COMPSCI 514: ALGORITHMS FOR DATA SCIENCE

Cameron Musco

University of Massachusetts Amherst. Fall 2019.

Lecture 14

LOGISTICS

- Midterm grades are on Moodle.
- Average was 32.67, median 33, standard deviation 6.8
- Come to office hours if you would like to see your exam/discuss solutions.

Last Few Weeks: Low-Rank Approximation and PCA

Last Few Weeks: Low-Rank Approximation and PCA

- Compress data that lies close to a k-dimensional subspace.
- Equivalent to finding a low-rank approximation of the data matrix $\mathbf{X}$: $\mathbf{X} \approx \mathbf{X}\mathbf{V}\mathbf{V}^T$.
- Optimal solution via PCA (eigendecomposition of $\mathbf{X}^T\mathbf{X}$ or equivalently, SVD of $\mathbf{X}$).

Last Few Weeks: Low-Rank Approximation and PCA

- Compress data that lies close to a k-dimensional subspace.
- Equivalent to finding a low-rank approximation of the data matrix $\mathbf{X}$: $\mathbf{X} \approx \mathbf{X}\mathbf{V}\mathbf{V}^T$.
- Optimal solution via PCA (eigendecomposition of $\mathbf{X}^T\mathbf{X}$ or equivalently, SVD of $\mathbf{X}$).

This Class: Non-linear dimensionality reduction.

Last Few Weeks: Low-Rank Approximation and PCA

- Compress data that lies close to a k-dimensional subspace.
- Equivalent to finding a low-rank approximation of the data matrix $\mathbf{X}$: $\mathbf{X} \approx \mathbf{X}\mathbf{V}\mathbf{V}^T$.
- Optimal solution via PCA (eigendecomposition of $\mathbf{X}^T\mathbf{X}$ or equivalently, SVD of $\mathbf{X}$).

This Class: Non-linear dimensionality reduction.

- How do we compress data that does not lie close to a k-dimensional subspace?
- Spectral methods (SVD and eigendecomposition) are still key techniques in this setting.
- Spectral graph theory, spectral clustering.

$\mathbb{R}^d \to \mathbb{R}^{d'} \quad d' < d$

End of Last Class: Embedding objects other than vectors into Euclidean space.

ENTITY EMBEDDINGS

End of Last Class: Embedding objects other than vectors into Euclidean space.

- Documents (for topic-based search and classification)
- Words (to identify synonyms, translations, etc.)
- Nodes in a social network

