CMPSCI 601:

Recall From Last Time

Lecture 21

Clique **TSP**

INAPPROX

exists P approx alg for no $\varepsilon < 1$

VertexCover MAX SAT

 ΔTSP

APPROX

some but not all $\varepsilon < 1$

PTAS • ETSP

all $\varepsilon < 1$

FPTAS Knapsack

P

poly in n, $1/\epsilon$

CMPSCI 601: Alternation Lecture 21

The concept of a nondeterministic acceptor of a boolean query has a long and rich history, going back to various kinds of nondeterministic automata.

It is important to remember that these are fictitious machines: we suspect that they cannot be built.

For $A \subseteq \mathrm{STRUC}_{\mathrm{fin}}[\tau]$ a boolean query, define its complement $\overline{A} = \mathrm{STRUC}_{\mathrm{fin}}[\tau] - A$. Given a complexity class, \mathcal{C} , define complementary class,

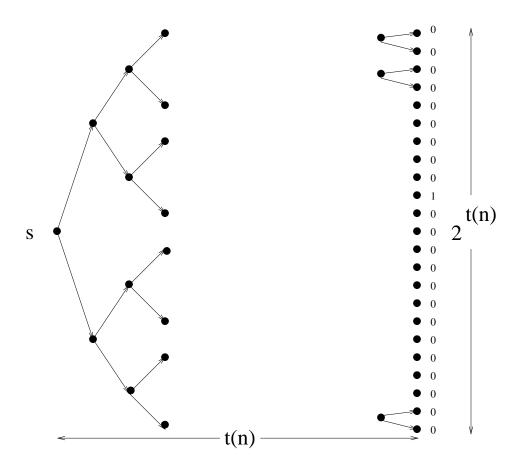
$$\operatorname{co-}\mathcal{C} = \{\overline{A} \mid A \in \mathcal{C}\}\$$

Example: SAT \in NP; $\overline{SAT} = UNSAT \in co-NP$

Open question: NP ? = co-NP

If one could really build an **NP** machine, then one could with a single gate to invert its answer also build a co-**NP** machine. From a very practical point of view, the complexity of a problem A and its complement, \overline{A} are identical.





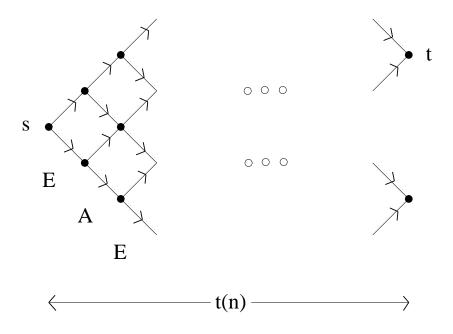
 $Value(ID) \equiv Value(LeftChild(ID)) \lor Value(Right(Child(ID)))$

weak communication pattern; wasteful use of all these processors

Definition 21.1 Define an *alternating Turing machine* to be a Turing machine whose states are divided into two groups: the *existential* states and the *universal* states.

Recall that an *instantaneous description* (ID) consists of the machine's state, work-tape contents, and head positions. The notion of when such a machine accepts an input is defined by induction: The alternating Turing machine in ID_0 *accepts* iff

- 1. ID_0 is in a final accepting state, or
- 2. ID_0 is in an existential state and there exists a next ID that accepts, or
- 3. ID_0 is in a universal state, there is at least one next ID, and all next ID's accept.



What does it mean for a string to be in the language of an alternating TM? We sometimes misleadingly say "the ATM accepts x" just as we might say "the NDTM accepts x". But this isn't really sensible, because we should not talk about what an NDTM or ATM will do, only what it might do.

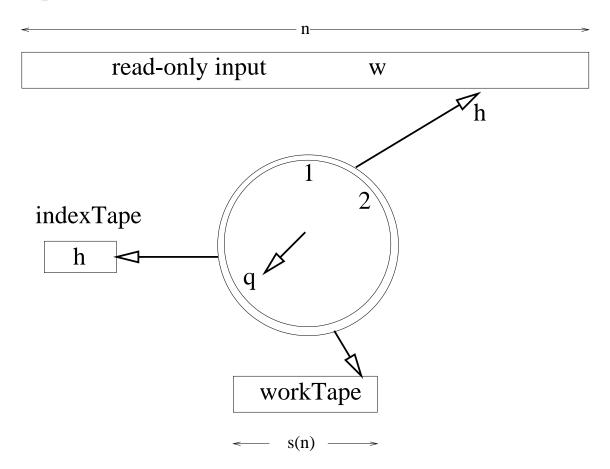
Language of an NDTM: $x \in \mathcal{L}(N)$ iff N might accept x.

