty} \mathbf{ATIME}[(t(n))^k] = \bigcup_{k=1}^{\infty} \mathbf{DSpace}[(t(n))^k]$$

$$\mathbf{ASpace}[s(n)] = \bigcup_{k=1}^{\infty} \mathbf{DTIME}[k^{s(n)}]$$

Corollary: In particular,

$$\mathbf{ASpace}[\log n] = \mathbf{P}$$

$$\mathbf{ATIME}[n^{O(1)}] = \mathbf{PSpace}$$

$$\mathbf{ASpace}[n^{O(1)}] = \mathbf{EXPTIME}$$

depth = parallel time

width = hardware

number of gates = computational work = sequential time

Theorem: For all i , $\text{CRAM}[(\log n)^i] = \text{AC}^i$

$$\text{AC}^0 \subseteq \text{ThC}^0 \subseteq \text{NC}^1 \subseteq \text{L} \subseteq \text{NL} \subseteq \text{sAC}^1 \subseteq$$

$$\text{AC}^1 \subseteq \text{ThC}^1 \subseteq \text{NC}^2 \subseteq \text{sAC}^2 \subseteq$$

$$\vdots \subseteq \vdots \subseteq \vdots \subseteq \vdots \subseteq$$

$$\text{AC}^i \subseteq \text{ThC}^i \subseteq \text{NC}^{i+1} \subseteq \text{sAC}^{i+1} \subseteq$$

$$\vdots \subseteq \vdots \subseteq \vdots \subseteq \vdots \subseteq$$

$$\text{NC} = \text{NC} = \text{NC} = \text{NC} =$$

$$\text{NC} \subseteq \text{P} \subseteq \text{NP}$$

Alternation/Circuit Theorem:

Log-space ATM's with:

- $O(\log^i n)$ time give \mathbf{NC}^i ($i \geq 1$)
- $O(\log^i n)$ alternations give \mathbf{AC}^i ($i \geq 1$)

Alternating TM's are one good way to design uniform families of circuits. We used this method to prove $\mathbf{CFL} \subseteq \mathbf{sAC}^1$.

First-order logic gives us another way to design uniform families of circuits. We've used this to construct \mathbf{AC}^0 circuits by showing a problem to be in FO.

We need uniformity definitions on our circuit classes to relate them to ordinary classes. For example, poly-size circuit families compute languages in \mathbf{P} only if they are at least \mathbf{P} -uniform.

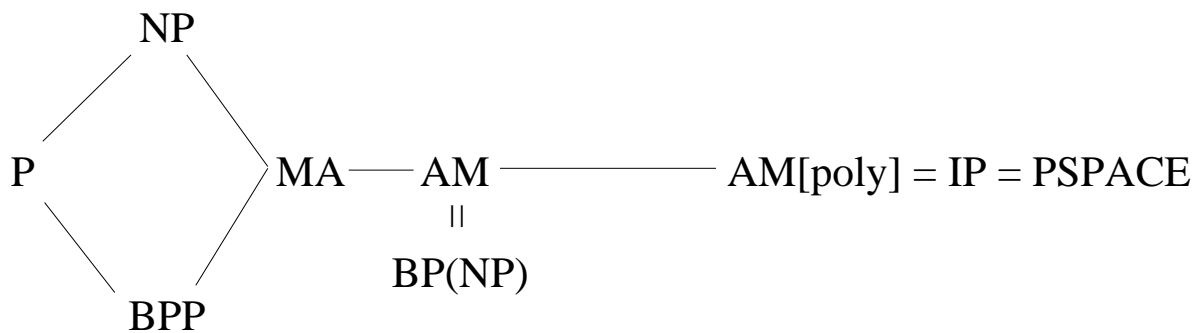
Theorem: PRIME and Factoring are in $\mathbf{NP} \cap \mathbf{co-NP}$.
(PRIME is now in \mathbf{P} as well.)