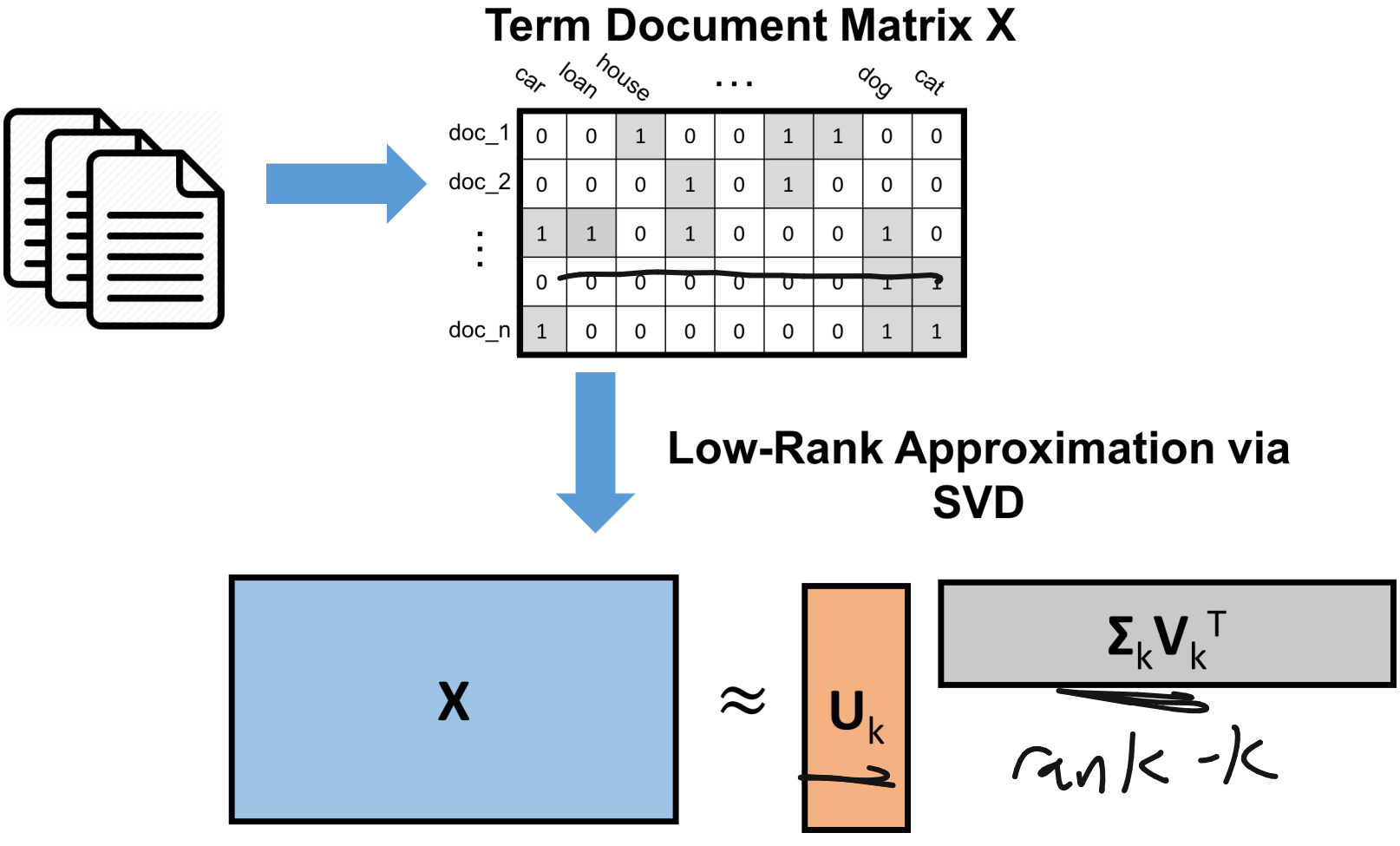
ENTITY EMBEDDINGS

End of Last Class: Embedding objects other than vectors into Euclidean space.

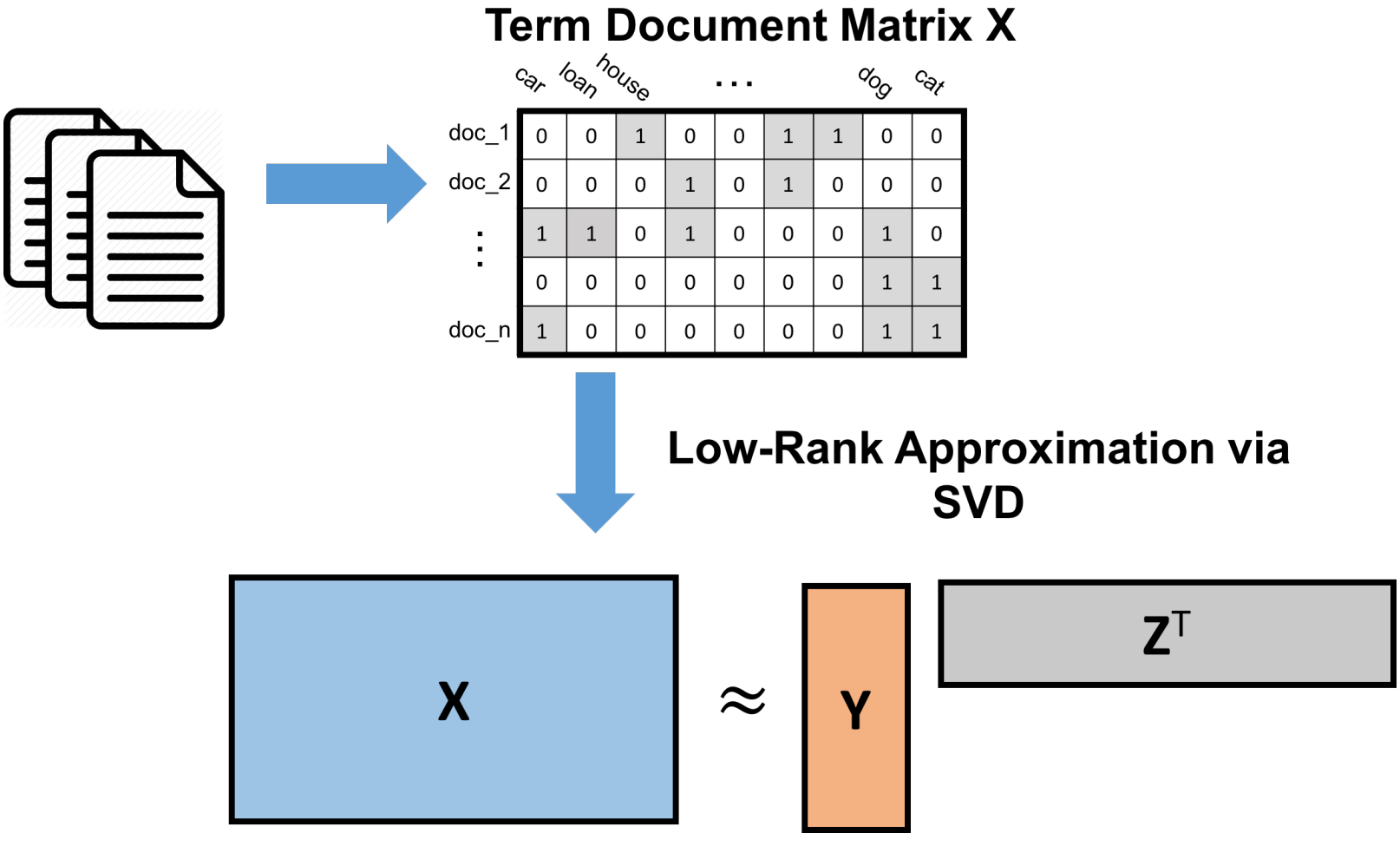
- Documents (for topic-based search and classification)
- Words (to identify synonyms, translations, etc.)
- Nodes in a social network

