

COMPSCI 514: ALGORITHMS FOR DATA SCIENCE

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University of Massachusetts Amherst. Fall 2021.

Lecture 22

- Problem Set 4 due December 1.
- No quiz this week.
- We're going to start on optimization after break. And just cover a bit less material.

Last Class:

- Efficient algorithms for SVD/eigendecomposition.
- Start on iterative methods: intuition behind the power method.

This Class:

- Finish power method analysis.
- Krylov subspace methods.
- Connections to random walks and Markov chains.

Power Method: The most fundamental iterative method for approximate SVD/eigendecomposition. Applies to computing $k = 1$ eigenvectors, but can be generalized to larger k .

$X^T X$

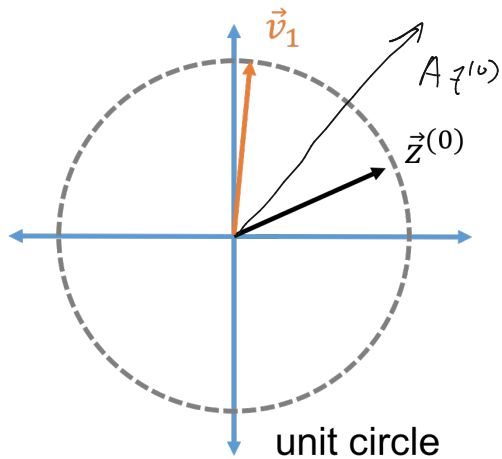
Goal: Given symmetric $A \in \mathbb{R}^{d \times d}$, with eigendecomposition $A = V \Lambda V^T$, find $\bar{z} \approx \bar{v}_1$ – the top eigenvector of A .

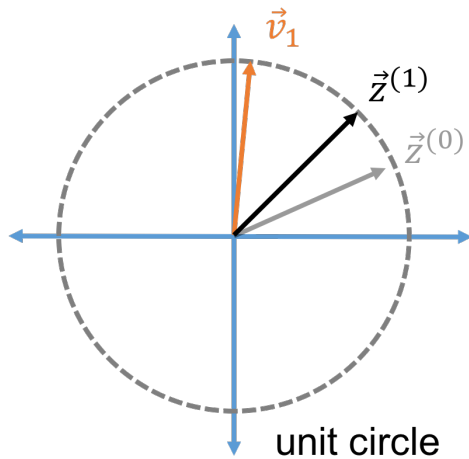
- **Initialize:** Choose $\bar{z}^{(0)}$ randomly. E.g. $\bar{z}^{(0)}(i) \sim \mathcal{N}(0, 1)$.

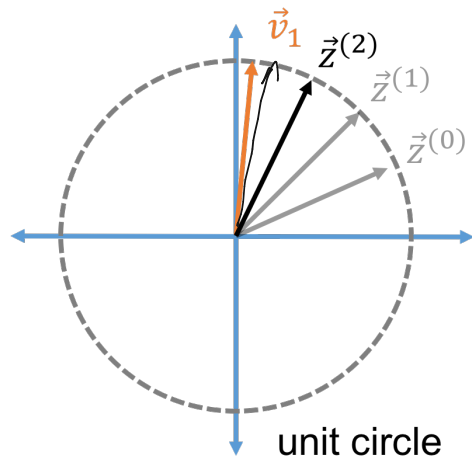
- For $i = 1, \dots, t$
 - $\bar{z}^{(i)} := A \cdot \bar{z}^{(i-1)}$
 - $\bar{z}_0^{(i)} := \frac{\bar{z}^{(i)}}{\|\bar{z}^{(i)}\|_2}$

Return $\bar{z}_0^{(t)}$

compute $\bar{z}^{(t)} = A \bar{z}^{(0)}$
 equivalent code $\bar{z}^{(t)} = \frac{\bar{z}^{(t)}}{\|\bar{z}^{(t)}\|_2}$