Theorem: [Solovay-Strassen, Miller]

$\mathbf{PRIME} \in \mathbf{BPP}$

Fact: $\mathbf{REACH}_u \in \mathbf{BPL}$

Interactive Proofs



Fact: $\mathbf{PCP}[\log n, 1] = \mathbf{NP}$

A is an *optimization problem* iff

For each instance x , $F(x)$ is the set of *feasible solutions*

Each $s \in F(x)$ has a cost $c(s) \in \mathbf{Z}^+$

For minimization problems,

$$\text{OPT}(x) = \min_{s \in F(x)} c(s)$$

For maximization problems,

$$\text{OPT}(x) = \max_{s \in F(x)} c(s)$$

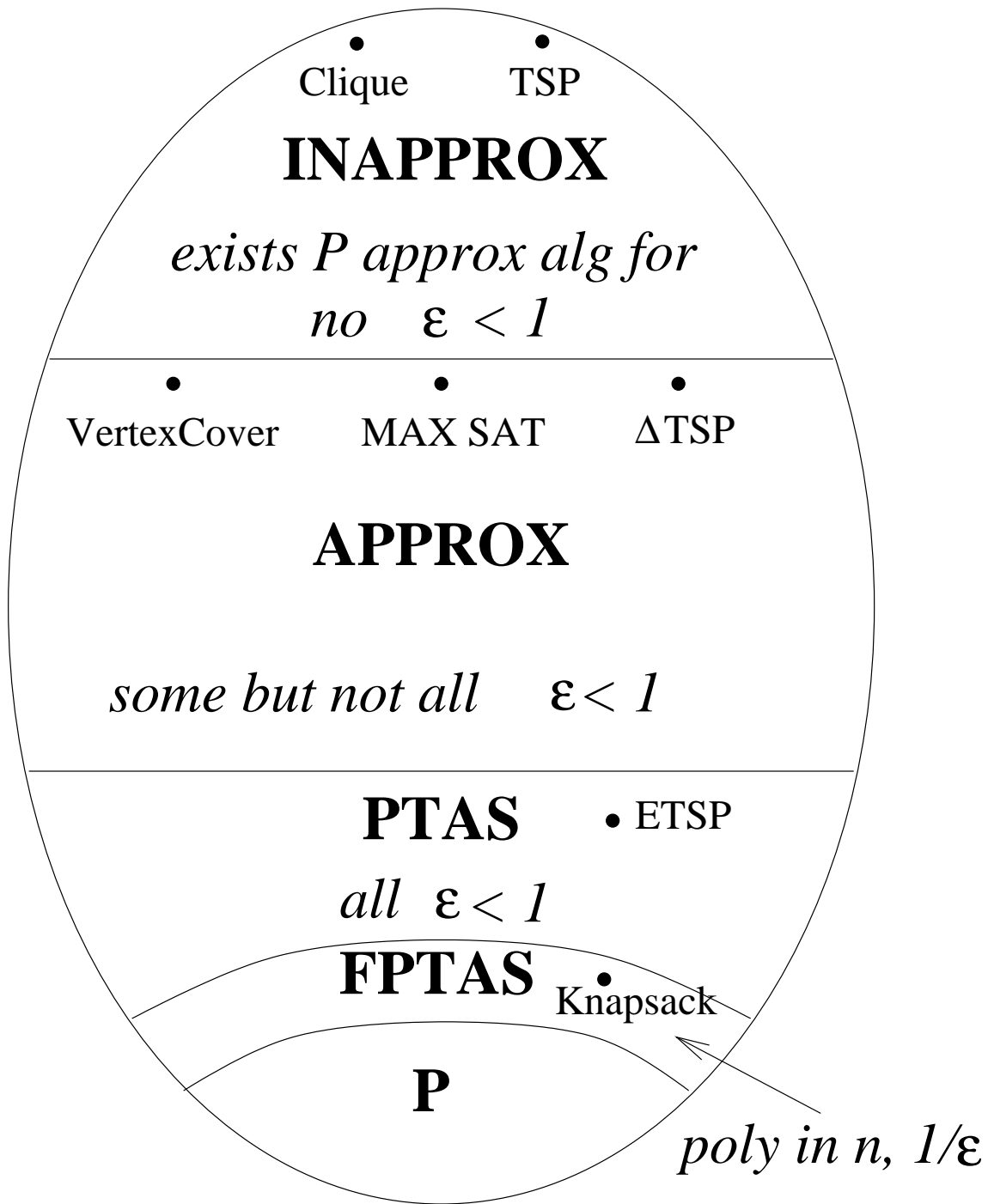
Let M be an algorithm s.t. on any instance x ,