Usual Approach: Convert each item into a high-dimensional feature vector and then apply low-rank approximation

EXAMPLE: LATENT SEMANTIC ANALYSIS



EXAMPLE: LATENT SEMANTIC ANALYSIS

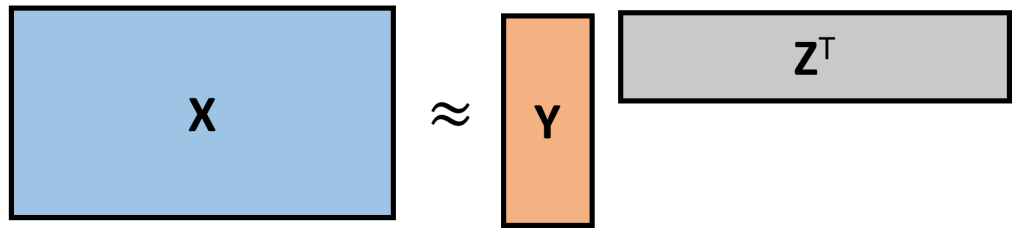


EXAMPLE: LATENT SEMANTIC ANALYSIS

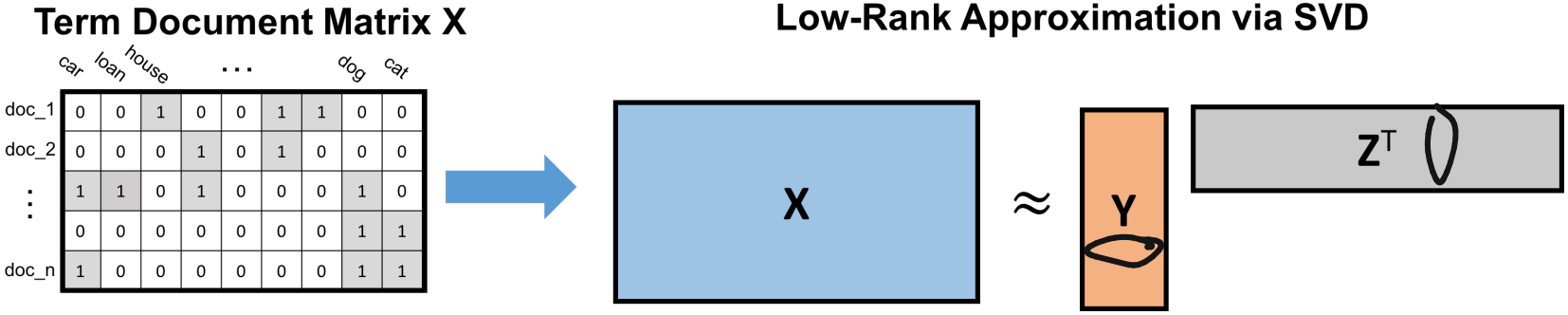
Term Document Matrix X

	car	loan	house	...	dog	cat
doc_1	0	0	1	0	0	1	1	0	0
doc_2	0	0	0	1	0	1	0	0	0
⋮	1	1	0	1	0	0	0	1	0
	0	0	0	0	0	0	0	1	1
doc_n	1	0	0	0	0	0	0	1	1

