

Summary

Last Week: Random sketching and subspace embedding. $\|S Ax\| \approx \|Ax\|$

- Subspace embedding from the distributional Johnson-Lindenstrauss lemma and an ϵ -net argument.
- Application to fast over-constrained linear regression.
- Proof of distributional JL via the Hanson-Wright inequality.
- You'll see two more applications of subspace embeddings on the problem set, along with problems practicing the use of ϵ -nets and the Hanson-Wright inequality.

Summary

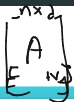
Last Week: Random sketching and subspace embedding.

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Today:

- Subspace embedding via sampling.
- The matrix leverage scores.
- Analysis via matrix concentration bounds.
- Spectral graph sparsifiers.

Quiz Review

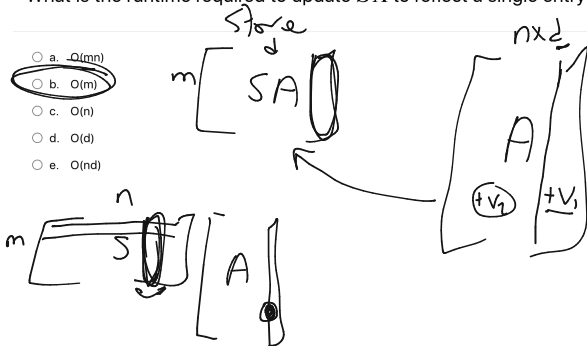


Nisan's PRG

Consider applying linear sketching in the streaming setting. There is some underlying matrix $A \in \mathbb{R}^{n \times d}$, initially zero. In each step you receive an update of the form (i, j, v) which modifies A_{ij} by adding v to it. You pick a random sketching matrix $S \in \mathbb{R}^{m \times n}$, and maintain the sketch SA over the updates of A . Storing this sketch requires storing only $m \times d$ entries, as opposed to $n \times d$ for storing all of A

What is the runtime required to update SA to reflect a single entry update to A ?

- a. $O(mn)$
- b. $O(m)$
- c. $O(n)$
- d. $O(d)$
- e. $O(nd)$



Question 4

Not complete

Points out of 1.00

Flag question

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Quiz Review

Which of the following concentration bounds can be apply to show that, for a random $x \in \mathbb{R}^n$ with i.i.d. ± 1 entries, and some fixed $A \in \mathbb{R}^{n \times n}$, that $x^T A x$ is concentrated around its mean? Select all that apply.

- a. Chebyshev inequality
- b. Hanson-Wright Inequality
- c. ~~Markov bound~~
- d. ~~Bernstein bound~~

$$\begin{aligned} \text{Var}(x^T A x) &= \text{Var}\left(\sum_{i,j} A_{i,j} x_i x_j\right) \\ &= \sum_{i \neq j} \text{Var}(A_{i,j} x_i x_j) + \sum_i \text{Var}(A_{i,i} x_i^2) \end{aligned}$$

Linearity of variance due to pairwise independence

Question 6

Not complete

Points out of 1.00

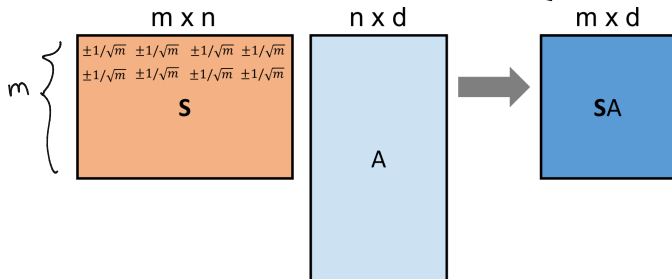
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Subspace Embedding

$S \in \mathbb{R}^{m \times n}$ is an ϵ -subspace embedding for $A \in \mathbb{R}^{n \times d}$, if for all $x \in \mathbb{R}^d$,

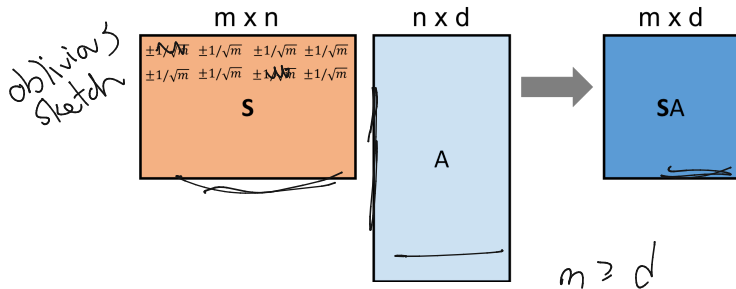
$$(1 - \epsilon) \|Ax\| \leq \|SAx\|_2 \leq (1 + \epsilon) \|Ax\|_2. \quad \|SAx\| \approx_{\epsilon} \|Ax\|$$



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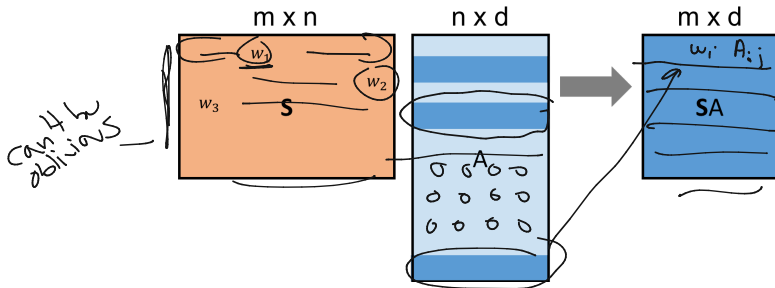


Last Time: If S is a random sign matrix, and $m = O\left(\frac{d + \log(1/\delta)}{\epsilon^2}\right)$, then for any A , S is an ϵ -subspace embedding with probability $\geq 1 - \delta$.

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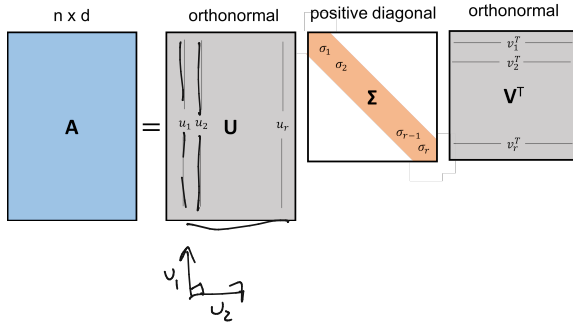


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In many applications it is preferable for S to be a **row sampling** matrix. The sample can preserve sparsity, structure, etc.

