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- Suppose we apply  $\Phi$  to  $\Sigma^s$
- $\Phi$  holding in  $\Sigma^s$  does not preclude the possibility that our program violates safety!

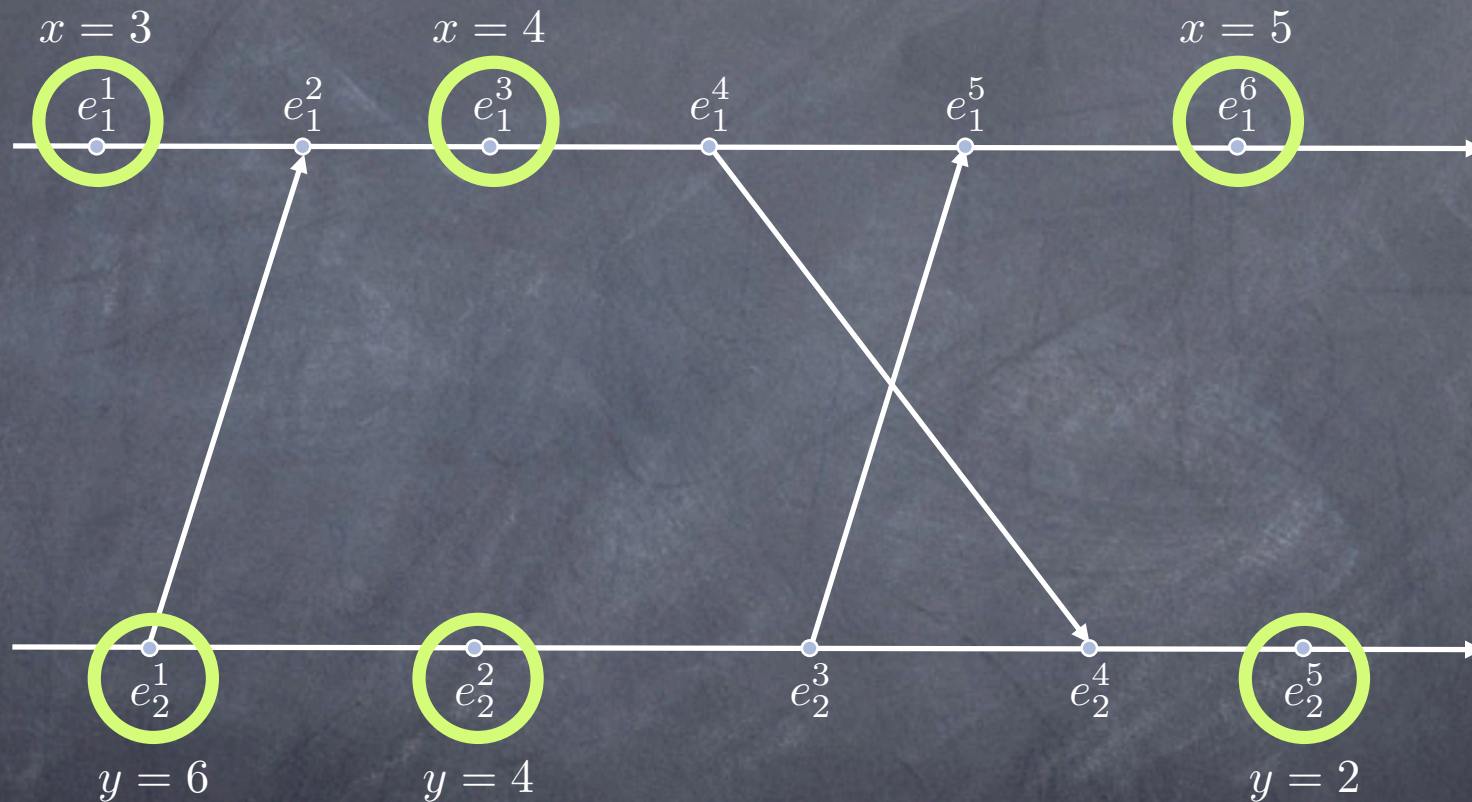
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- $\Phi$  holding in  $\Sigma^s$  does not imply that  $\Phi$  ever held during the actual computation!

# Example



Detect whether the following predicates hold:

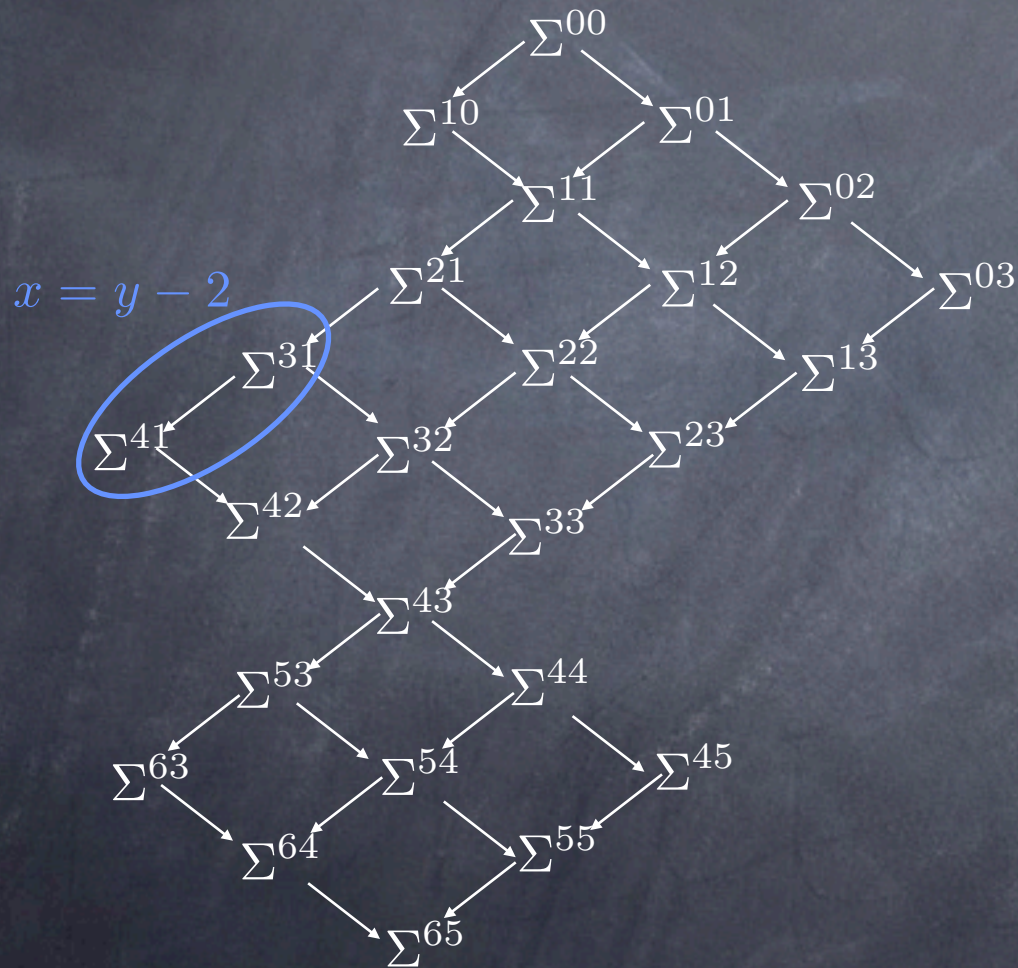
$$x = y$$

$$x = y - 2$$

Assume that initially:

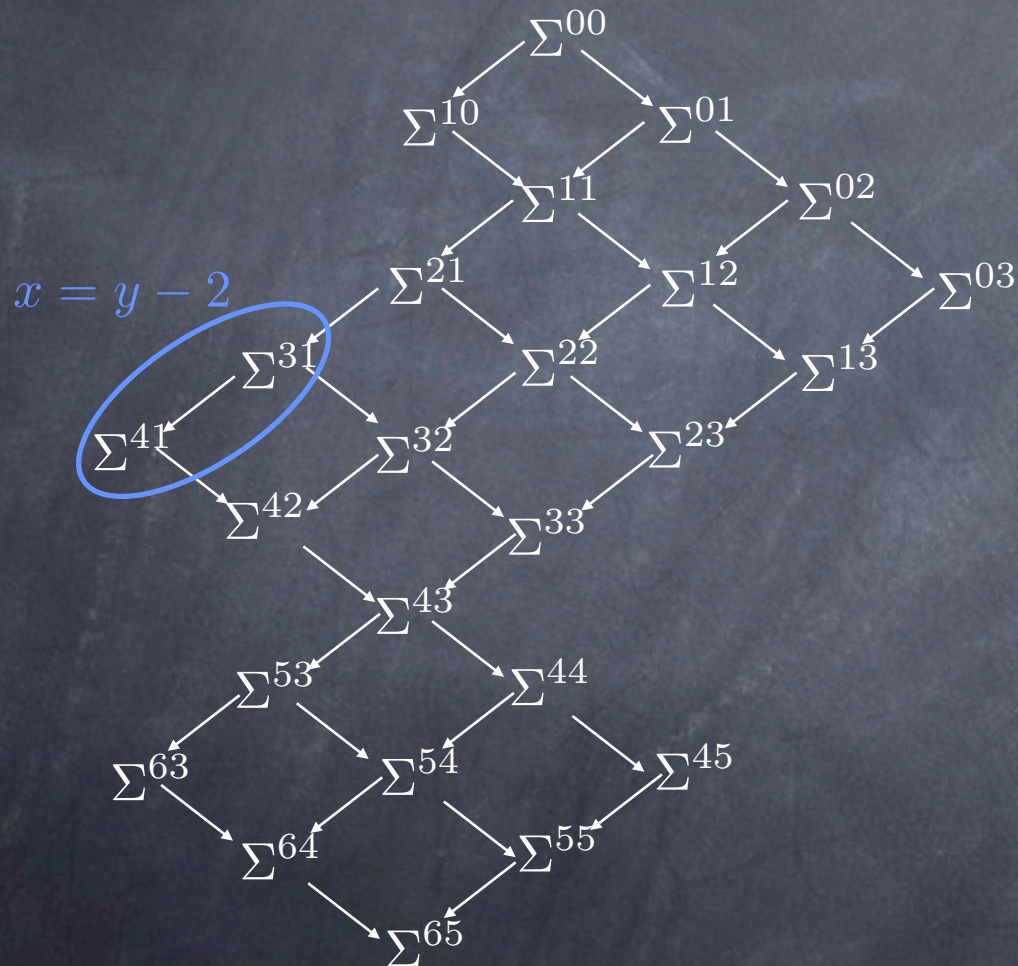
$$x = 0; y = 10$$

# Possibly

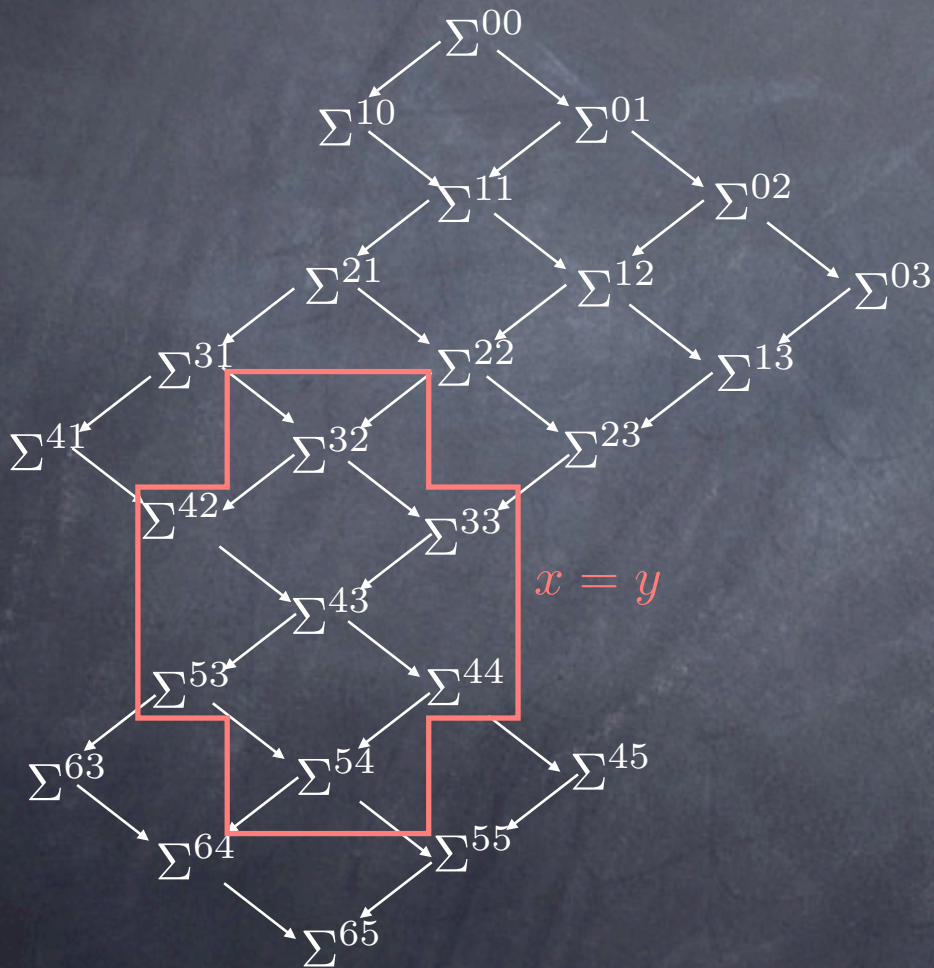


- If  $\Sigma^s$  is  $\Sigma^{31}$  or  $\Sigma^{41}$ ,  $x = y - 2$  is detected, but it may never have occurred

# Possibly

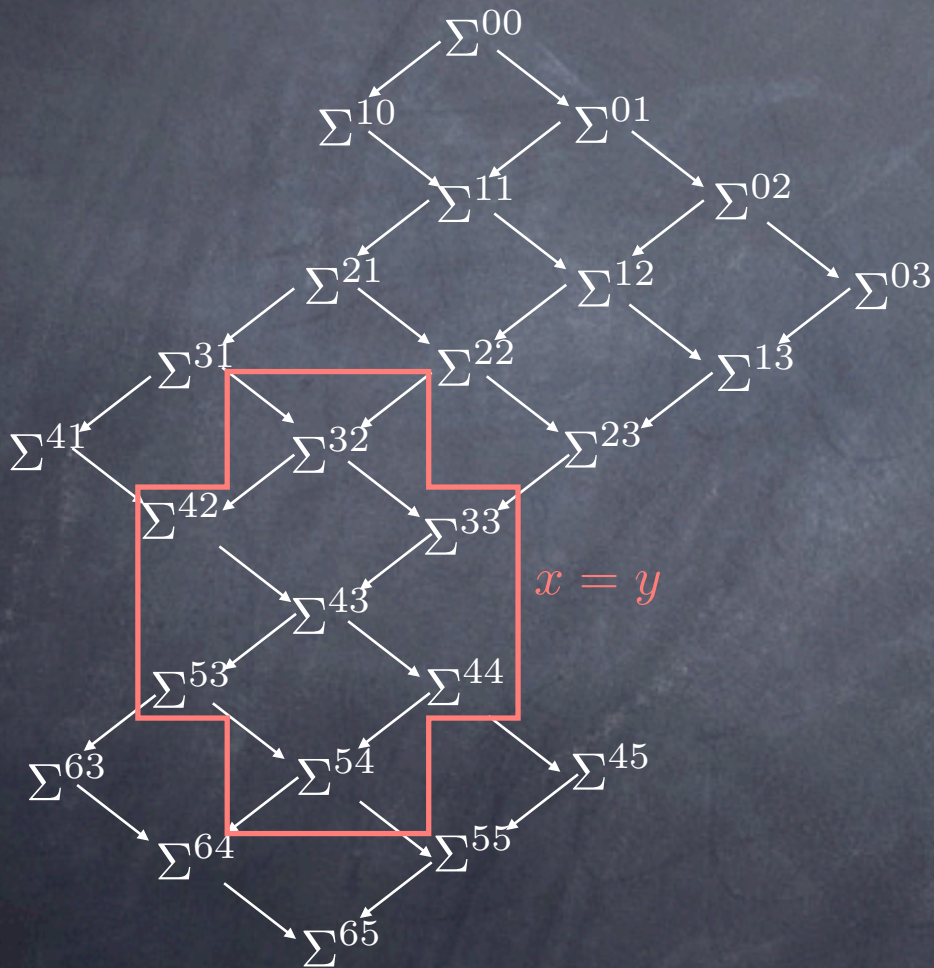


# Definitely



- We know that  $x = y$  has occurred, but it may not be detected if tested before  $\Sigma^{32}$  or after  $\Sigma^{54}$