Low-Rank Approximation via SVD



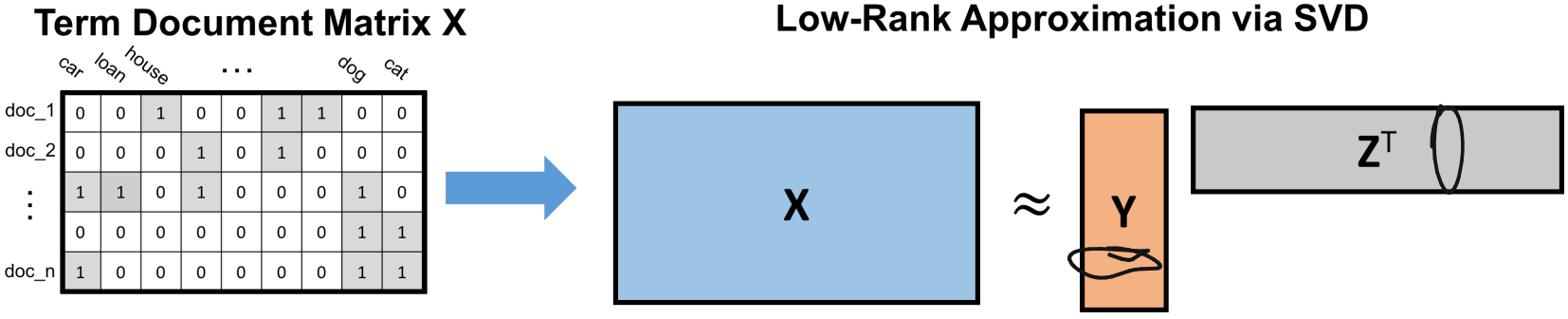
EXAMPLE: LATENT SEMANTIC ANALYSIS



- If the error $\|X - YZ^T\|_F$ is small, then on average,

$$X_{i,a} \approx (YZ^T)_{i,a} = \langle \vec{y}_i, \vec{z}_a \rangle.$$

EXAMPLE: LATENT SEMANTIC ANALYSIS

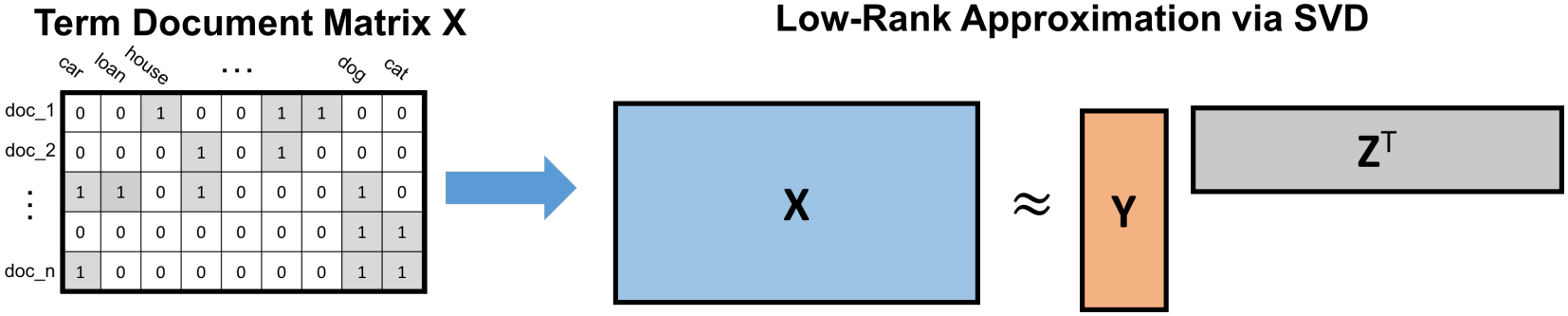


- If the error $\|\mathbf{X} - \mathbf{Y}\mathbf{Z}^T\|_F$ is small, then on average,

$$\mathbf{X}_{i,a} \approx (\mathbf{Y}\mathbf{Z}^T)_{i,a} = \langle \vec{y}_i, \vec{z}_a \rangle.$$

- I.e., $\langle \vec{y}_i, \vec{z}_a \rangle \approx 1$ when doc_i contains $word_a$.

EXAMPLE: LATENT SEMANTIC ANALYSIS



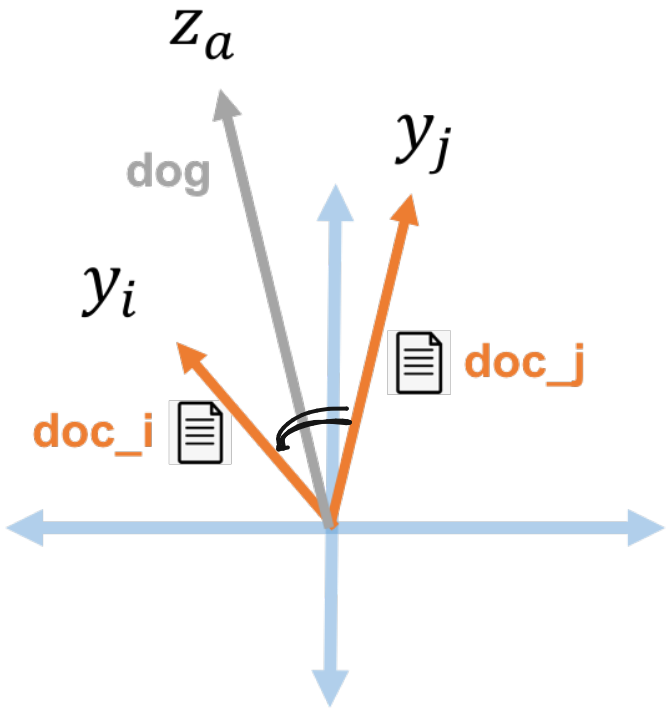
- If the error $\|\mathbf{X} - \mathbf{Y}\mathbf{Z}^T\|_F$ is small, then on average,

$$\mathbf{X}_{i,a} \approx (\mathbf{Y}\mathbf{Z}^T)_{i,a} = \langle \vec{y}_i, \vec{z}_a \rangle.$$

- I.e., $\langle \vec{y}_i, \vec{z}_a \rangle \approx 1$ when doc_i contains $word_a$.
- If doc_i and doc_j both contain $word_a$, $\langle \vec{y}_i, \vec{z}_a \rangle \approx \langle \vec{y}_j, \vec{z}_a \rangle \not\approx 1$.