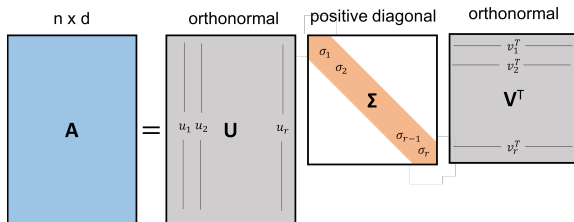
Problem Reformulation

For $A \in \mathbb{R}^{n \times d}$, let $A = U\Sigma V^T$ be its SVD. $U \in \mathbb{R}^{n \times \text{rank}(A)}$, $V \in \mathbb{R}^{d \times \text{rank}(A)}$ are orthonormal, and $\Sigma \in \mathbb{R}^{\text{rank}(A) \times \text{rank}(A)}$ is positive diagonal.



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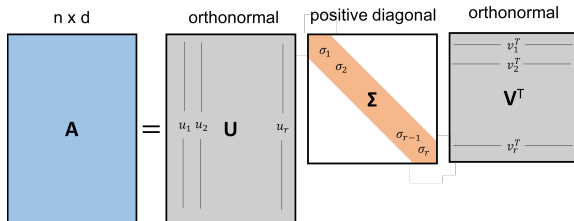


$$Ax = U\Sigma V^T x = Uz$$

- For any $x \in \mathbb{R}^d$, let $z = \Sigma V^T x$. Observe that: $\|Ax\|_2 = \|Uz\|_2$ and $\|SA^*x\|_2 = \|SUz\|_2$.

Problem Reformulation

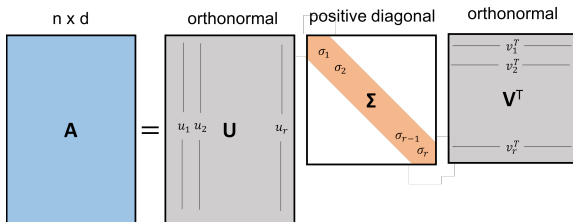
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- Thus, to prove that S is an ϵ -subspace embedding for A , it suffices to show that it is an ϵ -subspace embedding for U .

Problem Reformulation

For $A \in \mathbb{R}^{n \times d}$, let $A = U\Sigma V^T$ be its SVD. $U \in \mathbb{R}^{n \times \text{rank}(A)}$, $V \in \mathbb{R}^{d \times \text{rank}(A)}$ are orthonormal, and $\Sigma \in \mathbb{R}^{\text{rank}(A) \times \text{rank}(A)}$ is positive diagonal.



- For any $x \in \mathbb{R}^d$, let $z = \Sigma V^T x$. Observe that: $\|Ax\|_2 = \|Uv\|_2$ and $\|SA\|_2 = \|SUV\|_2$.
- Thus, to prove that S is an ϵ -subspace embedding for A , it suffices to show that it is an ϵ -subspace embedding for U .
- I.e., it suffices to show that for any $x \in \mathbb{R}^d$,

$$(1 - \epsilon) \|\underline{Ux}\|_2^2 \leq \|\underline{SUX}\|_2^2 \leq (1 + \epsilon) \|\underline{Ux}\|_2^2.$$

Loewner Ordering

Suffices to show that for any $x \in \mathbb{R}^d$,

$$(1-\epsilon)\|x\|_2^2 \leq \|S U x\|_2^2 \leq (1+\epsilon)\|x\|_2^2$$

Loewner Ordering

Suffices to show that for any $x \in \mathbb{R}^d$,

$$(1-\epsilon)x^T x \leq \|Sx\|_2^2 \leq (1+\epsilon)x^T x \implies (1-\epsilon)x^T I x \leq x^T \underbrace{U^T S^T S U}_{\text{Loewner}} x \leq (1+\epsilon)x^T I x.$$

Loewner Ordering

Suffices to show that for any $x \in \mathbb{R}^d$,

$$(1-\epsilon)\|x\|_2^2 \leq \|SUX\|_2^2 \leq (1+\epsilon)\|x\|_2^2 \implies \underline{(1-\epsilon)x^T I x \leq x^T U^T S^T S U x \leq (1+\epsilon)x^T I x.}$$

This condition is typically denoted by $\underline{(1-\epsilon)I \preceq U^T S^T S U \preceq (1+\epsilon)I.}$

$$M \preceq N \text{ iff } \forall x \in \mathbb{R}^d \quad \underline{x^T M x} \leq \underline{x^T N x} \quad (\text{Loewner Order})$$

Loewner Ordering

S ϵ -subspace embedding \cup $U^T S^T S U \approx_{\epsilon} I$

Suffices to show that for any $x \in \mathbb{R}^d$,

$$U^T U = I$$

$$(1-\epsilon)\|x\|_2^2 \leq \|S U x\|_2^2 \leq (1+\epsilon)\|x\|_2^2 \implies (1-\epsilon)x^T I x \leq x^T U^T S^T S U x \leq (1+\epsilon)x^T I x.$$

This condition is typically denoted by $(1-\epsilon)I \preceq U^T S^T S U \preceq (1+\epsilon)I$.

$M \preceq N$ iff $\forall x \in \mathbb{R}^d$ $x^T M x \leq x^T N x$ (Loewner Order)

When $(1-\epsilon)N \preceq M \preceq (1+\epsilon)N$, I will write $M \approx_{\epsilon} N$ as shorthand.

$$\begin{aligned}
 & x^T A x && \begin{matrix} x_1, \dots, x_d & \text{eigenvectors of } A \\ c_1, \dots, c_d & \text{coeff. of } x \text{ in eigenvector basis} \end{matrix} && \sum c_i^2 = \|x\|_2^2 \\
 & (c_1 x_1 + \dots + c_d x_d)^T A (c_1 x_1 + \dots + c_d x_d) && \leq (1+\epsilon) \\
 & \sum_i \sum_j c_i c_j \underbrace{x_i^T A x_j}_{x_i^T \lambda_j x_j} && = \sum_i c_i^2 \underbrace{x_i^T A x_i}_{\lambda_i} \\
 & && \leq \frac{1}{\epsilon} \sum_i c_i^2 \cdot (1+\epsilon) = (1+\epsilon) \sum c_i^2 = (1+\epsilon) \|x\|_2^2
 \end{aligned}$$

Loewner Ordering

$$\lambda_{\max}(U^T S^T S U) = \max_x \frac{x^T U^T S^T S U x}{x^T x} \quad \text{and} \quad \lambda_{\min}(U^T S^T S U) = \min_x \frac{x^T U^T S^T S U x}{x^T x}$$

$I x = x \implies$ All eigenvalues of I are one.