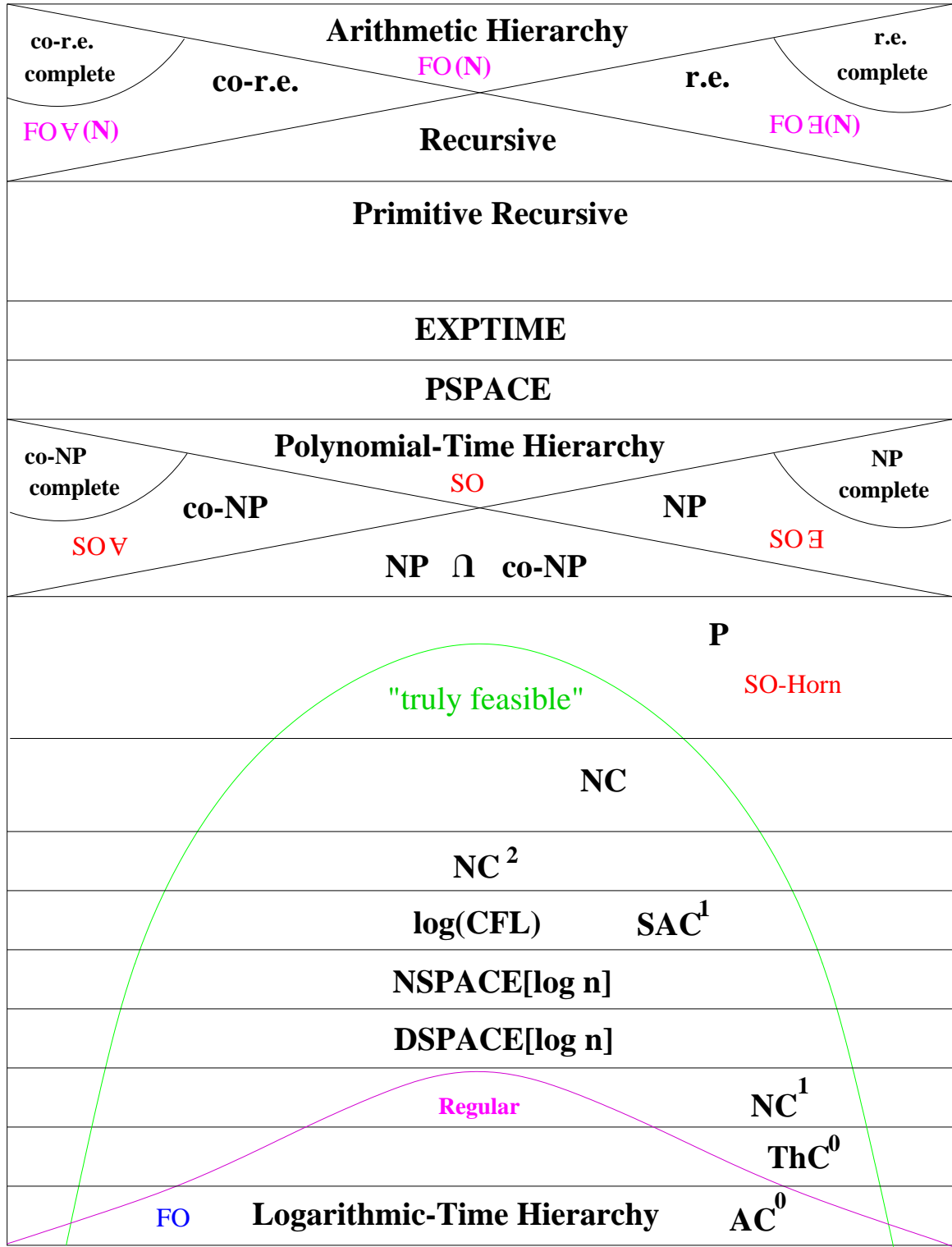
$$M(x) \in F(x)$$

M is an ϵ -*approximation algorithm* iff for all x ,

$$\frac{|c(M(x)) - \text{OPT}(x)|}{\max(\text{OPT}(x), c(M(x)))} \leq \epsilon$$







Why are the following so hard to prove?

- **$P \neq NP$**
- **$P \neq PSPACE$**
- **$ThC^0 \neq NP$**
- **$BPP = P$**

We do know a lot about computation. Reductions and complete problems are a key tool. So is the equivalence of apparently different models and methods. Yet much remains unknown.