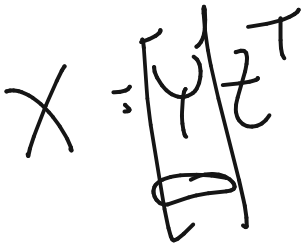
EXAMPLE: LATENT SEMANTIC ANALYSIS

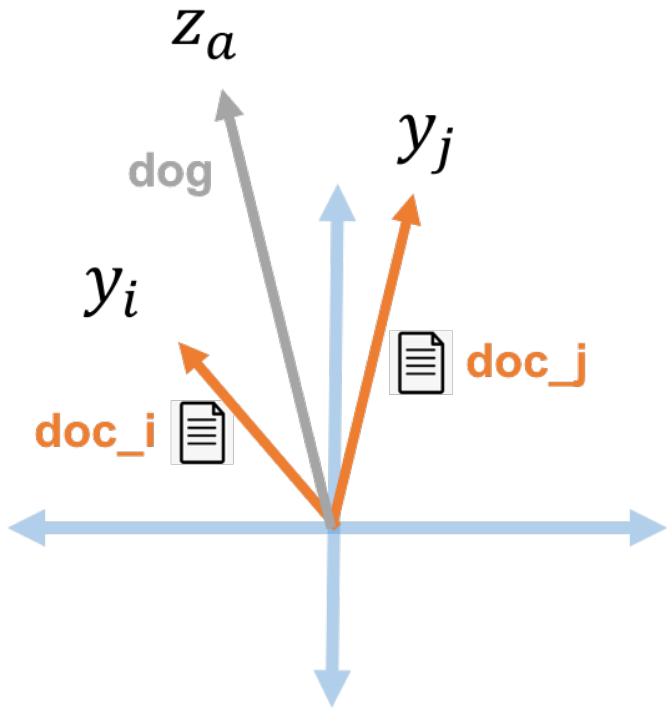
If doc_i and doc_j both contain $word_a$, $\langle \vec{y}_i, \vec{z}_a \rangle \approx \langle \vec{y}_j, \vec{z}_a \rangle = 1$



EXAMPLE: LATENT SEMANTIC ANALYSIS

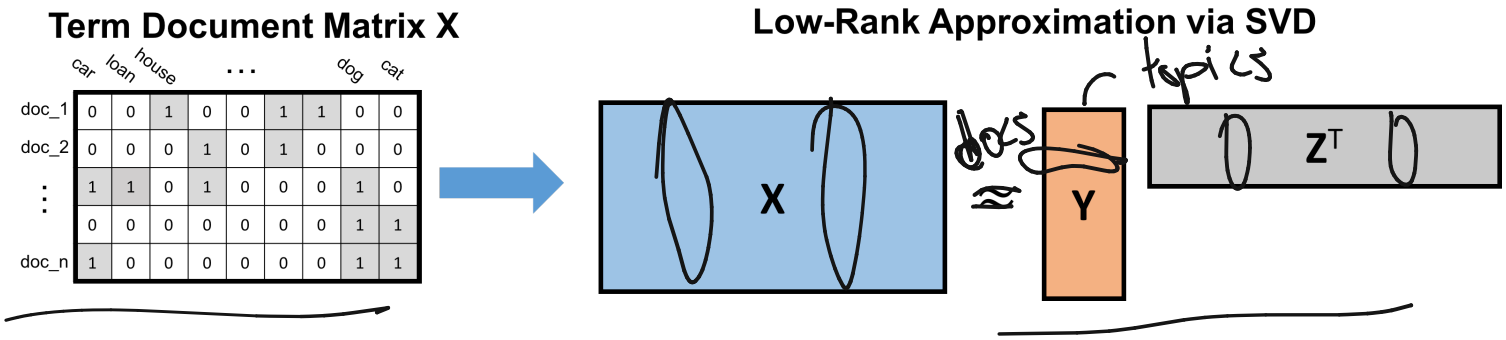
If doc_i and doc_j both contain $word_a$, $\langle \vec{y}_i, \vec{z}_a \rangle \approx \langle \vec{y}_j, \vec{z}_a \rangle = 1$





Another View: Each column of **Y** represents a 'topic'. $\vec{y}_i(j)$ indicates how much doc_i belongs to topic j. $\vec{z}_a(j)$ indicates how much $word_a$ associates with that topic.

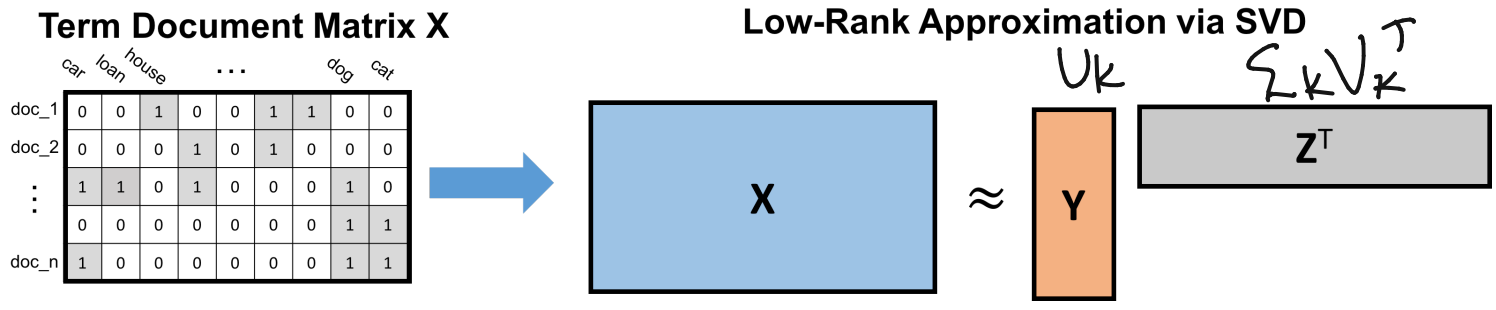
EXAMPLE: LATENT SEMANTIC ANALYSIS



- Just like with documents, $\vec{z}_a$ and $\vec{z}_b$ will tend to have high dot product if *word*$_a$ and *word*$_b$ appear in many of the same documents.