Suffices to show that for any $x \in \mathbb{R}^d$,

$$(1-\epsilon)\|x\|_2^2 \leq \|S U x\|_2^2 \leq (1+\epsilon)\|x\|_2^2 \implies (1-\epsilon)x^T I x \leq x^T U^T S^T S U x \leq (1+\epsilon)x^T I x.$$

This condition is typically denoted by $(1-\epsilon)I \preceq U^T S^T S U \preceq (1+\epsilon)I$.

$$M \preceq N \text{ iff } \forall x \in \mathbb{R}^d \quad x^T M x \leq x^T N x \quad (\text{Loewner Order})$$

When $(1-\epsilon)N \preceq M \preceq (1+\epsilon)N$, I will write $M \approx_\epsilon N$ as shorthand.

$(1-\epsilon)I \preceq U^T S^T S U \preceq (1+\epsilon)I$ is equivalent to all eigenvalues of $U^T S^T S U$ lying in $[1-\epsilon, 1+\epsilon]$.

eigenval of $U^T S^T S U$ $x_i^T U^T S^T S U x_i$ where x_i is an eigenvector

$\approx x_i^T I x_i \approx 1$

$(A) \implies (B)$ $(B) \overset{?}{\implies} (A)$ for any x , $x^T U^T S^T S U x = \underbrace{(c_1 x_1 + c_2 x_2 + \dots + c_n x_n)^T}_{U^T S^T S U (c_1 x_1 + \dots + c_n x_n)}$

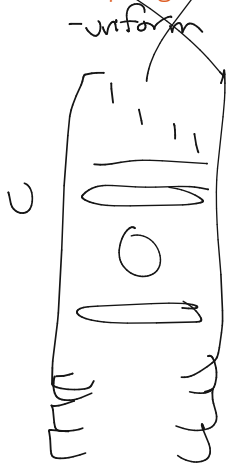
Sampling from U

So Far: We have an orthonormal matrix $U \in \mathbb{R}^{n \times d}$ and we want to sample rows so that $\underbrace{U^T S^T S U}_{\approx_{\epsilon} I} = U^T U$

$$A = U \Sigma V^T$$

Sampling from U

So Far: We have an orthonormal matrix $U \in \mathbb{R}^{n \times d}$ and we want to sample rows so that $U^T S^T S U \approx I$. What are some possible sampling strategies?



$$U^T S^T S U = I$$

- proportion \propto to $\|U_{:,i}\|_2^2$

in this case need to take at least $O(d \log d)$ by coupon collector

doing in streaming is hard



Leverage Score Sampling

- $\tau_i = \underline{\|U_{i,:}\|_2^2}$ is known as the i^{th} leverage score of U . ^(of A)

Leverage Score Sampling

- $\tau_i = \|U_{i,:}\|_2^2$ is known as the i^{th} leverage score of U .

- Let $p_i = \frac{\tau_i}{\sum_{i=1}^n \tau_i}$.

- Let $S_{:,j} = e_i^T \cdot \frac{1}{\sqrt{mp_i}}$ with probability p_i . $S \in \mathbb{R}^{m \times n}$

A handwritten diagram illustrating the sampling process. It shows a large square representing a matrix S . Inside the square, the letter S is written. A circle is drawn around a specific element in the matrix, and the label i/p_i is written inside the circle.

Leverage Score Sampling

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$$\mathcal{U}^T S^T S U \approx \mathcal{U} \quad \|S U x\| \approx \|x\|$$

$$\mathbb{E}[\underline{U^T S^T S U}] =$$

Leverage Score Sampling

- $\tau_i = \|U_{i,:}\|_2^2$ is known as the i^{th} **leverage score** of U .
- Let $p_i = \frac{\tau_i}{\sum_{i=1}^n \tau_i}$.
- Let $S_{:,j} = e_i^T \cdot \frac{1}{\sqrt{mp_i}}$ with probability p_i .


$$\mathbb{E}[U^T S^T S U] = \sum_{j=1}^m \mathbb{E}[U^T S_{:,j}^T S_{:,j} U]$$

Handwritten diagram illustrating the matrix dimensions and structure of the expectation formula. The matrix $U^T S^T S U$ is shown with dimensions d (rows) and n (columns). The matrix is partitioned into m columns, each of size n . A bracket under the columns is labeled with the sum $\sum_{j=1}^m S_{:,j}^T S_{:,j}$.

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$$\begin{aligned}
 \mathbb{E}[U^T S^T S U] &= \sum_{j=1}^m \mathbb{E}[U^T S_{:,j}^T S_{:,j} U] \\
 &= \sum_{j=1}^m \sum_{i=1}^n p_i \cdot \underbrace{\left(\frac{1}{\sqrt{mp_i}} U_{i,:}^T \right)}_{\substack{[d] \\ \downarrow \\ j_{i,i}}} \underbrace{\left(\frac{1}{\sqrt{mp_i}} U_{i,:} \right)}_{[d]}
 \end{aligned}$$



Leverage Score Sampling

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- Let $S_{:,j} = e_i^T \cdot \frac{1}{\sqrt{mp_i}}$ with probability p_i .

works for any p_i

$$\begin{aligned}
 \mathbb{E}[U^T S^T S U] &= \sum_{j=1}^m \mathbb{E}[U^T \overbrace{S_{:,j}^T}^{\text{should be } S_{:,j}^T S_{:,j}} S_{:,j} U] \\
 &= \sum_{j=1}^m \sum_{i=1}^n p_i \cdot \left(\frac{1}{\sqrt{mp_i}} U_{i,:}^T \right) \left(\frac{1}{\sqrt{mp_i}} U_{i,:} \right) = \sum_{j=1}^m \frac{1}{m} \underbrace{\sum_{i=1}^n U_{i,:}^T U_{i,:}}_{U^T U} \\
 &= \sum_{j=1}^m \frac{1}{m} U^T U = \underline{I} = U^T U
 \end{aligned}$$

$$\frac{1}{mp_i} U_{i,:}^T U_{i,:}$$

Matrix Concentration

$$U^T U = I$$

$$A, B \quad V^T A V, V^T B V$$

where V is

We want to show that $U^T S^T S U$ is close to $\mathbb{E}[U^T S^T S U] = I$. Need to apply a **matrix concentration bound**.

$$\lambda_{\max}(M) = \lambda_{\max}(I) = 1$$

Theorem (Matrix Chernoff Bound)

Consider independent symmetric random matrices

$$V \lambda_1 V^T, \dots, V \lambda_2 V^T$$

$X_1, \dots, X_m \in \mathbb{R}^{d \times d}$, with $X_i \succeq 0$, $\lambda_{\max}(X_i) \leq R$, and $X = \sum_{i=1}^m X_i$. Let