Equivalently: $x \in \mathcal{L}(N)$ if a smart player, who controls N's choices and wants N to accept, can make N accept.

Game Semantics of an ATM: There are two players, White who controls M in the existential states and wants M to accept, and Black who controls M in the universal states and wants M to reject. $x \in \mathcal{L}(M)$ iff White can force M to accept x given optimal play by each player.

This is *equivalent* to the definition of "acceptance" given on the last slide, but I find it much easier to understand.

From now on assume that our Turing machines have a $random\ access$ read-only input. There is an $index\ tape$ which can be written on and read like other tapes. Whenever the value h, written in binary, appears on the index tape, the read head will automatically scan bit h bit of the input.



Define the complexity classes $\mathbf{ASPACE}[s(n)]$, and $\mathbf{ATIME}[t(n)]$ to be the set of boolean queries accepted by alternating Turing machines using a maximum of O(s(n)) tape cells, respectively a maximum of O(t(n)) time steps in any computation path on an input of length n.

Theorem 21.2 For
$$s(n) \ge \log n$$
, and for $t(n) \ge n$,
$$\bigcup_{k=1}^{\infty} \mathbf{ATIME}[(t(n))^k] = \bigcup_{k=1}^{\infty} \mathbf{DSPACE}[(t(n))^k]$$
$$\mathbf{ASPACE}[s(n)] = \bigcup_{k=1}^{\infty} \mathbf{DTIME}[k^{s(n)}]$$

Corollary 21.3 In particular,

$$\begin{aligned} \mathbf{ASPACE}[\log n] &= \mathbf{P} \\ \mathbf{ATIME}[n^{O(1)}] &= \mathbf{PSPACE}. \end{aligned}$$

The Alternation Theorem has four parts.

We must simulate:

- 1. A time-bounded DTM with a space-bounded ATM, using *the circuit game*,
- 2. A space-bounded DTM with a time-bounded ATM, using *the Savitch game*,
- 3. A space-bounded ATM with a time-bounded DTM, using the *marking algorithm*, and
- 4. A time-bounded ATM with a space-bounded DTM, using *exhaustive search of the game tree*.

First, though, let's see some examples of alternating machines. I'll include both "classical" and game-semantics descriptions of each machine.

Define the monotone, circuit value problem (MCVP) to be the subset of CVP in which no negation gates occur. It turns out that MCVP is still P-complete.

Proposition 21.4 MCVP *is recognizable in* **ASPACE**[$\log n$].

Proof: Let G be a monotone boolean circuit. For $a \in V^G$, define "EVAL(a)",

- 1. if (InputOn(a)) then accept
- 2. **if** (InputOff(a)) **then reject**
- 3. if $(G_{\wedge}(a))$ then universally choose child b of a
- 4. if $(G_{\vee}(a))$ then existentially choose child b of a
- 5. Return(EVAL(b))

M simply calls EVAL(r). EVAL(a) returns "accept" iff gate a evaluates to one.

Space used for naming vertices a, b: $O(\log n)$.

Game Semantics for this Proof:

In the *Circuit Game*, we start with a marker at the output gate of a monotone Boolean circuit G. On each move, the marker moves from the current gate to one of its children (one of its inputs). For AND gates Black chooses which child to move to, and for OR gates White chooses. When we reach an input gate marked with a literal, White wins the game iff this literal evaluates to true.

White wants to stay on gates that evaluate to true, Black on gates that evaluate to false. Whoever is happy with the output gate can always move the marker to stay happy, until an input is reached.

Definition 21.5 The *quantified satisfiability problem* (QSAT) is the set of true formulas of the following form:

$$\Psi = (Q_1 x_1)(Q_2 x_2) \cdots (Q_r x_r) \varphi$$



For any boolean formula φ on variables \overline{x} ,

$$\varphi \in SAT \quad \Leftrightarrow (\exists \overline{x})\varphi \in QSAT$$

$$\varphi \not\in SAT \quad \Leftrightarrow (\forall \overline{x}) \neg \varphi \in QSAT$$

Thus QSAT logically contains SAT and \overline{SAT} .