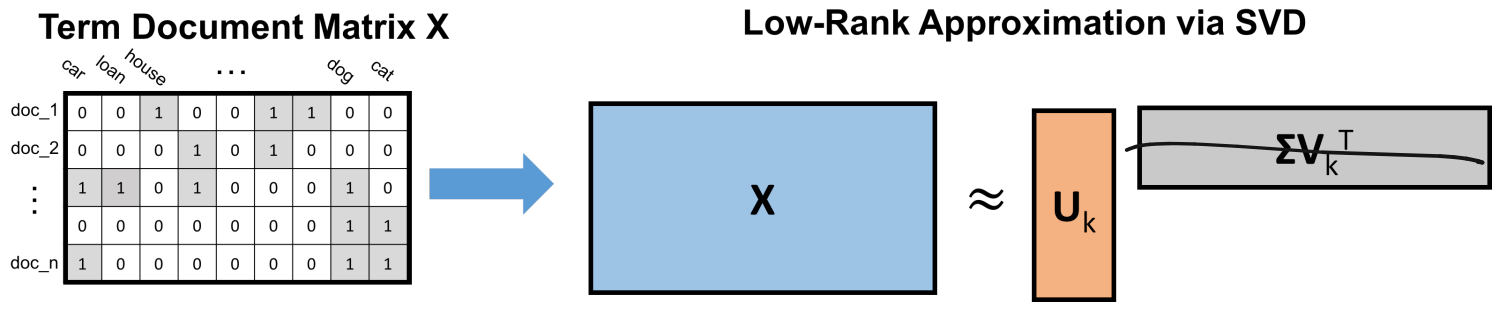
doc$_i$ $\vec{y}_i$ doc$_j$ $\vec{y}_j$ $\langle \vec{y}_i, \vec{y}_j \rangle$ $\sum y_i(k) y_j(k)$

EXAMPLE: LATENT SEMANTIC ANALYSIS



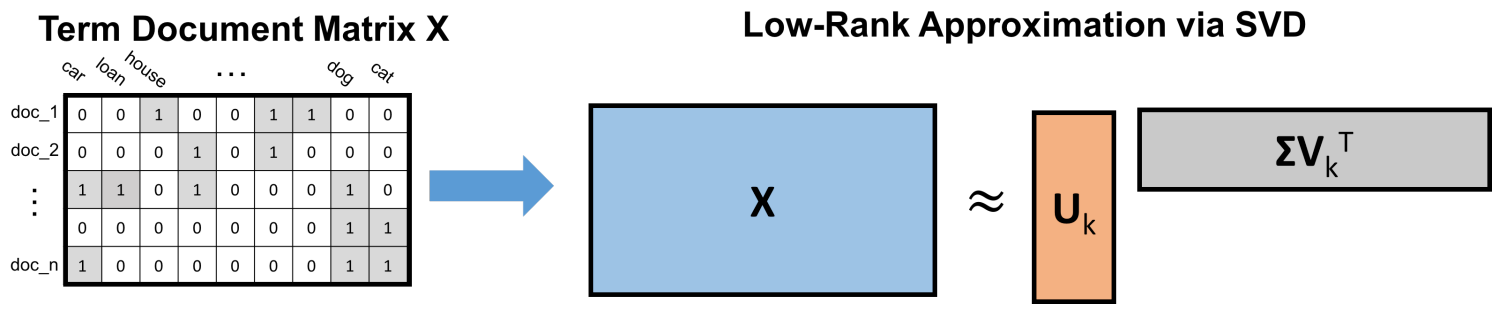
- Just like with documents, $\vec{z}_a$ and $\vec{z}_b$ will tend to have high dot product if $word_i$ and $word_j$ appear in many of the same documents.
- In an SVD decomposition we set $\mathbf{Z} = \mathbf{\Sigma}_k \mathbf{V}_K^T$.

EXAMPLE: LATENT SEMANTIC ANALYSIS



- Just like with documents, $\vec{z}_a$ and $\vec{z}_b$ will tend to have high dot product if $word_i$ and $word_j$ appear in many of the same documents.
- In an SVD decomposition we set $\mathbf{Z} = \mathbf{\Sigma}_k \mathbf{V}_K^T$.
- The columns of $\mathbf{V}_k$ are equivalently: the top k eigenvectors of $\mathbf{X}\mathbf{X}^T$.