$M = \mathbb{E}[X]$. Then: $x^T X_i x \geq 0 \quad \forall x$

$$\Pr[\lambda_{\min}(X) \leq (1 - \epsilon)\lambda_{\min}(M)] \leq d \cdot \left[\frac{e^{-\epsilon}}{(1 - \epsilon)^{1-\epsilon}} \right]^{\lambda_{\min}(M)/R}$$

$$\Pr[\lambda_{\max}(X) \geq (1 + \epsilon)\lambda_{\max}(M)] \leq d \cdot \left[\frac{e^{\epsilon}}{(1 + \epsilon)^{1+\epsilon}} \right]^{\lambda_{\max}(M)/R}$$

$$X_i = \begin{cases} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} & \text{w.p. } 1/6 \\ \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix} & \text{w.p. } 1/6 \\ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} & \text{w.p. } 2/3 \end{cases}$$

Matrix Concentration Applied to Leverage Score Sampling

Theorem (Matrix Chernoff Bound)

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$$\Pr \left[\lambda_{\max}(\mathbf{X}) \geq (1 + \epsilon) \lambda_{\max}(M) \right] \leq d \cdot \left[\frac{e^\epsilon}{(1 + \epsilon)^{1+\epsilon}} \right]^{\lambda_{\min}(M)/R}$$

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- In our setting, $\mathbf{X}_i = U^T \mathbf{S}_{:,j}^T \mathbf{S}_{:,j} U$. $\mathbf{X}_i = \frac{1}{mp_j} \underbrace{U_{i,:}^T U_{i,:}}_{\left[\begin{smallmatrix} \epsilon \\ \end{smallmatrix} \right]}$ with probability p_j .

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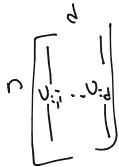
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• In our setting, $X_i = U^T S_{:,j}^T S_{:,j} U$. $X_i = \frac{1}{m p_i} U_{i,:}^T U_{i,:}$ with probability p_i .

• $M = \mathbb{E}[X] = I = U^T U$

• $R = \frac{\|u_i\|_2^2}{m p_i} = \frac{\|y\|_2^2}{m \cdot \frac{\|u_i\|_2^2}{\sum \|u_j\|_2^2}} = \frac{1}{m} \cdot \underbrace{\sum_{j=1}^n \|u_j\|_2^2}_{\|U\|_F^2} = \frac{1}{m} \|U\|_F^2 = \frac{d}{m}$



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• $M = \mathbb{E}[\mathbf{X}] = \mathbf{I}$

• $R = \frac{d}{m}$

• $\Pr[U^T \mathbf{S}^T \mathbf{S} U \succeq (1 + \epsilon) \mathbf{I}] \leq d \cdot \left[\frac{e^\epsilon}{(1 + \epsilon)^{1 + \epsilon}} \right]^{m/d}$

$$\Pr[\lambda_{\max}(U^T \mathbf{S}^T \mathbf{S} U) \geq (1 + \epsilon)] \lesssim d \cdot \left[\frac{e^\epsilon}{e^{\epsilon(1 + \epsilon)}} \right]^{m/d} = \underline{d \cdot e^{-\epsilon^2 m/d}}$$

$(1 + \epsilon) \approx e^\epsilon$
 $(1 + \epsilon)^{1 + \epsilon} \approx e$

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- $M = \mathbb{E}[\mathbf{X}] =$
- $R =$
- $\Pr[U^T \mathbf{S}^T \mathbf{S} U \succeq (1 + \epsilon)I] \leq d \cdot \left[\frac{e^\epsilon}{(1 + \epsilon)^{1+\epsilon}} \right]^{m/d} \lesssim d \cdot e^{-\epsilon^2 \cdot m/d}$

Matrix Concentration Applied to Leverage Score Sampling

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$\mathbf{X}_1, \dots, \mathbf{X}_m \in \mathbb{R}^{d \times d}$, with $\mathbf{X}_i \succeq 0$, $\lambda_{\max}(\mathbf{X}_i) \leq R$, and $\mathbf{X} = \sum_{i=1}^m \mathbf{X}_i$. Let $M = \mathbb{E}[\mathbf{X}]$. Then:

$$\Pr[\lambda_{\max}(\mathbf{X}) \geq (1 + \epsilon)\lambda_{\max}(M)] \leq d \cdot \left[\frac{e^\epsilon}{(1 + \epsilon)^{1+\epsilon}} \right]^{\lambda_{\min}(M)/R}$$

• In our setting, $\mathbf{X}_i = U^T \mathbf{S}_{:,j}^T \mathbf{S}_{:,j} U$. $\mathbf{X}_i = \frac{1}{mp_i} U_{i,:}^T U_{i,:}$ with probability p_i .

• $M = \mathbb{E}[\mathbf{X}] =$

• $R =$

• $\Pr[U^T \mathbf{S}^T \mathbf{S} U \succeq (1 + \epsilon)I] \leq d \cdot \left[\frac{e^\epsilon}{(1 + \epsilon)^{1+\epsilon}} \right]^{m/d} \lesssim d \cdot e^{-\epsilon^2 \cdot m/d}$

• If we set $m = O\left(\frac{d \log(d/\delta)}{\epsilon^2}\right)$ we have $\Pr[U^T \mathbf{S}^T \mathbf{S} U \succeq (1 + \epsilon)I] \leq \delta$.

$$m = \sqrt{d \log d}$$

$$\leq d \cdot e^{-\log(d/\delta)} = d \cdot \frac{\delta}{d}$$

Subspace Embedding via Sampling

Theorem (Subspace Embedding via Leverage Score Sampling)

For any $A \in \mathbb{R}^{n \times d}$ with ^{orthonormal} left singular vector matrix U , let

$\tau_i = \|U_{i,:}\|_2^2$ and $p_i = \frac{\tau_i}{\sum \tau_j}$. Let $S \in \mathbb{R}^{m \times n}$ have $S_{:,j}$ independently set to $\frac{1}{\sqrt{mp_i}} \cdot e_i^T$ with probability p_i .

Then, if $m = O\left(\frac{d \log(d/\delta)}{\epsilon^2}\right)$, with probability $\geq 1 - \delta$, S is an ϵ -subspace embedding for A .

Subspace Embedding via Sampling

$$\begin{bmatrix} \pm 1/\sqrt{m} & \pm 1/\sqrt{m} \\ \vdots & \vdots \\ \pm 1/\sqrt{m} & \pm 1/\sqrt{m} \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} = \begin{bmatrix} \pm 1/\sqrt{m} & \pm 1/\sqrt{m} \\ \vdots & \vdots \\ \pm 1/\sqrt{m} & \pm 1/\sqrt{m} \end{bmatrix}$$

Theorem (Subspace Embedding via Leverage Score Sampling)

For any $A \in \mathbb{R}^{n \times d}$ with left singular vector matrix U , let $\tau_i = \|U_{i,:}\|_2^2$ and $p_i = \frac{\tau_i}{\sum \tau_j}$. Let $S \in \mathbb{R}^{m \times n}$ have ~~diag~~ $S_{j,i}$ independently set to $\frac{1}{\sqrt{mp_i}} \cdot e_i^T$ with probability p_i .