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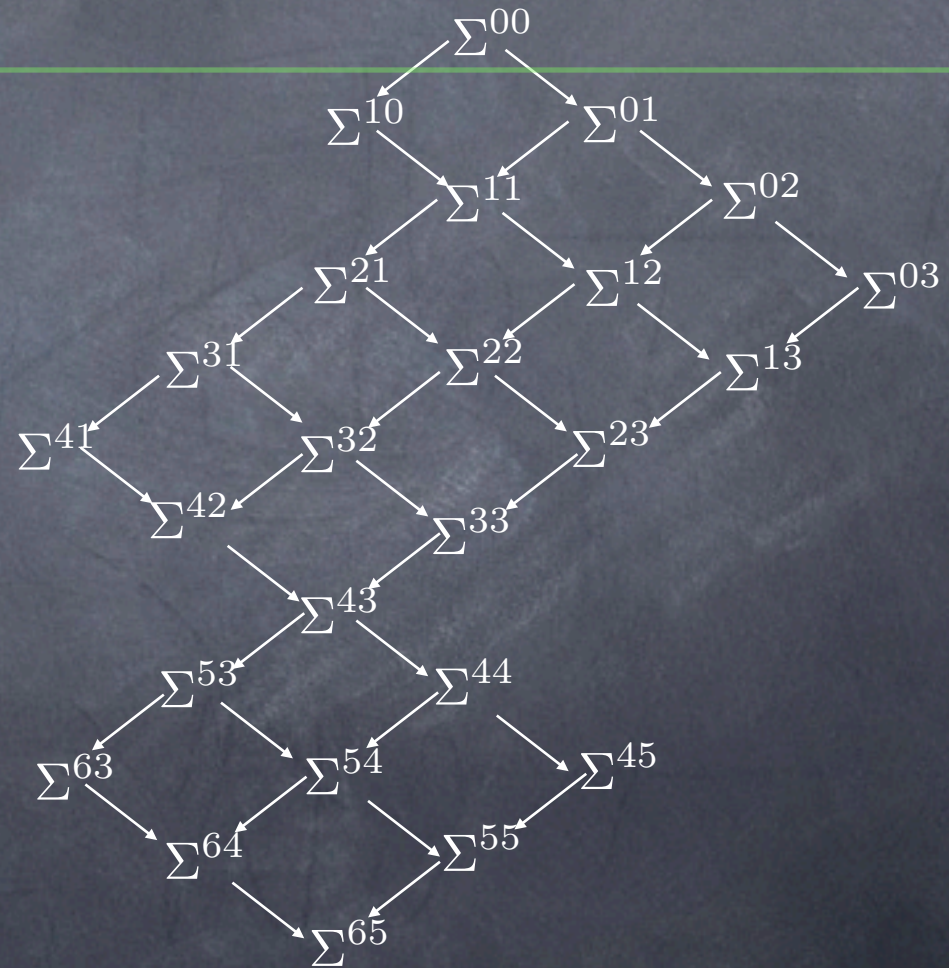


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• **Definitely( $\Phi$ )**  
For every consistent observation  $O$  of the computation, there exists a global state of  $O$  in which  $\Phi$  holds

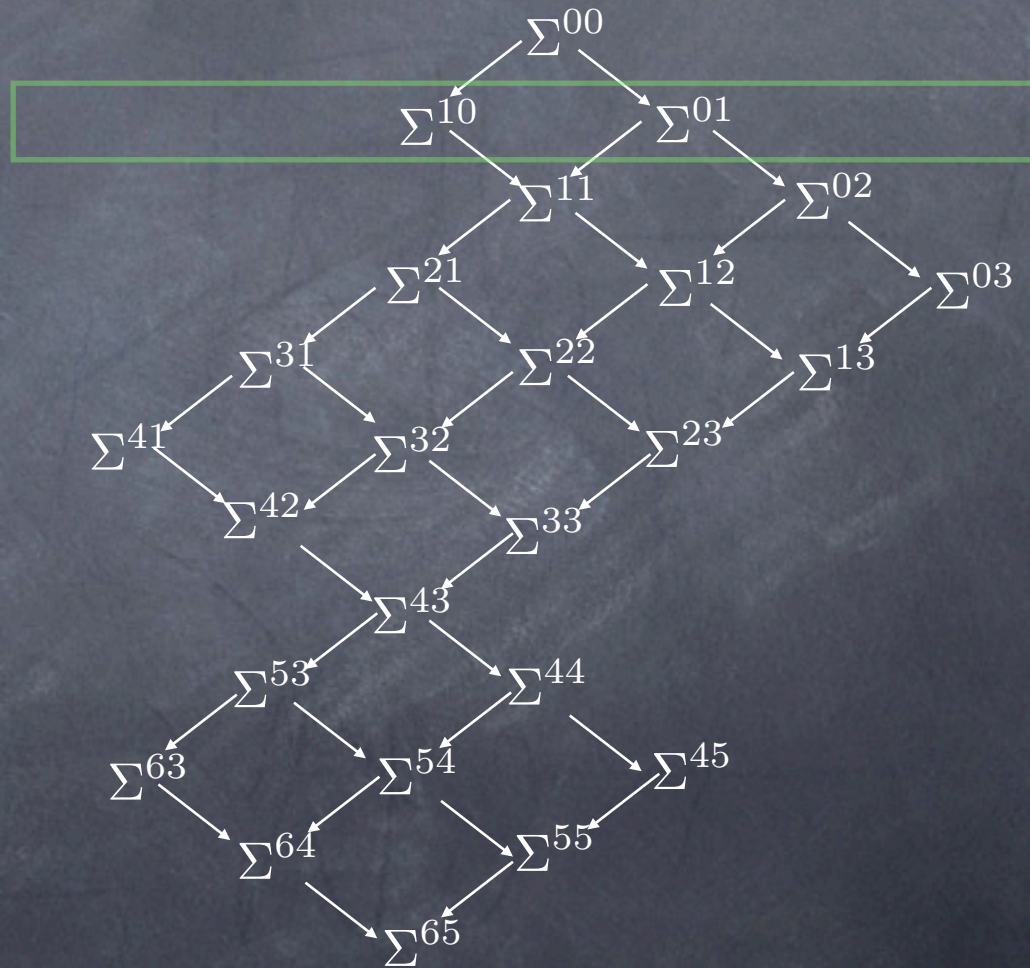
# Computing Possibly

- Scan lattice, level after level
- If  $\Phi$  holds in **one** global state, then  $\text{Possibly}(\Phi)$