EXAMPLE: LATENT SEMANTIC ANALYSIS



- Just like with documents, $\vec{z}_a$ and $\vec{z}_b$ will tend to have high dot product if $word_i$ and $word_j$ appear in many of the same documents.
- In an SVD decomposition we set $\mathbf{Z} = \mathbf{\Sigma}_k \mathbf{V}_K^T$.
- The columns of $\mathbf{V}_k$ are equivalently: the top k eigenvectors of $\mathbf{X}\mathbf{X}^T$. The eigendecomposition of $\mathbf{X}\mathbf{X}^T$ is $\mathbf{X}\mathbf{X}^T = \mathbf{V}\mathbf{\Sigma}^2\mathbf{V}^T$.

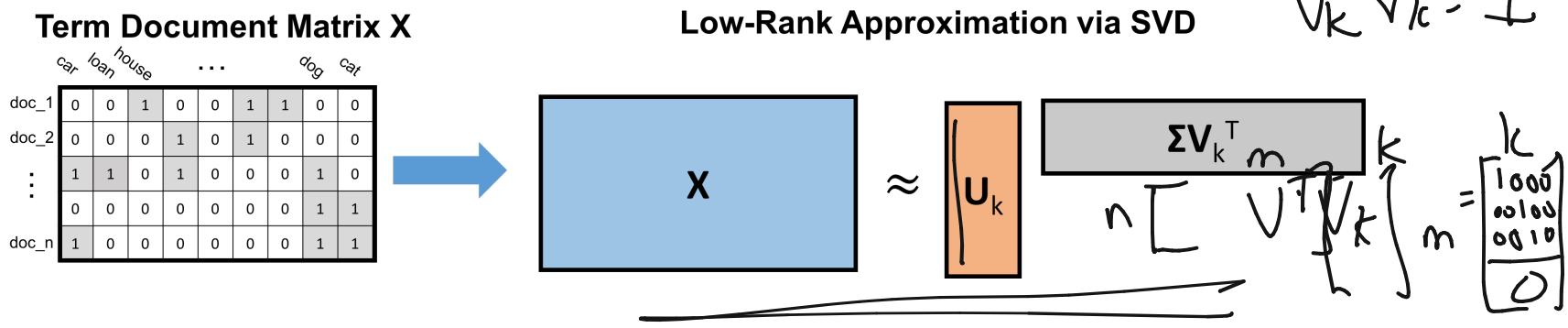
$X^T X$

$X = U \Sigma V^T$

$X^T X = V \Sigma U^T U \Sigma V^T = V \Sigma^2 V^T$

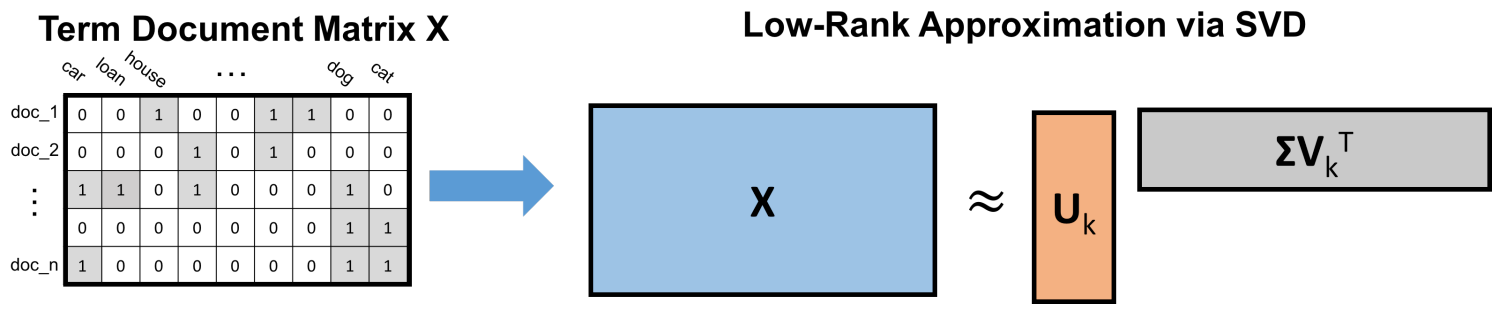
V_k

EXAMPLE: LATENT SEMANTIC ANALYSIS



- Just like with documents, $\vec{z}_a$ and $\vec{z}_b$ will tend to have high dot product if $word_i$ and $word_j$ appear in many of the same documents.
- In an SVD decomposition we set $\mathbf{Z}^T = \mathbf{\Sigma}_k \mathbf{V}_K^T$.
- The columns of $\mathbf{V}_k$ are equivalently: the top k eigenvectors of $\mathbf{X}\mathbf{X}^T$. The eigendecomposition of $\mathbf{X}\mathbf{X}^T$ is $\mathbf{X}\mathbf{X}^T = \mathbf{V}\mathbf{\Sigma}^2\mathbf{V}^T$.
- What is the best rank-k approximation of $\mathbf{X}\mathbf{X}^T$? I.e. $\arg\min_{\text{rank}-k\ \mathbf{B}} \|\mathbf{X}\mathbf{X}^T - \mathbf{B}\|_F$