Then, if $m = O\left(\frac{d \log(d/\delta)}{\epsilon^2}\right)$, with probability $\geq 1 - \delta$, S is an ϵ -subspace embedding for A .

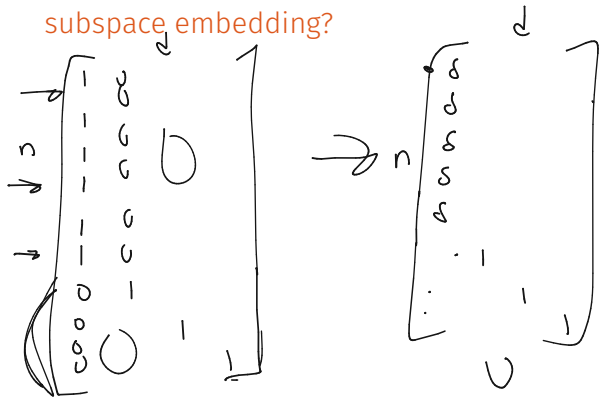
Matches oblivious random projection up to the $\log d$ factor.

$$m = O\left(\frac{d + \log(1/\delta)}{\epsilon^2}\right)$$

Leverage Score Intuition

Check-In

Check-in Question: Would row-norm sampling from A directly rather than its left singular vectors U have worked to give a subspace embedding?



$$A_{:i}^T A_{:j} = 0 \\ i \neq j$$

Variational Characterization of Leverage Scores

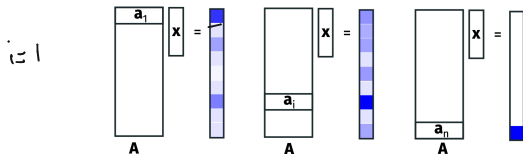
For a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = U\Sigma V^T$, the i^{th} leverage score is given by $\tau_i(A) = \underbrace{\|U_{i,:}\|_2^2}$.

Variational Characterization of Leverage Scores

For a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = U\Sigma V^T$, the i^{th} leverage score is given by $\tau_i(A) = \|U_{i,:}\|_2^2$. Consider the maximization problem:

$$\max_{x \in \mathbb{R}^d} \frac{[Ax](i)^2}{\|Ax\|_2^2}.$$

How much can a vector in A 's column span 'spike' at position i .

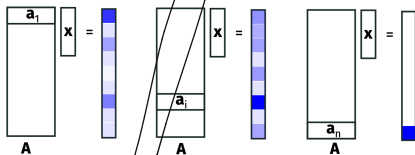


Variational Characterization of Leverage Scores

For a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = U\Sigma V^T$, the i^{th} leverage score is given by $\tau_i(A) = \|U_{i,:}\|_2^2$. Consider the maximization problem:

$$\max_{x \in \mathbb{R}^d} \frac{[Ax](i)^2}{\|Ax\|_2^2}. \quad Ax \quad Uz$$

How much can a vector in A 's column span 'spike' at position i .



Can rewrite this problem as:

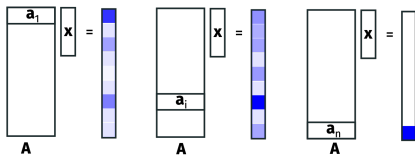
$$\max_{z: \|z\|_2=1} \frac{[Uz](i)^2}{\|Uz\|_2^2}$$

Variational Characterization of Leverage Scores

For a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = U\Sigma V^T$, the i^{th} leverage score is given by $\tau_i(A) = \|U_{i,:}\|_2^2$. Consider the maximization problem:

$$\max_{x \in \mathbb{R}^d} \frac{[Ax](i)^2}{\|Ax\|_2^2}.$$

How much can a vector in A 's column span 'spike' at position i .



Can rewrite this problem as:

$$\max_{z: \|z\|_2=1} \frac{[Uz](i)^2}{\|Uz\|_2^2} = [Uz](i)^2.$$

Variational Characterization of Leverage Scores

For a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = U\Sigma V^T$, the i^{th} leverage score is given by $\tau_i(A) = \|U_{i,:}\|_2^2$. Consider the maximization problem:

$$\max_{x \in \mathbb{R}^d} \frac{[Ax](i)^2}{\|Ax\|_2^2}.$$

How much can a vector in A 's column span 'spike' at position i .

Can rewrite this problem as:

$$\max_{z: \|z\|_2=1} \frac{[Uz](i)^2}{\|Uz\|_2^2} = [Uz](i)^2 = \langle U_{i,:}, z \rangle^2$$

What z maximizes this value?

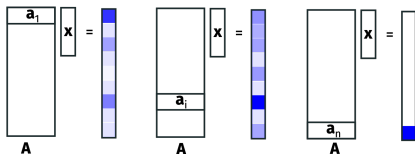
$$z = \frac{U_{i,:}}{\|U_{i,:}\|_2}$$

Variational Characterization of Leverage Scores

For a matrix $A \in \mathbb{R}^{n \times d}$ with SVD $A = U\Sigma V^T$, the i^{th} leverage score is given by $\tau_i(A) = \|U_{i,:}\|_2^2$. Consider the maximization problem:

$$\tau_i(A) = \max_{x \in \mathbb{R}^d} \frac{[Ax](i)^2}{\|Ax\|_2^2}$$

How much can a vector in A 's column span 'spike' at position i .



Can rewrite this problem as:

$$\max_{z: \|z\|_2=1} \frac{[Uz](i)^2}{\|Uz\|_2^2} = [Uz](i)^2 \approx \|U_{i,:}\|_2^2$$

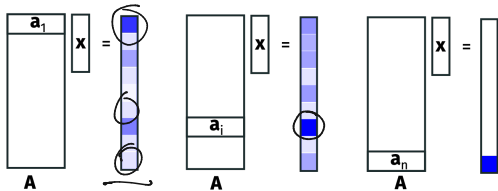
What z maximizes this value?

Variational Characterization of Leverage Scores

sensitivity

$$0 \leq \tau_i(A) \leq 1$$

$$\tau_i(A) = \max_{x \in \mathbb{R}^d} \frac{[Ax](i)^2}{\|Ax\|_2^2}$$



- Use Bernstein bound show that

$$\|Ax\| \approx \|SAx\|$$

u.h.p

- take a net over unit x norm

- Remember that we want $\|SAx\|_2^2 \approx \|Ax\|_2^2$ for all $x \in \mathbb{R}^d$.

The leverage scores ensure that we sample all Ax with high enough probability to well approximate $\|Ax\|_2^2$.