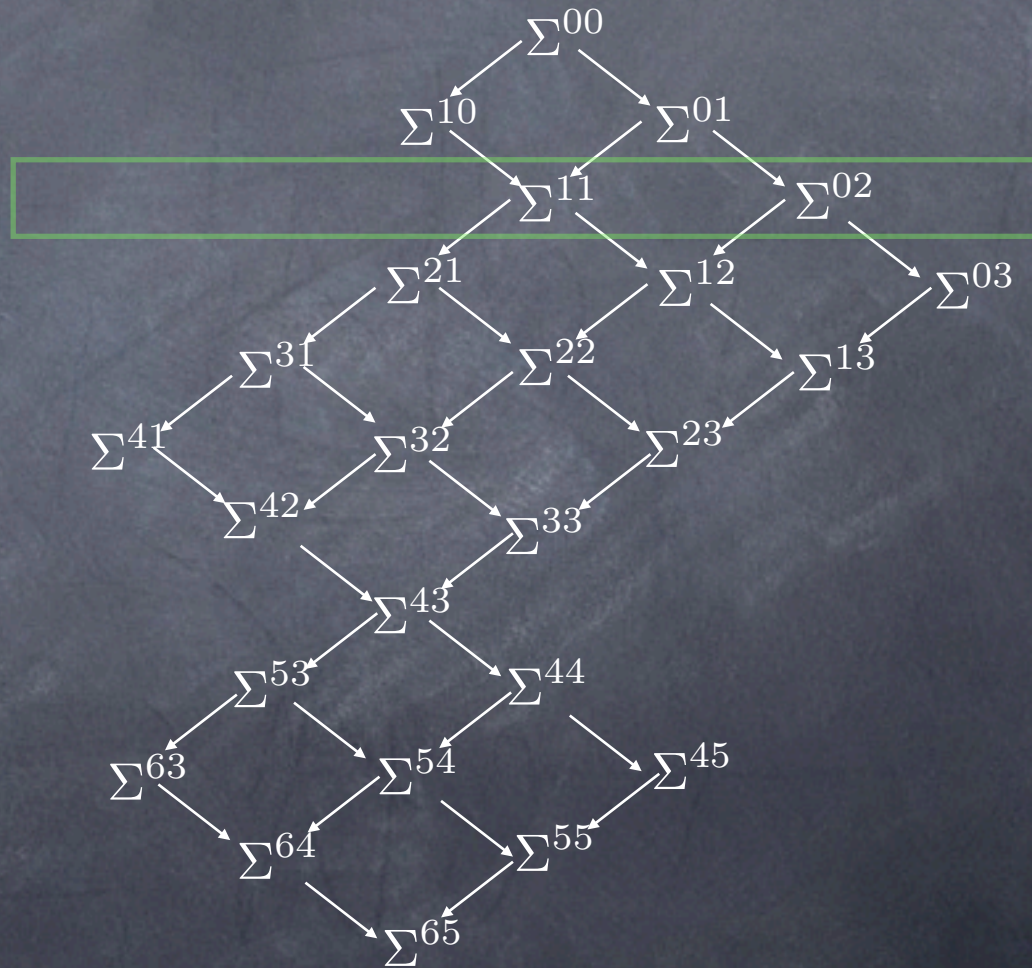
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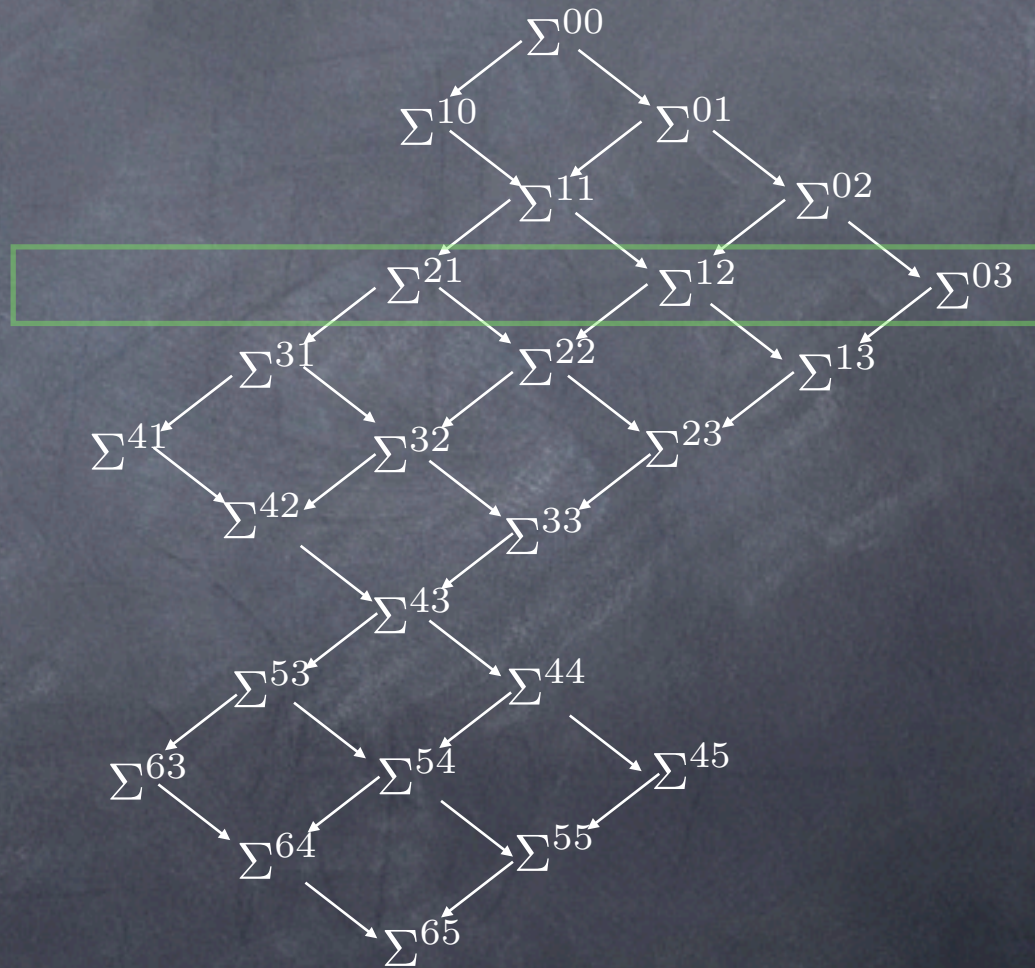
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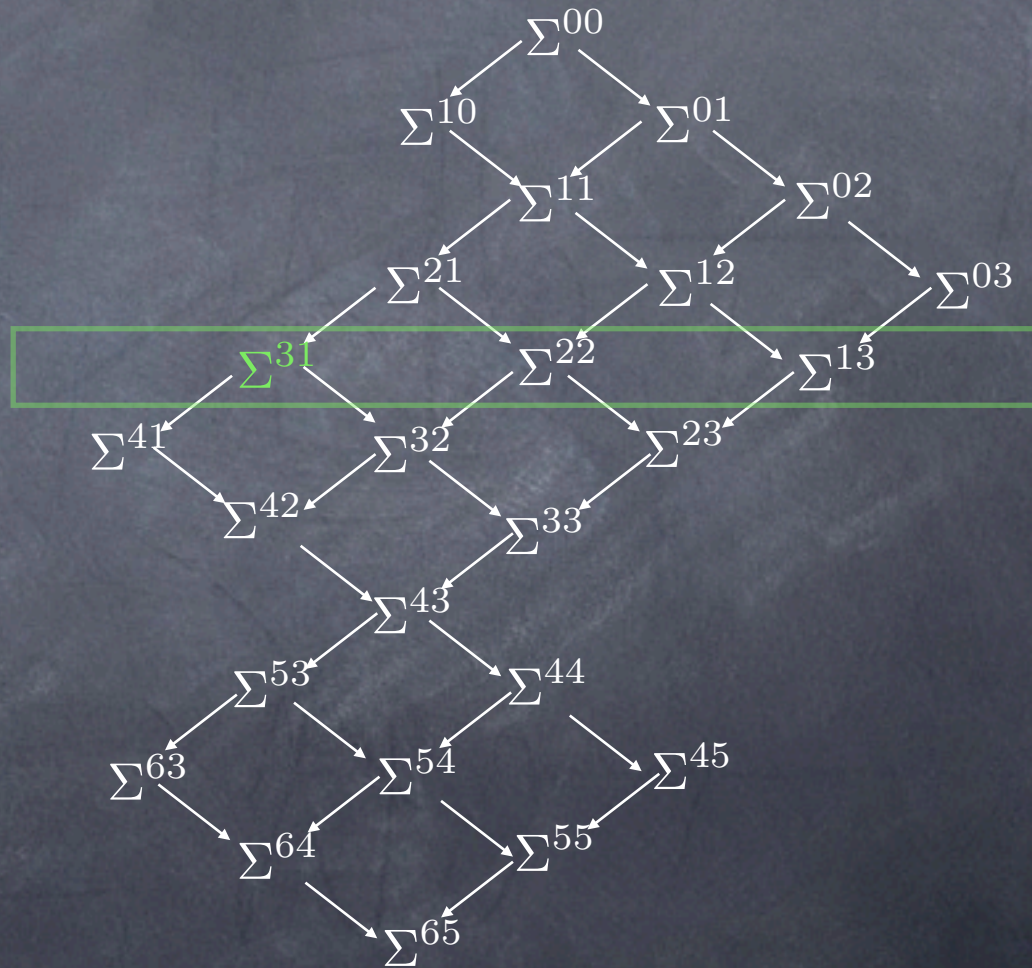
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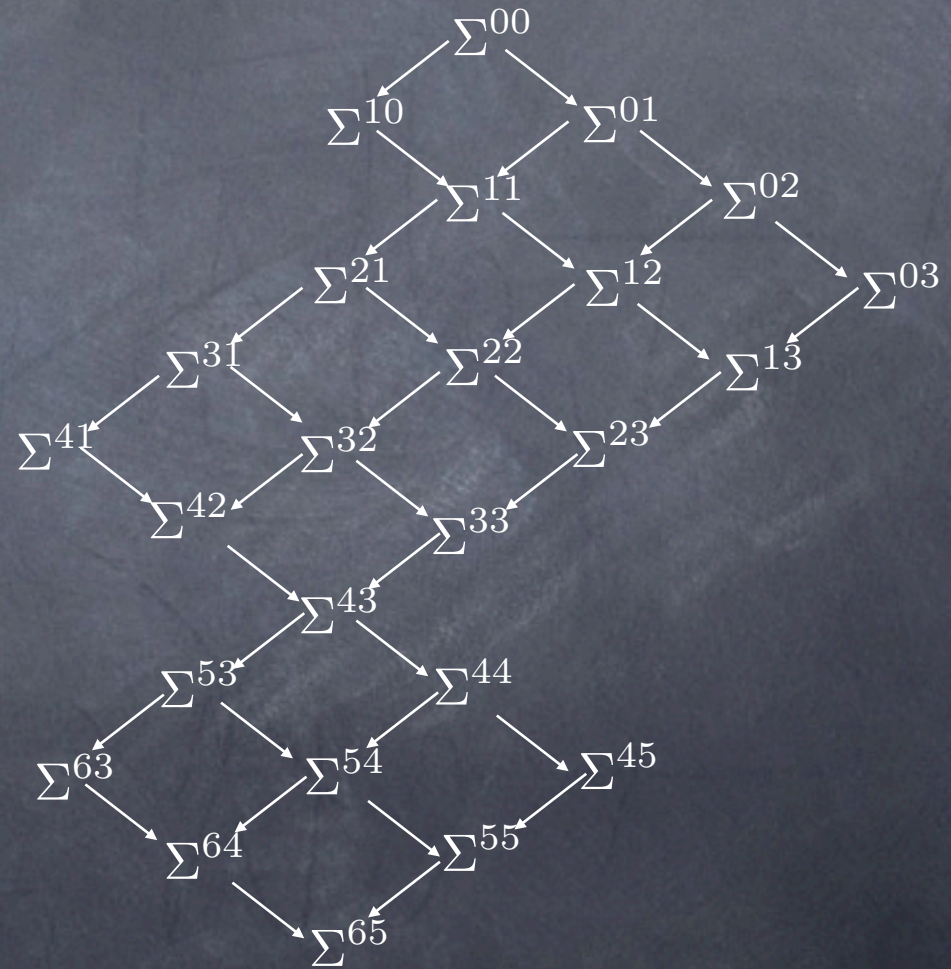
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$\text{Possibly}(x = y - 2)$

