

COMPSCI 514: ALGORITHMS FOR DATA SCIENCE

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Lecture 18

- Problem Set 3 was due yesterday.
- Solutions have been posted.
- There was no quiz due this week. Will have one due next Monday as usual.

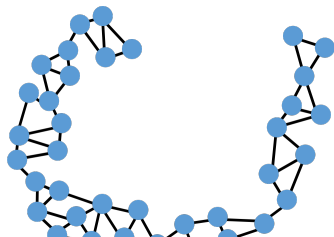
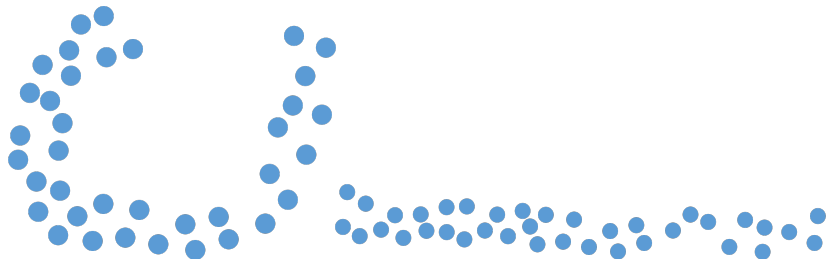
Last Class: Applications of Low-Rank Approximation

- Low-rank matrix completion (predicting missing measurements using low-rank structure).
- Entity embeddings (e.g., LSA, word embeddings). View as low-rank approximation of a similarity matrix.

Spectral Graph Theory & Spectral Clustering.

- Low-rank approximation on graph adjacency matrix for non-linear dimensionality reduction.
- Eigendecomposition to partition graphs into clusters.
- Application to the *stochastic block model* and community detection.

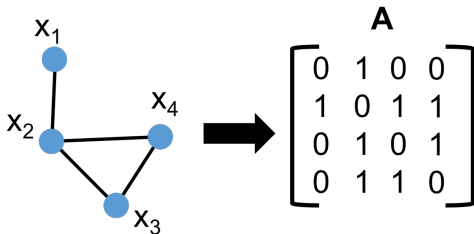
NON-LINEAR DIMENSIONALITY REDUCTION



LINEAR ALGEBRAIC REPRESENTATION OF A GRAPH

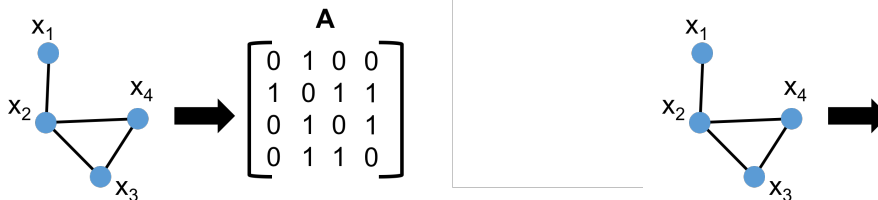
Once we have connected n data points x_1, \dots, x_n into a graph, we can represent that graph by its (weighted) adjacency matrix.

$\mathbf{A} \in \mathbb{R}^{n \times n}$ with $\mathbf{A}_{i,j}$ = edge weight between nodes i and j



In LSA example, when \mathbf{X} is the term-document matrix, $\mathbf{X}^T\mathbf{X}$ is like an adjacency matrix, where $word_a$ and $word_b$ are connected if they appear in at least 1 document together (edge weight is # documents they appear in together).

NORMALIZED ADJACENCY MATRIX



What is the sum of entries in the i^{th} column of A ? The (weighted) degree of vertex i .

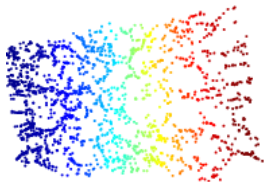
Often, A is normalized as $\bar{A} = D^{-1/2}AD^{-1/2}$ where D is the degree matrix.

Spectral graph theory is the field of representing graphs as matrices and applying linear algebraic techniques.

How do we compute an optimal low-rank approximation of \mathbf{A} ?

- Project onto the top k eigenvectors of $\mathbf{A}^T\mathbf{A} = \mathbf{A}^2$. These are just the eigenvectors of \mathbf{A} .