Proposition 21.6 QSAT is recognizable in **ATIME**[n].

Proof: Construct an alternating machine A as follows. To evaluate the sentence,

$$\Phi \equiv (\exists x_1)(\forall x_2)\cdots(Q_rx_r)\alpha(\overline{x}),$$

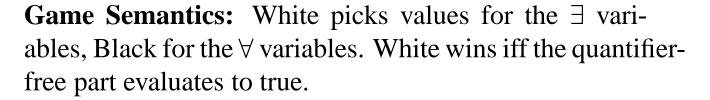
in an existential state, A writes down a boolean value for x_1 , in a universal state it writes a bit for x_2 , and so on.

Next A must evaluate the quantifier-free boolean formula α on these chosen values. For each " \wedge " in α , A universally chooses which side to evaluate; for each " \vee ", A existentially chooses.

Thus A only has to read one of the chosen bits, x_i , and accept iff it is true and occurs positively, or false and occurs negatively.

A runs in linear time.

A accepts Φ iff Φ is true.



Theorem 21.7 For any $s(n) \ge \log n$,

$$\mathbf{NSPACE}[s(n)] \subseteq \mathbf{ATIME}[s(n)^2] \subseteq \mathbf{DSPACE}[s(n)^2]$$

Proof: NSPACE $[s(n)] \subseteq ATIME[s(n)^2]$:

Let N be an **NSPACE**[s(n)] Turing machine.

Let w be an input to N, n = |w|.

$$w \in \mathcal{L}(N) \Leftrightarrow \mathsf{CompGraph}(N, w) \in \mathsf{REACH}$$

P(d, x, y) accepts iff there is a path in CompGraph(N, w) of length at most 2^d from x to y.

$$P(d, x, y) \equiv (\exists z)(P(d-1, x, z) \land P(d-1, z, y))$$

- 1. Existentially: choose middle ID z.
- 2. Universally: (x, y) := (x, z) AND (z, y)
- 3. Return(P(d-1, x, y))

$$T(d) = O(s(n)) + T(d-1) = O(d \cdot s(n))$$
 $d = O(s(n))$
 $T(d) = O((s(n))^2)$

Game Semantics for this version of Savitch's Theorem:

White originally *claims* that the path from s to t, of length at most $2^{s(n)}$, exists in CompGraph(N, w). White *advances* this claim by naming the alleged middle vertex of the alleged path. Black picks either the *first half* or the *second half* of the path to *challenge*. The path whose existence is disputed is then half the length. They continue, halving the length of the disputed path each time, until they dispute the existence of an *edge*. At this point the player with the correct claim about this edge wins.

If White's path actually exists, White has a winning strategy that consists of always telling the truth. If White is wrong, however, either the first or second half of the alleged path must fail to exist, and Black has a winning move.

$ATIME[t(n)] \subseteq DSPACE[t(n)]$:

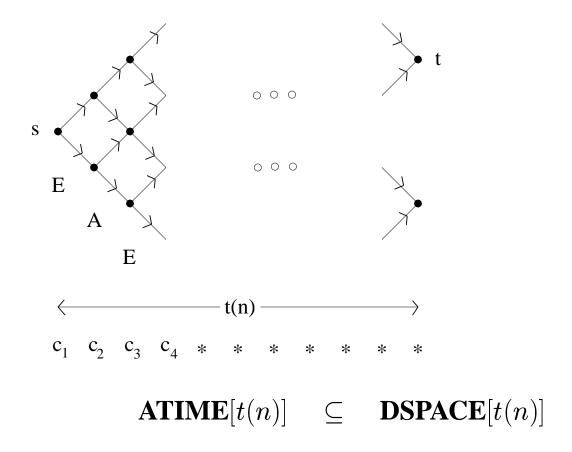
Let A be an $\mathbf{ATIME}[t(n)]$ machine, input w, n = |w|. CompGraph(A, w) has depth O(t(n)) and size $2^{O(t(n))}$.