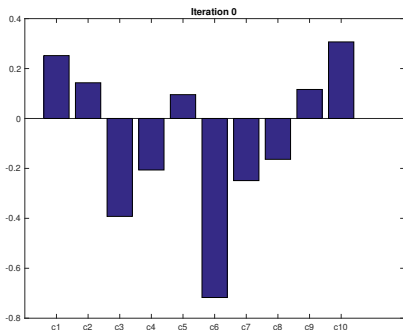
POWER METHOD CONVERGENCE

After t iterations, we have 'powered' up the eigenvalues, making the component in the direction of v_1 much larger, relative to the other components.

$$A_{(b)}^{(t)}$$

$$\underline{\bar{z}}^{(0)} = c_1 \underline{\vec{v}}_1 + c_2 \underline{\vec{v}}_2 + \dots + c_d \underline{\vec{v}}_d \implies \underline{\bar{z}}^{(t)} = c_1 \lambda_1^t \underline{\vec{v}}_1 + c_2 \lambda_2^t \underline{\vec{v}}_2 + \dots + c_d \lambda_d^t \underline{\vec{v}}_d$$

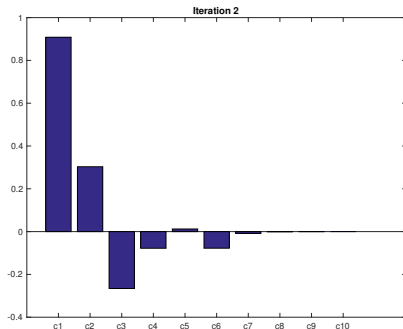
$$\lambda_1^t > \lambda_i^t \text{ for all } i > 1.$$



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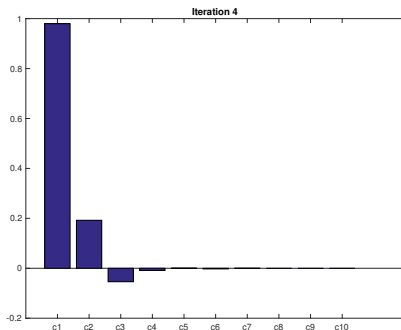
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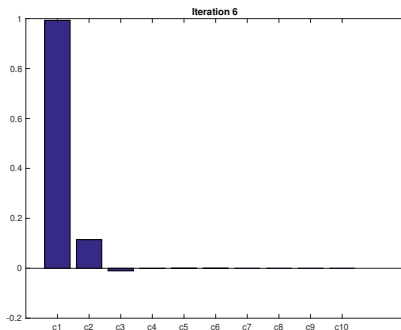
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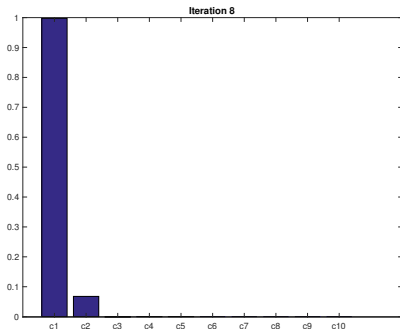
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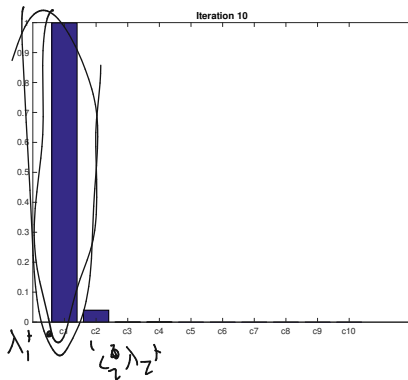
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$$\vec{z}^{(0)} = c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_d\vec{v}_d \implies \vec{z}^{(t)} = \underbrace{c_1\lambda_1^t}_{\text{dominant}}\vec{v}_1 + \underbrace{c_2\lambda_2^t}_{\text{smaller}}\vec{v}_2 + \dots + \underbrace{c_d\lambda_d^t}_{\text{smallest}}\vec{v}_d$$



$$\lambda_2 \approx \lambda_1$$

POWER METHOD CONVERGENCE RATE

$$\vec{z}^{(0)} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_d \vec{v}_d \Rightarrow \vec{z}^{(t)} = \underbrace{c_1 \lambda_1^t \vec{v}_1}_{\sim \vec{v}_1} + c_2 \lambda_2^t \vec{v}_2 + \dots + c_d \lambda_d^t \vec{v}_d$$