- Similar vertices (close with regards to graph proximity) should have similar embeddings.

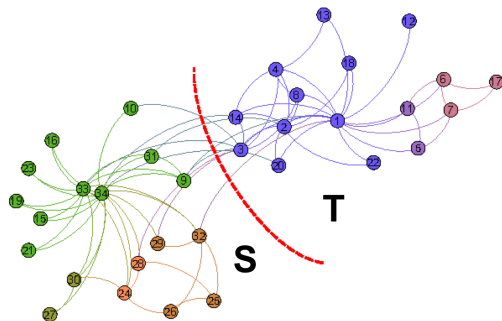


What other methods do you know for embedding or representing data points with non-linear structure?

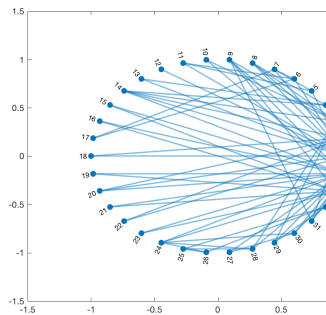
SPECTRAL CLUSTERING

A very common task is to **partition or cluster** vertices in a graph based on similarity/connectivity.

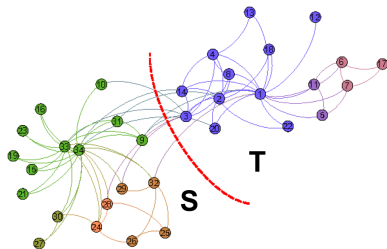
Community detection in naturally occurring networks.



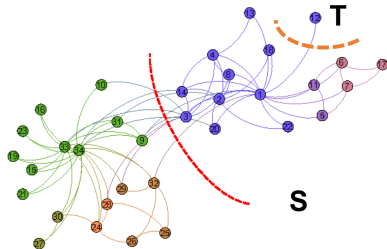
(a) Zachary Karate Club Graph



Simple Idea: Partition clusters along minimum cut in graph.



(a) Zachary Karate Club Graph



(a) Zachary Karate Club Graph

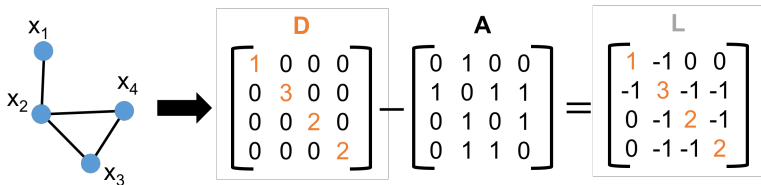
Small cuts are often not informative.

Solution: Encourage cuts that separate large sections of the graph.

- Let $\vec{v} \in \mathbb{R}^n$ be a **cut indicator**: $\vec{v}(i) = 1$ if $i \in S$. $\vec{v}(i) = -1$ if $i \in T$.
Want \vec{v} to have roughly equal numbers of 1s and -1 s. I.e., $\vec{v}^T \vec{1} \approx 0$.

THE LAPLACIAN VIEW

For a graph with adjacency matrix \mathbf{A} and degree matrix \mathbf{D} , $\mathbf{L} = \mathbf{D} - \mathbf{A}$ is the **graph Laplacian**.



For any vector \vec{v} , its 'smoothness' over the graph is given by:

$$\sum_{(i,j) \in E} (\vec{v}(i) - \vec{v}(j))^2 = \vec{v}^T \mathbf{L} \vec{v}.$$

For a cut indicator vector $\vec{v} \in \{-1, 1\}^n$ with $\vec{v}(i) = -1$ for $i \in S$ and $\vec{v}(i) = 1$ for $i \in T$:

1. $\vec{v}^T \mathbf{L} \vec{v} = \sum_{(i,j) \in E} (\vec{v}(i) - \vec{v}(j))^2 = 4 \cdot \text{cut}(S, T)$.
2. $\vec{v}^T \vec{1} = |V| - |S|$.

Want to minimize both $\vec{v}^T \mathbf{L} \vec{v}$ (cut size) and $\vec{v}^T \vec{1}$ (imbalance).

Next Step: See how this dual minimization problem is naturally solved by eigendecomposition.