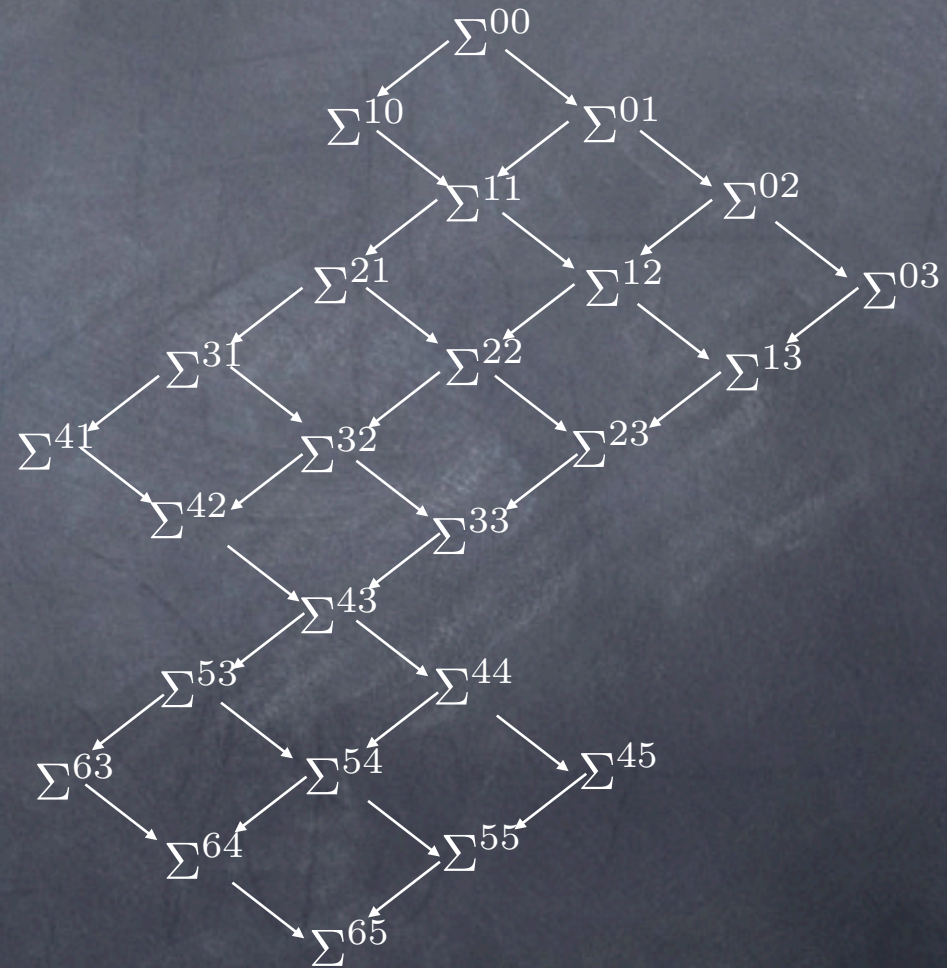
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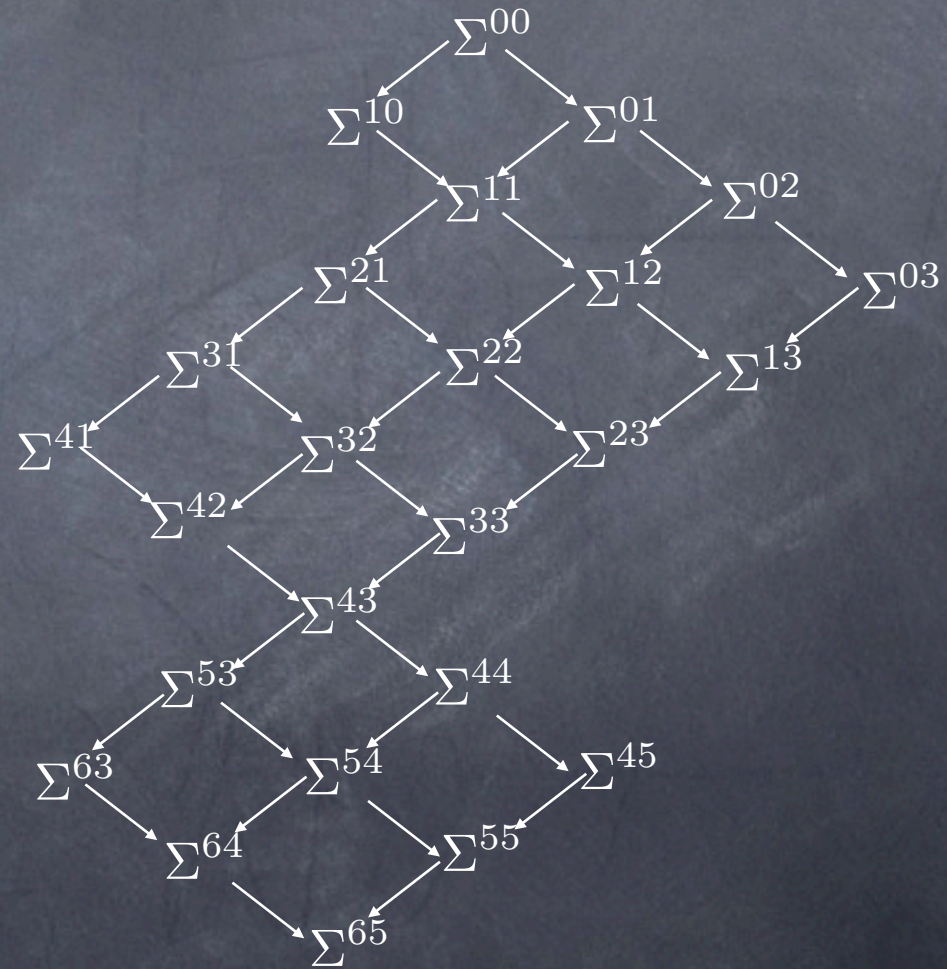
# Computing Definitely

Scan lattice, level after level

Given a level, only expand nodes that correspond to states for which  $\neg\Phi$

If no such state, then  $\text{Definitely}(\Phi)$

If reached last state  $\Sigma^l$ , and  $\Phi(\Sigma^l)$ , then  $\neg\text{Definitely}(\Phi)$



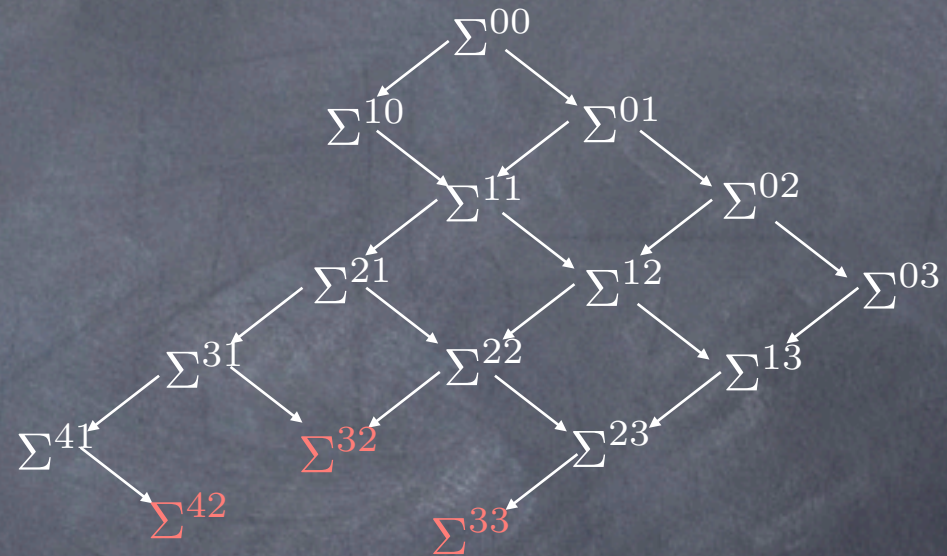
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$\text{Definitely}(x = y)$

# Building the lattice: collecting local states

- To build the global states in the lattice,  $p_0$  collects **local states** from each process.
- $p_0$  keeps the set of local states received from  $p_i$  in a FIFO queue  $Q_i$

Key questions:

1. when is it safe for  $p_0$  to discard a local state  $\sigma_i^k$  of  $p_i$ ?
2. Given level  $i$  of the lattice, how does one build level  $i + 1$ ?