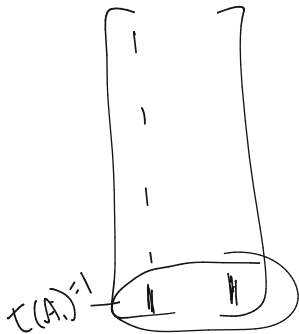
- In fact, could prove the subspace embedding theorem by showing that for a fixed $x \in \mathbb{R}^d$, $\|SAx\|_2^2 \approx \|Ax\|_2^2$, and then applying a net argument + union bound. Although you would lose a factor d over the optimal bound.

Leverage Score Intuition

- When a_i is not spanned by the other rows of A , $\tau_i(A) = 1$.

$$\max_x \frac{(Ax)_i^2}{\|Ax\|_2^2}$$

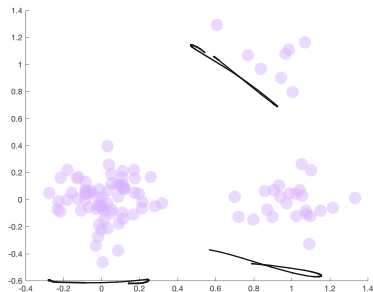
$$x = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad Ax = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$



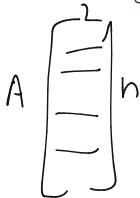
Leverage Score Intuition

- When a_j is not spanned by the other rows of A , $\tau_i(A) = 1$.
- $\tau_i(A)$ is small when many rows are similar to a_j .

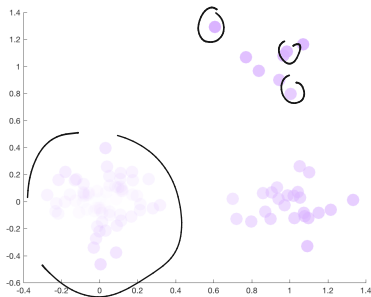
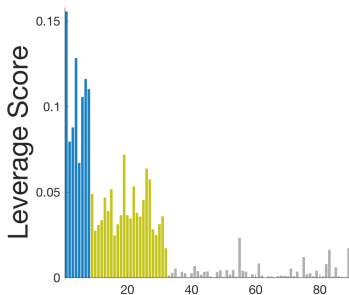
Leverage Score Intuition



- Leverage scores are a 'smooth' indicator of cluster structure.

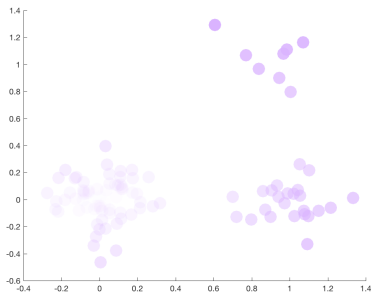
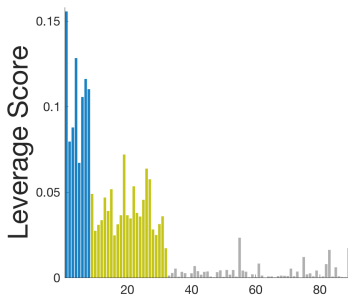


Leverage Score Intuition



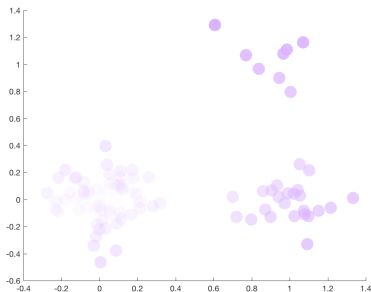
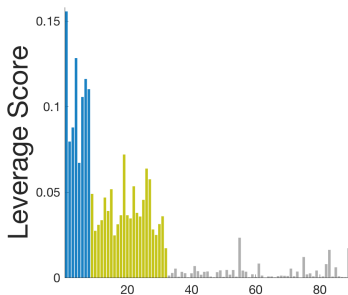
- Leverage scores are a 'smooth' indicator of cluster structure.

Leverage Score Intuition



- Leverage scores are a 'smooth' indicator of cluster structure.
- Very high leverage scores tend to correspond to outliers – original motivation for use in statistics.

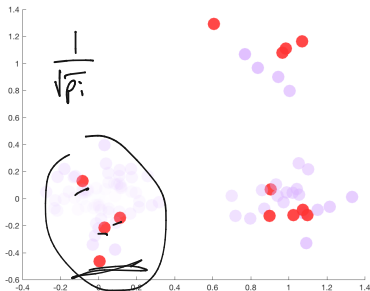
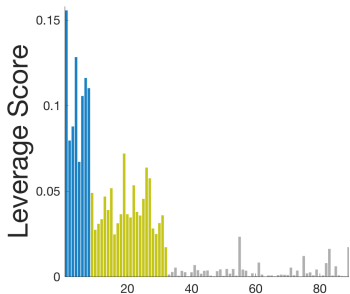
Leverage Score Intuition



- Leverage scores are a ‘smooth’ indicator of cluster structure.
- Very high leverage scores tend to correspond to outliers – original motivation for use in statistics.
- When used as sampling probabilities, give a more ‘balanced sample’ than uniform sampling.

Leverage Score Intuition

0

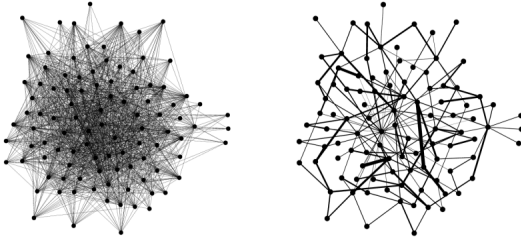


- Leverage scores are a 'smooth' indicator of cluster structure.
- Very high leverage scores tend to correspond to outliers – original motivation for use in statistics.
- When used as sampling probabilities, give a more 'balanced sample' than uniform sampling.

Spectral Graph Sparsification

Graph Sparsification

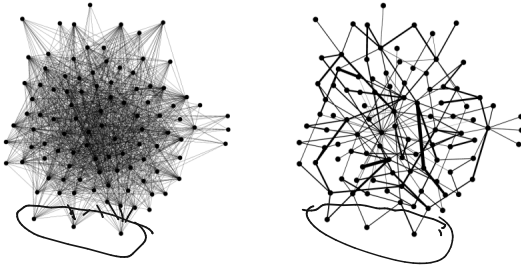
Given a graph $G = (V, E)$, find a (weighted) subgraph G' with many fewer edges that approximates various properties of G .¹



¹Image taken from Nick Harvey's notes <https://www.cs.ubc.ca/~nickhar/W15/Lecture11Notes.pdf>.