Write $|\lambda_2| = (1 - \gamma) |\lambda_1|$ for 'gap' $\gamma = \frac{|\lambda_1| - |\lambda_2|}{|\lambda_1|}$.

How many iterations t does it take to have $|\lambda_2|^t \leq \frac{1}{e} \cdot |\lambda_1|^t$?

$$\left((1 - \gamma) |\lambda_1| \right)^t \leq \frac{1}{e} |\lambda_1|^t$$

$$(1 - \gamma)^t < \frac{1}{e} \quad t > 1/\gamma.$$

$$\lim_{x \rightarrow 0} (1-x)^{1/x} = \frac{1}{e}$$

$$\lim_{x \rightarrow 0} (1+x)^{1/x} = e$$

$$1-x \approx \frac{1}{1+x}$$

$$.99 \approx \frac{1}{1.01}$$

Example

$$\gamma = 1/3$$

$$\lambda_2 = \frac{2}{3} \lambda_1$$

$$t = 3$$

$$\lambda_2^3 = \frac{8}{27} \lambda_1^3 \approx \frac{1}{3} \lambda_1^3 \approx \frac{1}{e} \lambda_1^3$$

$A \in \mathbb{R}^{d \times d}$: input matrix with eigendecomposition $A = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^T$. \vec{v}_1 : top eigenvector, being computed, $\vec{z}^{(i)}$: iterate at step i , converging to \vec{v}_1 .

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How many iterations t does it take to have $|\lambda_2|^t \leq \delta \cdot |\lambda_1|^t$?

$$t = O\left(\frac{\ln(1/\delta)}{\gamma}\right)$$

$\ln_{1-\gamma}(d)$

$$|\lambda_2|^{1/\gamma} \leq \frac{1}{e} |\lambda_1|^{1/\gamma}$$
$$\left(|\lambda_2|^{1/\gamma}\right)^{\ln(1/\delta)} \leq \frac{1}{e^{\ln(1/\delta)}} \cdot \left(|\lambda_1|^{1/\gamma}\right)^{\ln(1/\delta)}$$
$$|\lambda_2| \frac{\ln(1/\delta)}{\gamma} \leq \delta |\lambda_1| \frac{\ln(1/\delta)}{\gamma}$$

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Will have for all $i > 1$, $|\lambda_i|^t \leq |\lambda_2|^t \leq \delta \cdot |\lambda_1|^t$.

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Will have for all $i > 1$, $|\lambda_i|^t \leq |\lambda_2|^t \leq \delta \cdot |\lambda_1|^t$.

How small must we set δ to ensure that $c_1 \lambda_1^t$ dominates all other components and so $\vec{z}^{(t)}$ is very close to \vec{v}_1 ?

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RANDOM INITIALIZATION

Claim: When $z^{(0)}$ is chosen with random Gaussian entries, writing $z^{(0)} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_d \vec{v}_d$, with very high probability, for all i :

$$c_1 = \langle \underbrace{\vec{v}_1}_{\downarrow}, z^{(0)} \rangle$$

$$\underline{O(1/d^2)} \leq |c_i| \leq \underline{O(\log d)}$$

Corollary: $z^{(0)} \sim \mathcal{N}(0, I)$

$$\max_j \left| \frac{c_j}{c_1} \right| \leq O(d^2 \log d).$$

$$\frac{\log d}{1/d^2}$$

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Claim 2: For gap $\gamma = \frac{|\lambda_1| - |\lambda_2|}{|\lambda_1|}$, and $t = \frac{\ln(1/\delta)}{\gamma}$, $\left| \frac{\lambda_i^t}{\lambda_1^t} \right| \leq \delta$ for all i .