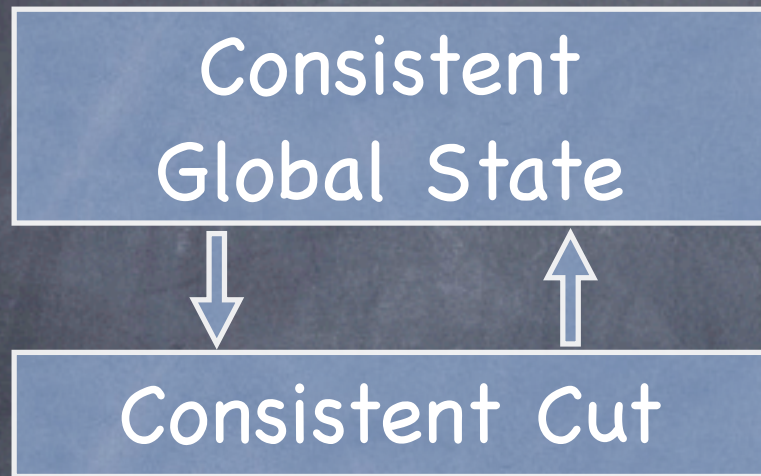
# Garbage-collecting local states

- ⑥ For each local state  $\sigma_i^k$ , we need to determine:
  - $\Sigma_{min}(\sigma_i^k)$ , the **earliest** consistent state that  $\sigma_i^k$  can belong to
  - $\Sigma_{max}(\sigma_i^k)$ , the **latest** consistent state that  $\sigma_i^k$  can belong to

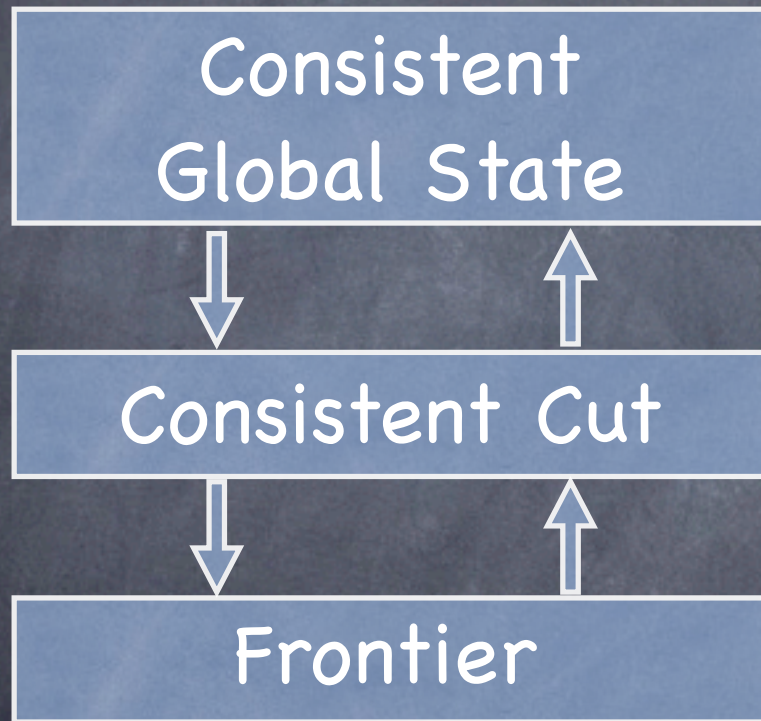
# Defining "earliest" and "latest"

Consistent  
Global State

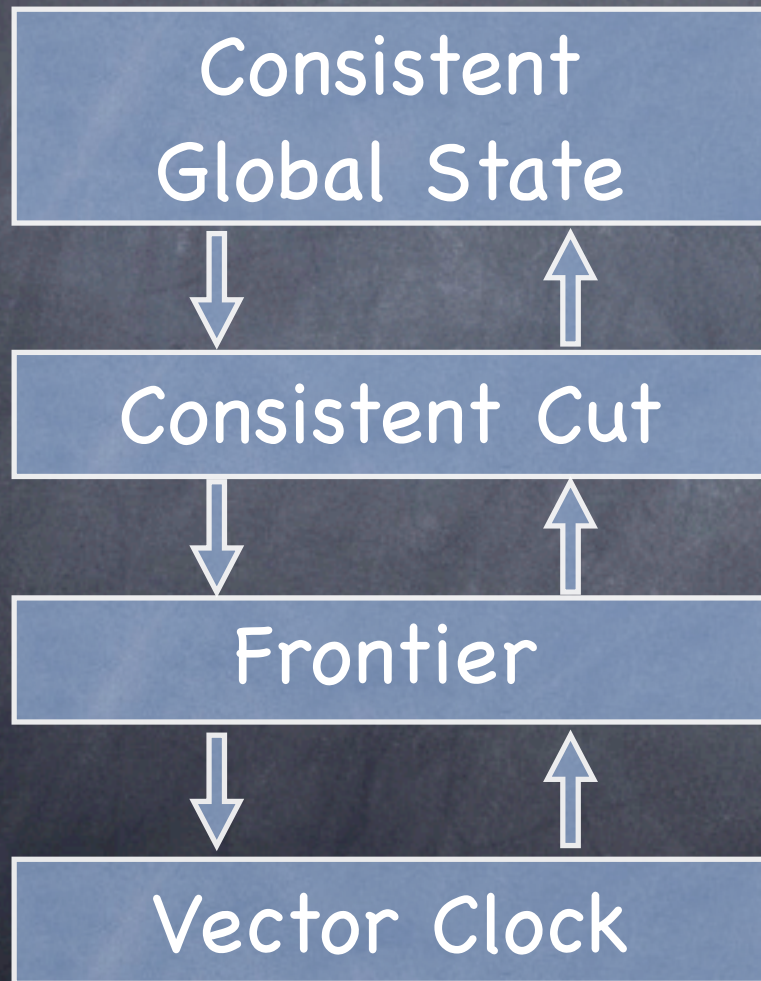
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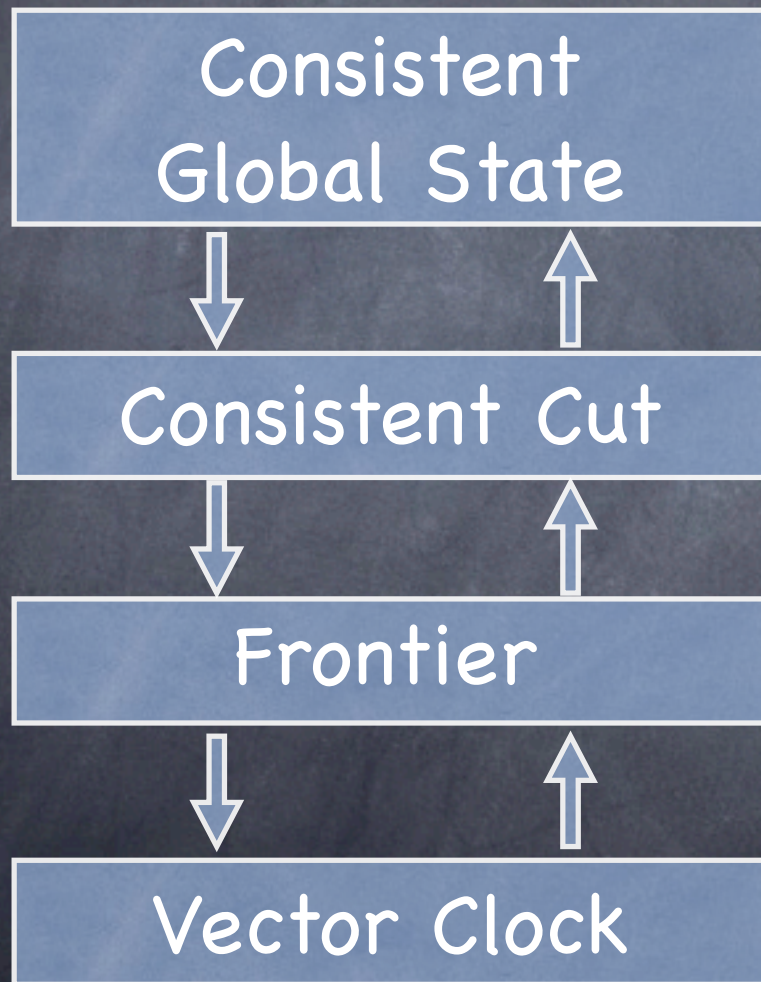
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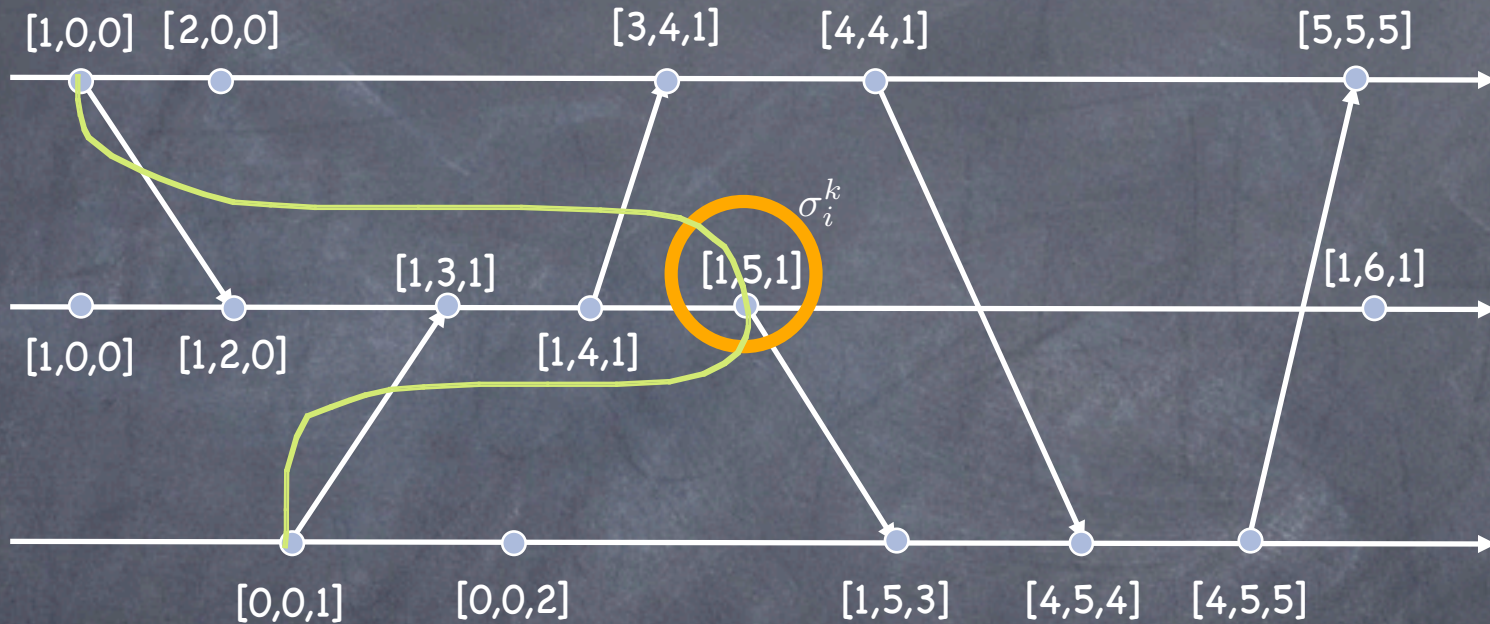
# Defining "earliest" and "latest"