Graph Sparsification

Given a graph $G = (V, E)$, find a (weighted) subgraph G' with many fewer edges that approximates various properties of G .¹



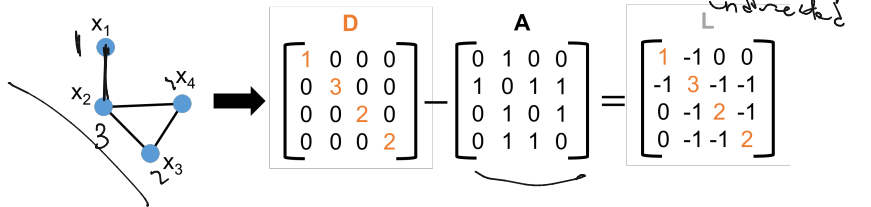
Cut Sparsifier: (Karger) For any set of nodes S ,

$$\text{CUT}'(S, \sum_{i \in S} w_i) \approx_{\epsilon} \text{CUT}(S, \sum_{i \in S} w_i).$$

¹Image taken from Nick Harvey's notes <https://www.cs.ubc.ca/~nickhar/W15/Lecture11Notes.pdf>.

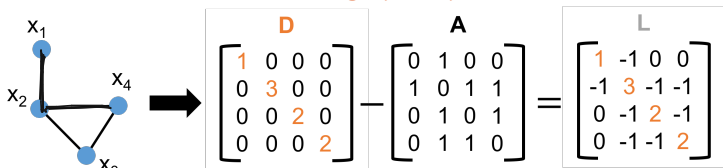
The Graph Laplacian

For a graph with adjacency matrix $A \in \{0, 1\}^{n \times n}$ and diagonal degree matrix $D \in \mathbb{R}^{n \times n}$, $L = D - A$ is the **graph Laplacian**.



The Graph Laplacian

For a graph with adjacency matrix $A \in \{0, 1\}^{n \times n}$ and diagonal degree matrix $D \in \mathbb{R}^{n \times n}$, $L = D - A$ is the **graph Laplacian**.



L can be written as $\underline{L} = \sum_{(u,v) \in E} \underline{L}_{u,v}$ where $L_{u,v}$ is an 'edge Laplacian'

$$\underline{L} = \underline{L}_{1,2} + \underline{L}_{2,4} + \dots$$

The diagram shows the decomposition of the Laplacian matrix L into edge Laplacians $L_{u,v}$.

The edge Laplacian $L_{1,2}$ is:

$$\underline{L}_{1,2} = \begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The edge Laplacian $L_{2,4}$ is:

$$\underline{L}_{2,4} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

Laplacian Smoothness

Observation 1: For any $z \in \mathbb{R}^d$,

$$\underline{z^T L z} = \sum_{(u,v) \in E} \underline{z^T L_{u,v} z}$$

| | | |
|---|--|--|
| $\begin{bmatrix} z(1) & z(2) & z(3) & z(4) \end{bmatrix}$ | $\begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ | $\begin{bmatrix} z(1) \\ z(2) \\ z(3) \\ z(4) \end{bmatrix}$ |
|---|--|--|

$$z(u)^2 + z(v)^2 + z(u) \cdot z(v) \cdot -2$$

$$(z(u) - z(v))^2$$

Laplacian Smoothness

Observation 1: For any $z \in \mathbb{R}^d$, *difference of z across edge (u,v)*

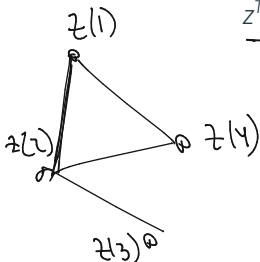
$$z^T L z = \sum_{(u,v) \in E} z^T L_{u,v} z = \sum_{(u,v) \in E} (z(u) - z(v))^2.$$

| | | | | | | | | |
|--------|--------|--------|--------|------|------|-----|-----|--------|
| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ | 1 | -1 | 0 | 0 | $v(1)$ |
| | | | | -1 | 1 | 0 | 0 | $v(2)$ |
| | | | | 0 | 0 | 0 | 0 | $v(3)$ |
| | | | | 0 | 0 | 0 | 0 | $v(4)$ |

Laplacian Smoothness

Observation 1: For any $z \in \mathbb{R}^d$,

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| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ |
|--------|--------|--------|--------|
| 1 | -1 | 0 | 0 |
| -1 | 1 | 0 | 0 |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 0 |

| |
|--------|
| $v(1)$ |
| $v(2)$ |
| $v(3)$ |
| $v(4)$ |

- $z^T L z$ measures how smoothly z varies across the graph.

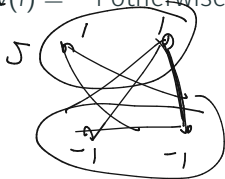
Laplacian Smoothness

Observation 1: For any $z \in \mathbb{R}^d$,

$$z^T L z = \sum_{(u,v) \in E} z^T L_{u,v} z = \sum_{(u,v) \in E} (z(i) - z(j))^2.$$

| | | | | | | | | | | |
|--------|--------|--------|--------|--|------|------|-----|-----|--|--------|
| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ | | 1 | -1 | 0 | 0 | | $v(1)$ |
| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ | | -1 | 1 | 0 | 0 | | $v(2)$ |
| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ | | 0 | 0 | 0 | 0 | | $v(3)$ |
| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ | | 0 | 0 | 0 | 0 | | $v(4)$ |

- $z^T L z$ measures how smoothly z varies across the graph.
- If $z \in \{-1, 1\}^n$ is a **cut indicator vector** with $z(i) = 1$ for $i \in S$ and $z(i) = -1$ otherwise, then $z^T L z = 4 \cdot \text{CUT}(S, V \setminus S)$.



$$(z(u) - z(v))^2 = (1 - (-1))^2 = 4$$

Laplacian Smoothness

Observation 1: For any $z \in \mathbb{R}^d$,

$$z^T L z = \sum_{(u,v) \in E} z^T L_{u,v} z = \sum_{(u,v) \in E} (z(i) - z(j))^2.$$

| | | | | | | | | | | |
|--------|--------|--------|--------|--|------|------|-----|-----|--|--------|
| $v(1)$ | $v(2)$ | $v(3)$ | $v(4)$ | | 1 | -1 | 0 | 0 | | $v(1)$ |
| | | | | | -1 | 1 | 0 | 0 | | $v(2)$ |
| | | | | | 0 | 0 | 0 | 0 | | $v(3)$ |
| | | | | | 0 | 0 | 0 | 0 | | $v(4)$ |

- $z^T L z$ measures how smoothly z varies across the graph.
- If $z \in \{-1, 1\}^n$ is a **cut indicator vector** with $v(i) = 1$ for $i \in S$ and $v(i) = -1$ otherwise, then $z^T L z = 4 \cdot \text{CUT}(S, V \setminus S)$.
- So G' with (weighted) Laplacian $L' \approx_\epsilon L$ will be a cut sparsifier, with $\text{CUT}'(S, S \setminus T) \approx_\epsilon \text{CUT}(S, S \setminus T)$ for all S .