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$$\|\vec{z}^{(t)} - \vec{v}_1\|_2 \leq \left\| \frac{c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d}{\|c_1 \lambda_1^t \vec{v}_1\|_2} - \vec{v}_1 \right\|_2$$



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$$\| \overbrace{z^{(t)}} - \vec{v}_1 \|_2 \leq \left\| \frac{c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d}{\|c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d\|_2} - \vec{v}_1 \right\|_2$$

$$\frac{c_1 \lambda_1^t \vec{v}_1 = \vec{v}_1}{c_1 \lambda_1^t} = \left\| \frac{c_2 \lambda_2^t}{c_1 \lambda_1^t} \vec{v}_2 + \dots + \frac{c_d \lambda_d^t}{c_1 \lambda_1^t} \vec{v}_d \right\|_2 = c_1 \lambda_1^t \left\| \frac{c_2 \lambda_2^t}{c_1 \lambda_1^t} \vec{v}_2 + \dots + \frac{c_d \lambda_d^t}{c_1 \lambda_1^t} \vec{v}_d \right\|_2$$

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$$\begin{aligned} \vec{z}^{(t)} &:= \frac{c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d}{\|c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d\|_2} \implies \\ \|\vec{z}^{(t)} - \vec{v}_1\|_2 &\leq \left\| \frac{c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d}{\|c_1 \lambda_1^t \vec{v}_1\|_2} - \vec{v}_1 \right\|_2 \\ &= \left\| \frac{c_2 \lambda_2^t}{c_1 \lambda_1^t} \vec{v}_2 + \dots + \frac{c_d \lambda_d^t}{\lambda_1^t} \vec{v}_d \right\|_2 = \underbrace{\left| \frac{c_2 \lambda_2^t}{c_1 \lambda_1^t} \right|}_{\leq \delta} + \dots + \underbrace{\left| \frac{c_d \lambda_d^t}{\lambda_1^t} \right|}_{\leq \delta} \end{aligned}$$

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by random initialization because $t = \frac{\ln(1/\delta)}{\gamma}$

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$$\|\vec{z}^{(t)} - \vec{v}_1\|_2 \leq \left\| \frac{c_1 \lambda_1^t \vec{v}_1 + \dots + c_d \lambda_d^t \vec{v}_d}{\|c_1 \lambda_1^t \vec{v}_1\|_2} - \vec{v}_1 \right\|_2$$

$$= \left\| \frac{c_2 \lambda_2^t}{c_1 \lambda_1^t} \vec{v}_2 + \dots + \frac{c_d \lambda_d^t}{\lambda_1^t} \vec{v}_d \right\|_2 = \left| \frac{c_2 \lambda_2^t}{c_1 \lambda_1^t} \right| + \dots + \left| \frac{c_d \lambda_d^t}{c_1 \lambda_1^t} \right| \leq \delta \cdot O(d^2 \log d) \cdot d.$$

Setting $\delta = O\left(\frac{\epsilon}{d^3 \log d}\right)$ gives $\|\vec{z}^{(t)} - \vec{v}_1\|_2 \leq \epsilon$.

Handwritten notes:
 $t = O\left(\frac{\log(d/\epsilon)}{\gamma}\right)$
 $\log(1/\delta) = \log\left(\frac{d^3 \log d}{\epsilon}\right)$
 $\gamma = O\left(\frac{\log(d/\epsilon)}{d}\right)$

$\mathbf{A} \in \mathbb{R}^{d \times d}$: input matrix with eigendecomposition $\mathbf{A} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^T$. \vec{v}_1 : top eigenvector, being computed, $\vec{z}^{(i)}$: iterate at step i , converging to \vec{v}_1 .