A deterministic Turing machine can systematically search this entire and-or graph using space O(t(n)). This is done, by keeping a string of length O(t(n)): $c_1c_2 \ldots c_r \star \ldots \star$ denoting that we are currently simulating step r of A's computation having made choices $c_1 \ldots c_r$ on all of the existential and universal branches up until now. The rest of the simulation will report an **answer** as to whether choices $c_1 \ldots c_r$ will lead to acceptance. This is done as follows:

If one of the following conditions holds:

- 1. $c_r = 1$, or
- 2. **answer** = "yes" and step r was existential, or
- 3. **answer** = "no" and step r was universal,

then let $c_r = \star$ and report **answer** back to the $r-1^{\rm st}$ step. Otherwise, set $c_r = 1$ and continue. Note, that we do not have to store intermediate IDs of the simulation because the sequence $c_1c_2 \ldots c_r \star \ldots \star$ uniquely determines which ID of A we go to next.



We evaluate the computation graph of $\mathbf{ATIME}[t(n)]$ machine using t(n) space to cycle through all possible computations of A on input w.

The **game tree** for the machine represents all possible configurations and moves of the players. In effect our algorithm exhaustively searches every possible path through this tree, using space t(n) to keep track of where in the search it might be. (One could do this with a very time-inefficient recursive algorithm.)

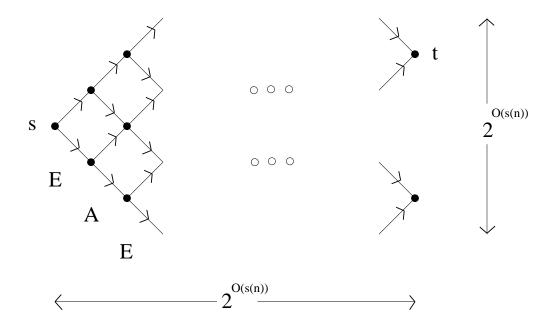
Theorem 21.8 ASPACE $[s(n)] = \mathbf{DTIME}[2^{O(s(n))}]$

Proof: ASPACE $[s(n)] \subseteq \text{DTIME}[2^{O(s(n))}]$:

Let A be an $\mathbf{ASPACE}[s(n)]$ machine. Let w be an input, n=|w|.

CompGraph(A(w)) has size $\leq 2^{O(s(n))}$

The marking algorithm evaluates this in $\mathbf{DTIME}[2^{O(s(n))}]$.



We mark the winner at each point, starting from the end configurations and working backward.

 $\mathbf{DTIME}[2^{O(s(n))}] \subseteq \mathbf{ASPACE}[s(n)]$:

Let M be a **DTIME** $[2^{k(s(n))}]$ TM.

w an input, n = |w|.

Define an alternating procedure C(t, p, a) which accepts iff the contents of cell p at time t in M's computation on input w is symbol a.

Inductively, C(t+1, p, b) holds iff the three symbols a_{-1}, a_0, a_1 in tape positions p-1, p, p+1 lead to a "b" in position p in one step of M's computation.

$$(a_{-1}, a_0, a_1) \stackrel{M}{\rightarrow} b$$

$$C(t+1, p, b) \equiv (\exists a_{-1}, a_0, a_1) ((a_{-1}, a_0, a_1) \xrightarrow{M} b \land (\forall i \in \{-1, 0, 1\}) (C(t, p+i, a_i)))$$

Space needed is $O(\log 2^{k(s(n))}) = O(s(n))$.

Note that M accepts w iff $C(2^{k(s(n))},1,\langle q_f,1\rangle)$

	Space					
	1	2	p	n		T(n)
Time 0	$\langle q_0,w_1 angle$	w_2		w_n \sqcup		Ш
1	w_1	$\langle q_1, w_2 \rangle$	• • •	w_n \sqcup		
	:	:	:		•	
t			$a_{-1} a_0 a_1$			
t+1			b			
	:	:	:		•	
T(n)	$\langle q_f, 1 angle$	• • •	• • •		• • •	

$$C(t+1, p, b) \equiv (\exists a_{-1}, a_0, a_1) ((a_{-1}, a_0, a_1) \xrightarrow{M} b \land (\forall i \in \{-1, 0, 1\}) (C(t, p+i, a_i)))$$

Game Semantics: At each point in the game the contents of a single cell of the tableau are in dispute. Originally this is the bottom-left cell, which White claims is accepting. At each move White names the three cells above the current one, which must imply the claimed contents of the current one. Black then picks one of these three to dispute. Note the similarity to the Circuit Game.

This completes the proof of Theorem 21.2.