$$(1-\epsilon)L \preceq L' \preceq (1+\epsilon)L$$

Laplacian Smoothness

Observation 1: For any $z \in \mathbb{R}^d$,

$$z^T L z = \sum_{(u,v) \in E} z^T L_{u,v} z = \sum_{(u,v) \in E} (z(i) - z(j))^2.$$

| | | | |
|------|------|------|------|
| v(1) | v(2) | v(3) | v(4) |
|------|------|------|------|

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v(1) \\ v(2) \\ v(3) \\ v(4) \end{bmatrix}$$

$$z^T L z \approx z^T L' z$$

- $z^T L z$ measures how smoothly z varies across the graph.
- If $z \in \{-1, 1\}^n$ is a **cut indicator vector** with $v(i) = 1$ for $i \in S$ and $v(i) = -1$ otherwise, then $z^T L z = 4 \cdot \text{CUT}(S, V \setminus S)$.
- So G' with (weighted) Laplacian $L' \approx_\epsilon L$ will be a cut sparsifier, with $\text{CUT}'(S, S \setminus T) \approx_\epsilon \text{CUT}(S, S \setminus T)$ for all S .
- Such a G' is called an **ϵ -spectral sparsifier** of G .

Laplacian Factorization

Observation 2: $L_{u,v} = b_{u,v}b_{u,v}^T$

(1) indicate vector for (u,v)

$$L = \sum L_{u,v}$$

$$\begin{matrix} & L_{2,4} \\ \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix} & = & \begin{matrix} b_{2,4} \\ \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix} \end{matrix} \begin{matrix} b_{2,4}^T \\ \boxed{0 \ 1 \ 0 \ -1} \end{matrix} \end{matrix}$$

Laplacian Factorization

Observation 2: $L_{u,v} = b_{u,v}b_{u,v}^T$. So $\underline{L} = \sum_{(u,v) \in E} b_{u,v}b_{u,v}^T$.

$$\begin{array}{c} L_{2,4} \\ \left[\begin{array}{cccc} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{array} \right] \end{array} = \begin{array}{c} b_{2,4} \\ \left[\begin{array}{c} 0 \\ 1 \\ 0 \\ -1 \end{array} \right] \end{array} \begin{array}{c} b_{2,4}^T \\ \left[\begin{array}{cccc} 0 & 1 & 0 & -1 \end{array} \right] \end{array}$$

Laplacian Factorization

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$$\begin{array}{c} L_{2,4} \\ \left[\begin{array}{cccc} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{array} \right] \end{array} = \begin{array}{c} \mathbf{b}_{2,4} \\ \left[\begin{array}{c} 0 \\ 1 \\ 0 \\ -1 \end{array} \right] \end{array} \begin{array}{c} \mathbf{b}_{2,4}^T \\ \left[\begin{array}{cccc} 0 & 1 & 0 & -1 \end{array} \right] \end{array}$$

That is, letting $B \in \mathbb{R}^{m \times n}$ have rows $\{b_{u,v}^T : (u,v) \in E\}$, $L = \underline{B^T B}$.

Laplacian Factorization

Observation 2: $L_{u,v} = b_{u,v}b_{u,v}^T$. So $L = \sum_{(u,v) \in E} b_{u,v}b_{u,v}^T$.

$$\begin{array}{c}
 \mathbf{L}_{2,4} \\
 \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}
 \end{array}
 =
 \begin{array}{c}
 \mathbf{b}_{2,4} \\
 \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}
 \end{array}
 \begin{array}{c}
 \mathbf{b}_{2,4}^T \\
 \boxed{0 \ 1 \ 0 \ -1}
 \end{array}$$

| | | | |
|----|----|----|----|
| 1 | -1 | 0 | 0 |
| 0 | 1 | 0 | -1 |
| 0 | 0 | 1 | -1 |
| -1 | 0 | 1 | 0 |
| 1 | 0 | -1 | 0 |
| 0 | 1 | -1 | 0 |
| 1 | 0 | 0 | -1 |
| 0 | 0 | 1 | -1 |

vertex-edge
incidence matrix B

That is, letting $B \in \mathbb{R}^{m \times n}$ have rows $\{b_{u,v}^T : (u,v) \in E\}$, $L = B^T B$.

Laplacian Factorization

Observation 2: $L_{u,v} = b_{u,v}b_{u,v}^T$. So $L = \sum_{(u,v) \in E} b_{u,v}b_{u,v}^T$.

G is connected
 G is not connected
 $\exists v$ s.t. $V^T G V = 0$
 $\exists v$ s.t. $V^T G V \neq 0$
 $\exists v$ s.t. $(1-c)V^T G V > 0$

$$L_{2,4} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

$$b_{2,4} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}$$

$$b_{2,4}^T = \begin{bmatrix} 0 & 1 & 0 & -1 \end{bmatrix}$$

| | | | |
|----|----|----|----|
| 1 | -1 | 0 | 0 |
| 0 | 1 | 0 | -1 |
| 0 | 0 | 1 | -1 |
| -1 | 0 | 1 | 0 |
| 1 | 0 | -1 | 0 |
| 0 | 1 | -1 | 0 |
| 1 | 0 | 0 | -1 |
| 0 | 0 | 1 | -1 |

vertex-edge incidence matrix B

$$\begin{bmatrix} 1 & -1 \\ 2 & -1 \\ 3 & 0 & 0 \end{bmatrix}$$

That is, letting $B \in \mathbb{R}^{m \times n}$ have rows $\{b_{u,v}^T : (u,v) \in E\}$, $L = B^T B$.

- So if a sampling matrix S is a subspace embedding for B , then $B^T S^T S B \approx_\epsilon B^T B \approx_\epsilon L$. I.e., $S B$ is the weighted vertex-edge incidence matrix of an ϵ -spectral sparsifier of G .
- By our results on subspace embedding, every graph G has an ϵ -spectral sparsifier with just $O(n \log n / \epsilon^2)$ edges.

Some History

- The concept of spectral sparsification was first introduced by Spielman and Teng '04 in their seminal work on fast system solvers for graph Laplacians. In this work, sparsifiers are used as preconditioners (like in Problem Set 3).
- Spielman and Srivastava '08 showed how to construct sparsifiers with $O(n \log n / \epsilon^2)$ edges via effective resistance (leverage score) sampling.
- Batson, Spielman, and Srivastava '08 showed how to achieve $O(n / \epsilon^2)$ edges with a deterministic algorithm.
- Marcus, Spielman, and Srivastava '13 built on this work to give optimal bipartite expanders with any degree and to resolve the famous Kadison-Singer problem in functional analysis.