Theorem (Basic Power Method Convergence)

Let $\gamma = \frac{|\lambda_1| - |\lambda_2|}{|\lambda_1|}$ be the relative gap between the first and second eigenvalues. If Power Method is initialized with a random Gaussian vector $\vec{v}^{(0)}$ then, with high probability, after $t = O\left(\frac{\ln(d/\epsilon)}{\gamma}\right)$ steps:

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with A .

Total runtime: $O(t)$ matrix-vector multiplications. [^] If $A = X^T X$:

$$O\left(\underbrace{\text{nnz}(X)} \cdot \underbrace{\frac{\ln(d/\epsilon)}{\gamma}}\right) = O\left(\underbrace{nd} \cdot \underbrace{\left(\frac{\ln(d/\epsilon)}{\gamma}\right)}\right). \quad \underbrace{O(nd^2)}_{\text{full SVD}}$$

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How is ϵ dependence? — super good

How is γ dependence? — not great

Krylov subspace methods (Lanczos method, Arnoldi method.)

- How `svds/eigs` are actually implemented. Only need $t = O\left(\frac{\ln(d/\epsilon)}{\sqrt{\gamma}}\right)$ steps for the same guarantee.

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- Power method: power up to λ_1^t and λ_j^t . $T(x) = x^t$
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- Krylov methods: apply a **better** degree t polynomial $T_t(\cdot)$ to the eigenvalues to separate $T_t(\lambda_1)$ from $T_t(\lambda_i)$.
- Still requires just t matrix vector multiplies. **Why?**

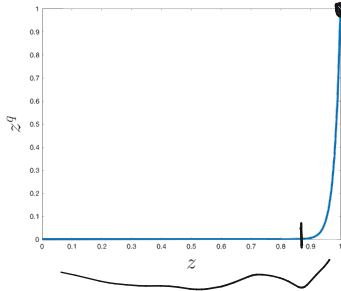
$$T_+(A)z^{(0)} = c_+ A^+ z^{(0)} + c_{+1} A^{+1} z^{(0)} + \dots + c_- A z^{(0)} + c_0 z^{(0)}$$

10

KRYLOV SUBSPACE METHODS

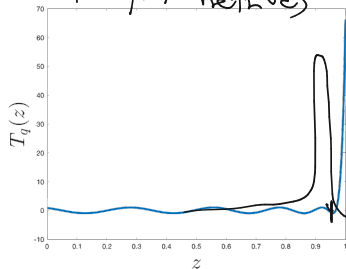
z^t

power method



vs.

Krylov methods $T_+(λ_2) \ll T_4(λ_1)$



Optimal 'jump' polynomial in general is given by a degree t **Chebyshev polynomial**. Krylov methods find a polynomial tuned to the input matrix that does at least as well.

GENERALIZATIONS TO LARGER k

- Block Power Method (a.k.a. Simultaneous Iteration, Subspace Iteration, or Orthogonal Iteration)
- Standard Krylov methods (i.e., **svds/eigs**)
- Block Krylov methods

$$d \begin{bmatrix} 1 \\ \vdots \\ z_0 \end{bmatrix}$$
$$d \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ z_0 \\ \vdots \end{bmatrix}$$

Runtime: $O\left(\underbrace{ndk} \cdot \underbrace{\frac{\ln(d/\epsilon)}{\sqrt{\gamma}}}\right)$

to accurately compute the top k singular vectors.

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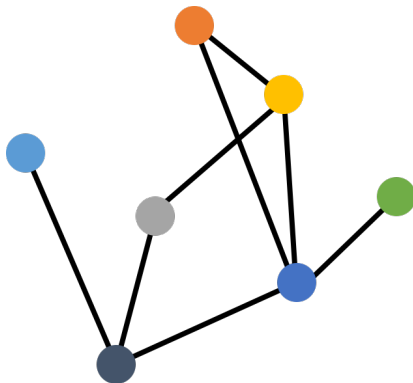
'Gapless' Runtime: $O\left(ndk \cdot \frac{\ln(d/\epsilon)}{\sqrt{\epsilon}}\right)$

if you just want a set of vectors that gives an ϵ -optimal low-rank approximation when you project onto them.