Associate a vector clock with each consistent global state

- $\Sigma_{min}(\sigma_i^k)$  is the consistent global state with the lowest vector clock that has  $\sigma_i^k$  on its frontier
- $\Sigma_{max}(\sigma_i^k)$  is the one with the highest

# Computing $\Sigma_{min}$

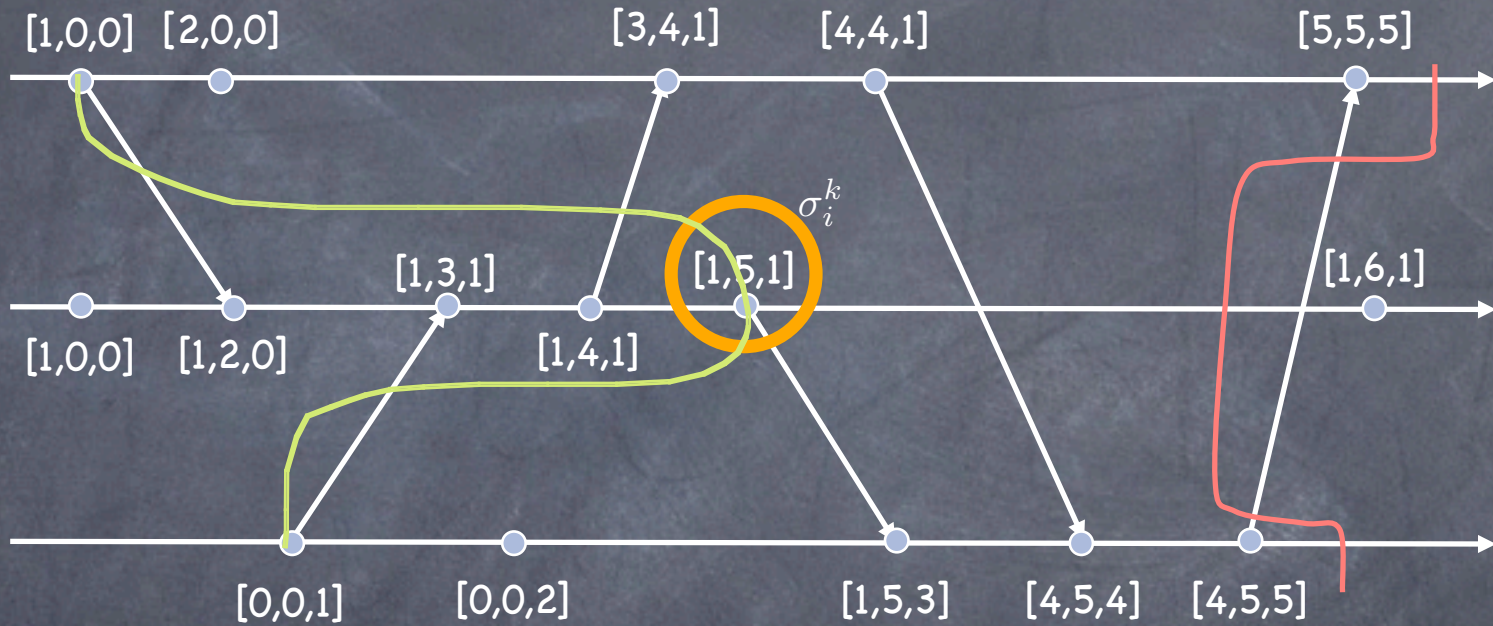


Label  $\sigma_i^k$  with  $VC(e_i^k)$

$$\Sigma_{min}(\sigma_i^k) = (\sigma_1^{c_1}, \sigma_2^{c_2}, \dots, \sigma_n^{c_n}) : \forall j : c_j = VC(\sigma_i^k)[j]$$

$\Sigma_{min}(\sigma_i^k)$  and  $\sigma_i^k$  have the same vector clock!

