

## Lecture-7

### \* POMDP review -

$$M = (S, A, \Omega, O, P, R, do, V)$$

$\Omega$  = set of possible observations that agent can make  
 $O$  = Observation function

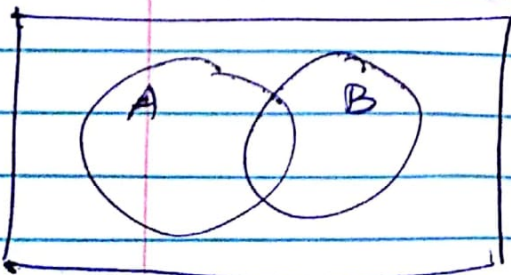
$$O: S \times \Omega \Rightarrow [0, 1]$$

$$O(s, \omega) = Pr(\omega_t = \omega | s_t = s)$$

$\omega$  = Observation at time  $t$

### \* Conditional Probability -

$$P(A = a | B = b) = \frac{P(A = a, B = b)}{P(B = b)}$$



$$E[A | B = b] = \sum_a a \cdot P_i(A = a | B = b)$$

## Marginalization —

$A$  = Sum of two die-roll  
 $B$  = First die-roll

$$\Pr(A=a) = \sum_b \Pr(B=b) \cdot \Pr(A=a|B=b)$$

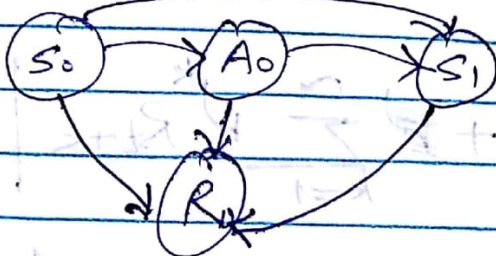
## Baye's Theorem —

$$\Pr(A=a|B=b) = \frac{\Pr(A=a, B=b)}{\Pr(B)}$$

$$\Pr(B=b|A=a) = \frac{\Pr(B=b, A=a)}{\Pr(A)}$$

$$\therefore \Pr(A=a|B=b) = \frac{\Pr(B=b|A=a) \Pr(A=a)}{\Pr(B=b)}$$

Baye's Net = (Deseperation)



• Conditional independence:

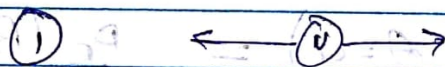
if  $X$  is independent of  $Z$

given  $Y$  men,

$$P_\theta(X=x | Y=y, Z=z) \\ = P_\theta(X=x | Y=y)$$

deseperation :  $X$  &  $Z$  are deseperated by evidence variables  $Y$  iff every undirected path from  $X$  to  $Z$  is blocked

path blocked if :  $\exists v \in Y$



Belman equation :

$$V^\pi(s) = \mathbb{E} \left[ R_t + \gamma \sum_{k=1}^{\infty} \gamma^k R_{t+k} \mid S_t=s, \pi \right]$$

$$= \mathbb{E} \left[ R_t + \gamma \sum_{k=0}^{\infty} \gamma^k R_{t+k+1} \mid S_t=s, \pi \right]$$

$$= \sum_a P_\pi(A_t=a \mid S_t=s, \pi) \mathbb{E} \left[ R_t + \gamma \sum_{k=0}^{\infty} \gamma^k R_{t+k+1} \mid S_t=s, \pi, A_t=a \right]$$

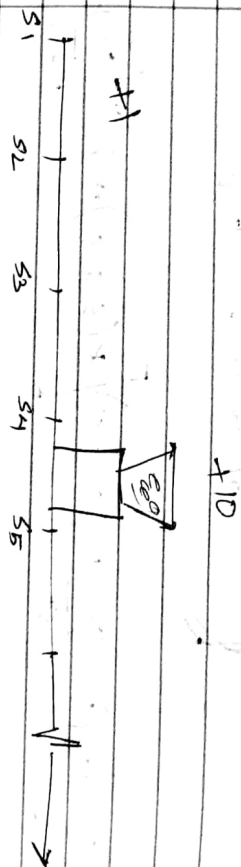
$$= \sum_a \pi(s, a) \sum_{s'} P(s, a, s') \left( \mathbb{E}[R_t | s_t = s, A_t = a, s_{t+1} = s', A_{t+1} = a] + \mathbb{E}\left[\sum_{k=0}^{\infty} \gamma^k R_{t+1+k} \mid \begin{matrix} s_t = s \\ a_t = a \\ s_{t+1} = s' \\ a_{t+1} = a \end{matrix}\right] \right)$$

$$= \sum_a \pi(s, a) \sum_{s'} P(s, a, s') \left[ R(s, a, s') + \gamma \mathbb{E}\left[\sum_{k=0}^{\infty} \gamma^k R_{t+1+k} \mid \begin{matrix} s_t = s \\ a_t = a \\ s_{t+1} = s' \\ a_{t+1} = a \end{matrix}\right] \right]$$

$$V^{\pi}(s')$$

$$\therefore = \sum_a \pi(s, a) \sum_{s'} P(s, a, s') \left[ R(s, a, s') + \gamma V^{\pi}(s') \right]$$

## \* Example



$$v^{\pi}(s_5) = 0$$

$$v^{\pi}(s_4) = 10$$

$$v^{\pi}(s_1) = R(s_1, s_2) + \gamma v^{\pi}(s_2)$$

$$= 1 + 5/4$$

\* Optimal value function

$$v^* : S \Rightarrow R$$

$$v^*(s) = \max_{\pi \in \Pi} v^{\pi}(s)$$