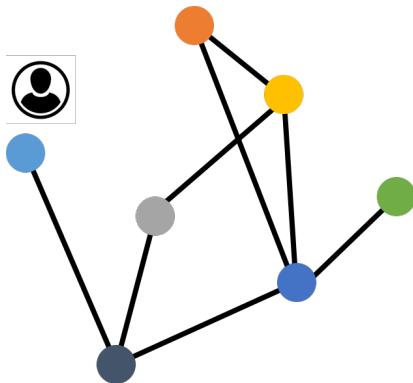
A hand-drawn black bracket on the left side of the slide, with a curved top and a curved bottom, pointing towards the text.

Connection Between Random Walks, Eigenvectors, and Power Method

Consider a random walk on a graph G with adjacency matrix A .

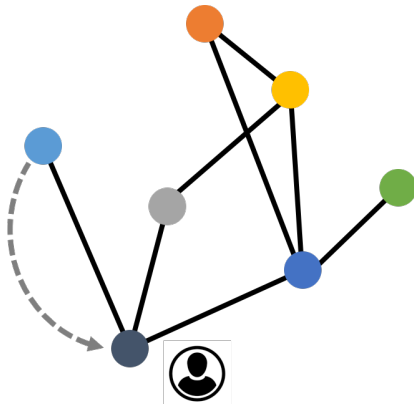


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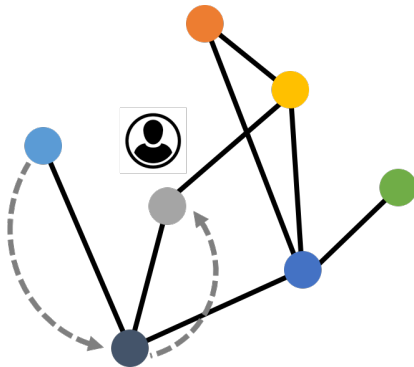


At each step, move to a random vertex, chosen uniformly at random from the neighbors of the current vertex.

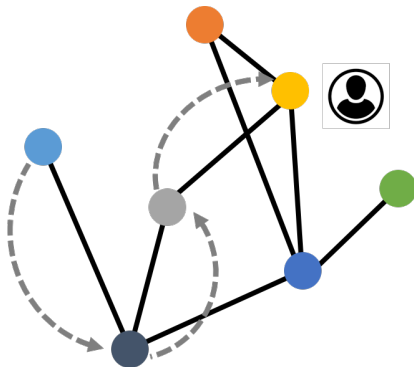
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- $\vec{p}^{(t)} = \mathbf{AD}^{-1} \vec{p}^{(t-1)} = \underbrace{\mathbf{AD}^{-1} \mathbf{AD}^{-1} \dots \mathbf{AD}^{-1}}_{t \text{ times}} \vec{p}^{(0)}$

Claim: After t steps, the probability that a random walk is at node i is given by the i^{th} entry of

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$$\mathbf{D}^{-1/2} \vec{p}^{(t)} = \underbrace{(\mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2})(\mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2}) \dots (\mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2})}_{t \text{ times}} (\mathbf{D}^{-1/2} \vec{p}^{(0)}).$$

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- Will converge to the top eigenvector of the normalized adjacency matrix $\mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2}$. **Stationary distribution.**
- Like the power method, the time a random walk takes to converge to its stationary distribution (mixing time) is dependent on the gap between the top two eigenvalues of $\mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2}$. The **spectral gap**.

A small spectral gap for $\mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2}$ corresponds to a small second smallest eigenvalue for the normalized Laplacian $\mathbf{D}^{-1/2}\mathbf{L}\mathbf{D}^{-1/2}$. Why?

Why does this make sense intuitively given what we know about the second smallest eigenvalue of the Laplacian?