# Computing $\Sigma_{max}$

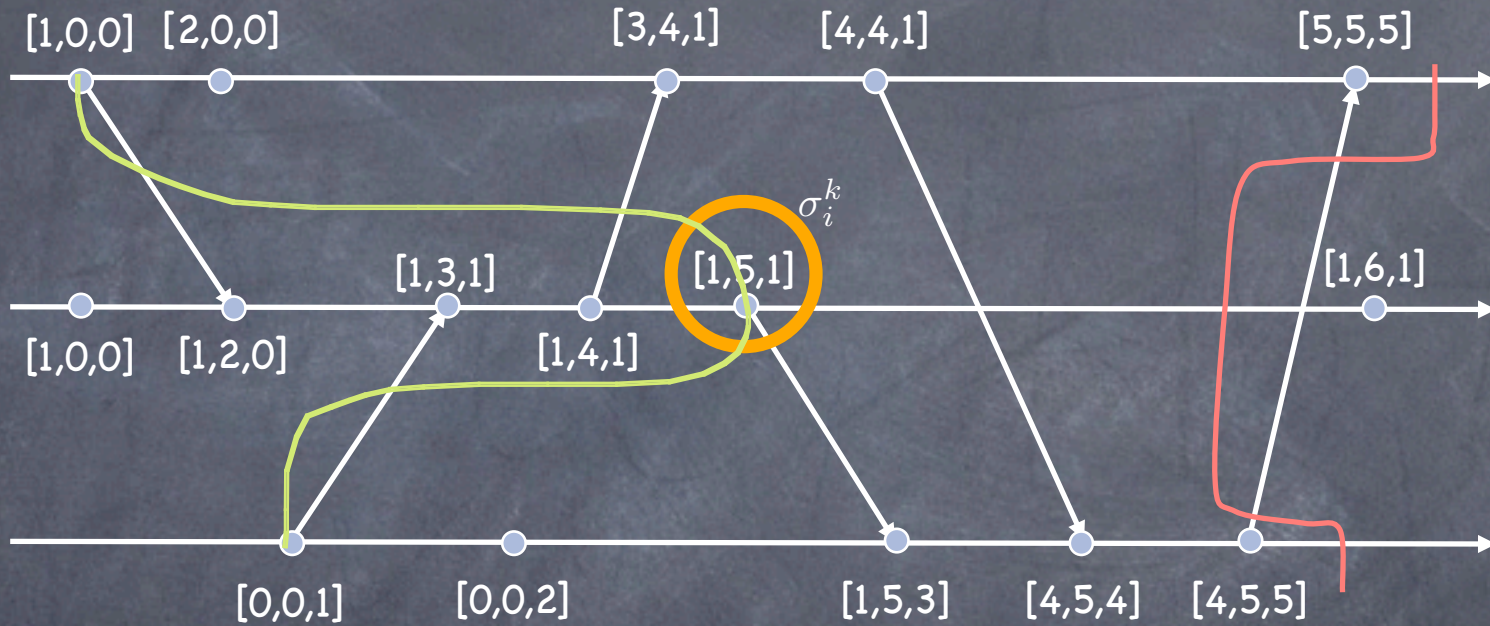


$$\Sigma_{max}(\sigma_i^k) = (\sigma_1^{c_1}, \sigma_2^{c_2}, \dots, \sigma_n^{c_n}) :$$

$$\wedge \forall j : VC(\sigma_j^{c_j})[i] \leq VC(\sigma_i^k)[i]$$

$$\wedge ((\sigma_j^{c_j} = \sigma_j^{c_{j+1}}) \vee VC(\sigma_j^{c_{j+1}})[i] > VC(\sigma_i^k)[i])$$

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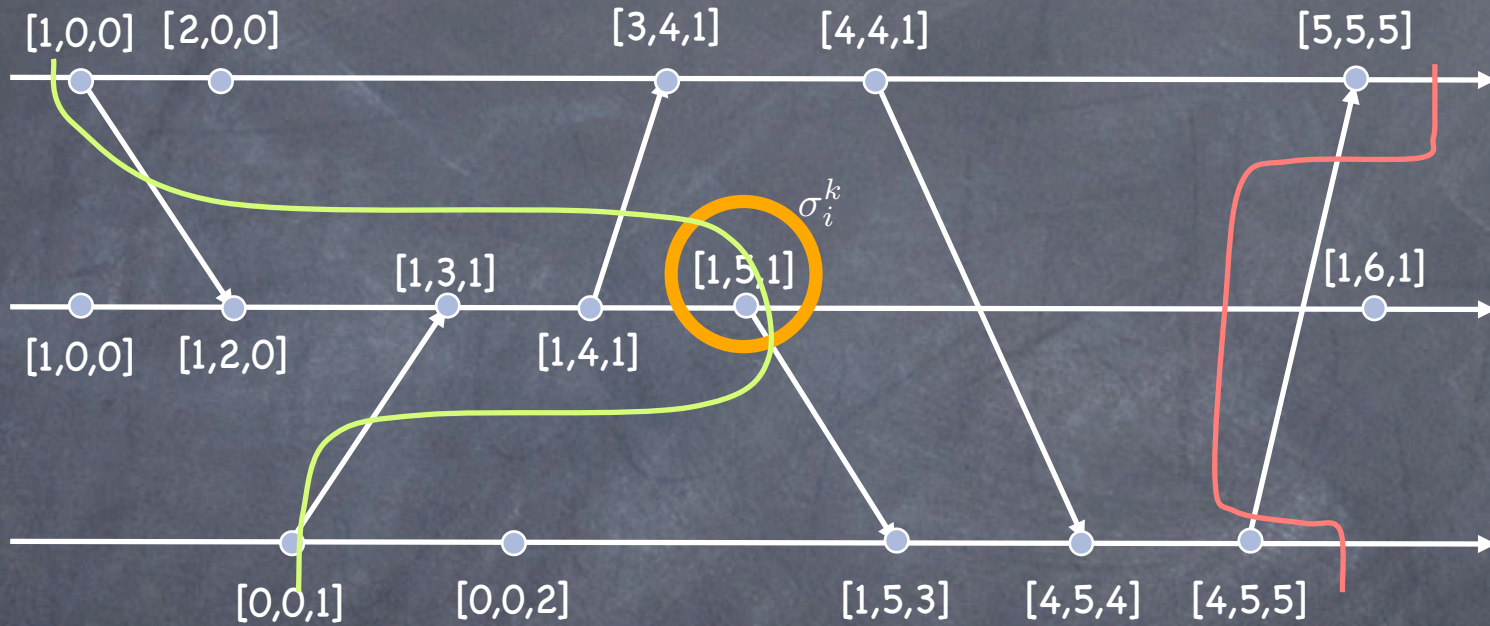
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set of local states  
one for each process,  
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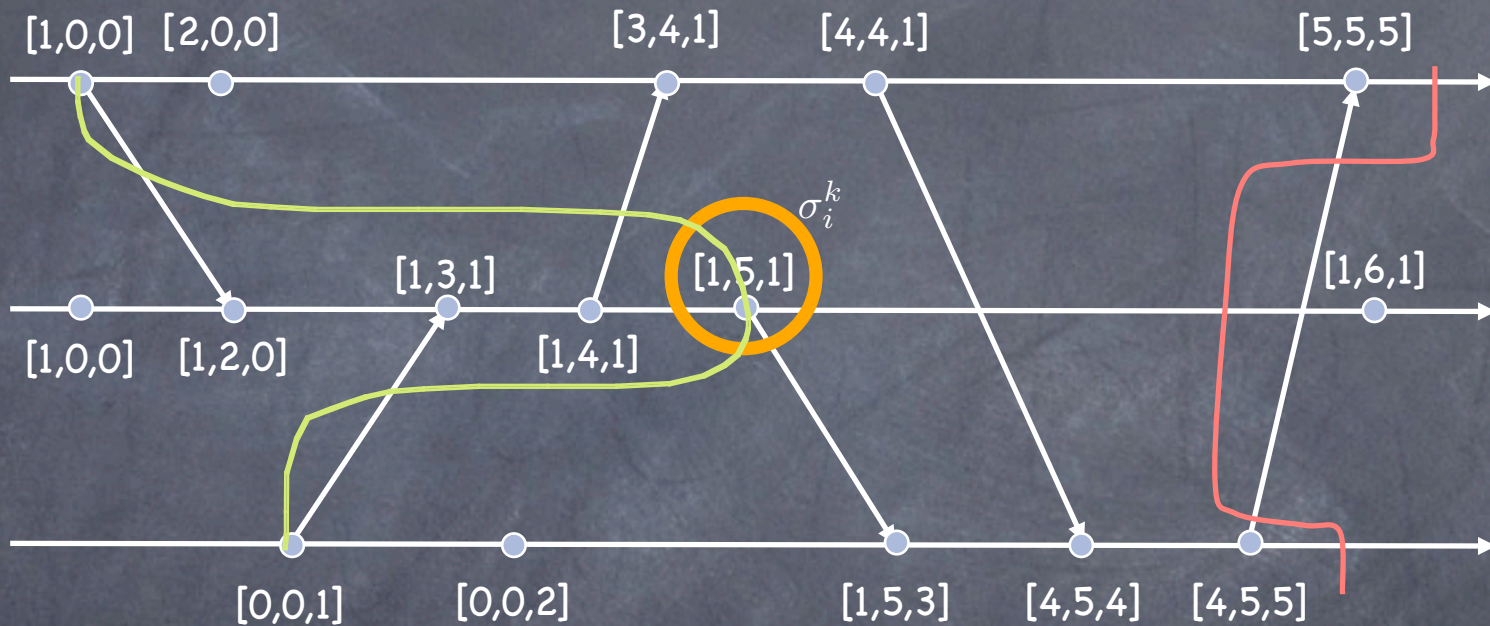
$$\wedge ((\sigma_j^{c_j} = \sigma_j^{c_f}) \vee VC(\sigma_j^{c_j+1})[i] > VC(\sigma_i^k)[i])$$

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all local states are pair-  
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wise consistent with  $\sigma_i^k$

and they are the  
last such state

# Assembling the levels

• To build level  $l$

□ wait until each  $Q_i$  contains a local state for whose vector clock:

$$\sum_{i=1}^n VC[i] \geq l$$

• To build level  $l + 1$

□ For each global state  $\sum^{i_1, i_2, \dots, i_n}$  on level  $l$ , build

$$\sum^{i_1+1, i_2, \dots, i_n}, \sum^{i_1, i_2+1, \dots, i_n}, \dots, \sum^{i_1, i_2, \dots, i_n+1}$$

□ Using  $VC$ s, check whether these global states are consistent