EXAMPLE: LATENT SEMANTIC ANALYSIS

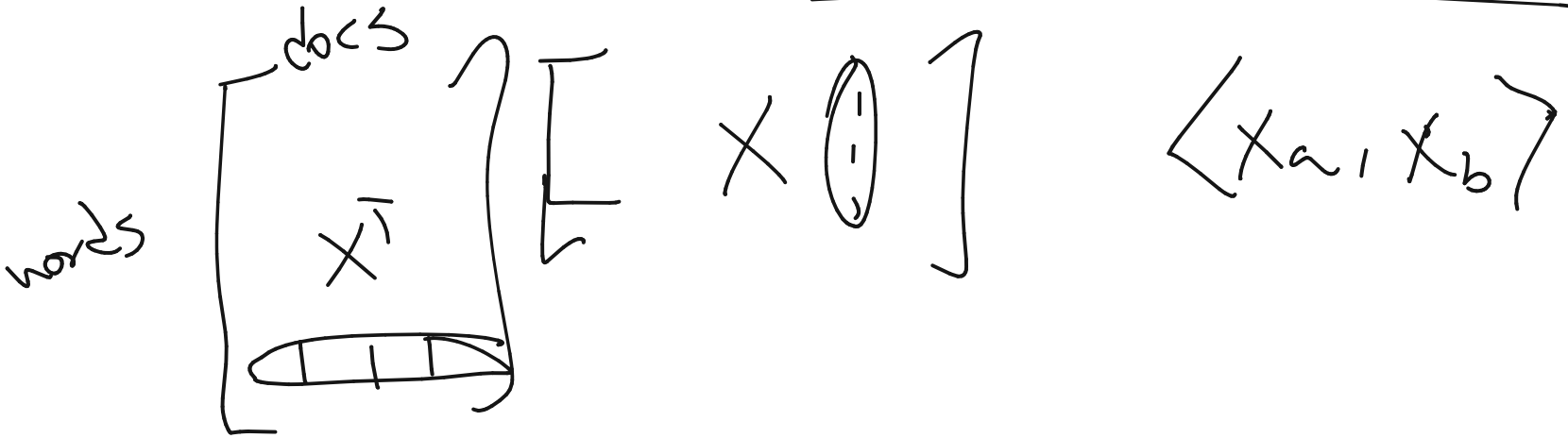


- Just like with documents, $\vec{z}_a$ and $\vec{z}_b$ will tend to have high dot product if $word_i$ and $word_j$ appear in many of the same documents.
- In an SVD decomposition we set $\mathbf{Z} = \mathbf{\Sigma}_k \mathbf{V}_K^T$.
- The columns of $\mathbf{V}_k$ are equivalently: the top k eigenvectors of $\mathbf{X}\mathbf{X}^T$. The eigendecomposition of $\mathbf{X}\mathbf{X}^T$ is $\mathbf{X}\mathbf{X}^T = \mathbf{V}\mathbf{\Sigma}^2\mathbf{V}^T$.
- What is the best rank-k approximation of $\mathbf{X}\mathbf{X}^T$? I.e. $\arg\min_{\text{rank}-k\ \mathbf{B}} \|\mathbf{X}\mathbf{X}^T - \mathbf{B}\|_F$
- $\mathbf{X}\mathbf{X}^T \approx \mathbf{V}_k \mathbf{\Sigma}_k^2 \mathbf{V}_k^T = \mathbf{Z}\mathbf{Z}^T$.

EXAMPLE: WORD EMBEDDING

LSA gives a way of embedding words into k-dimensional space.

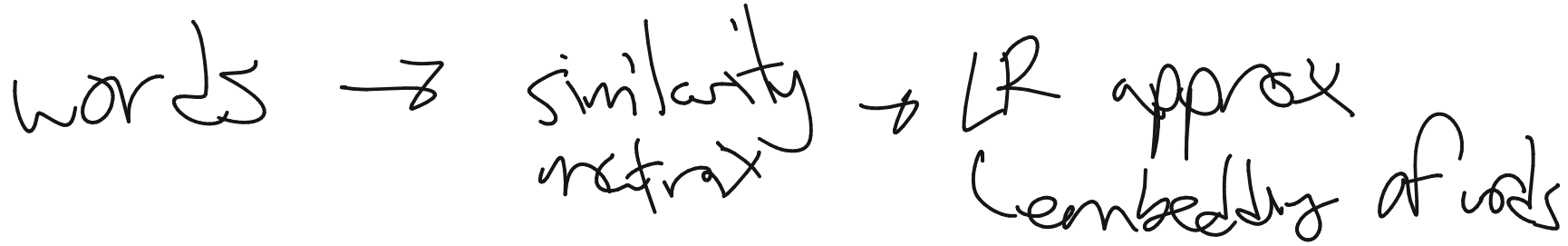
- Embedding is via low-rank approximation of $\mathbf{X}\mathbf{X}^T$: where $(\mathbf{X}\mathbf{X}^T)_{a,b}$ is the number of documents that both $word_a$ and $word_b$ appear in.



EXAMPLE: WORD EMBEDDING

LSA gives a way of embedding words into k-dimensional space.

- Embedding is via low-rank approximation of $\mathbf{X}\mathbf{X}^T$: where $(\mathbf{X}\mathbf{X}^T)_{a,b}$ is the number of documents that both $word_a$ and $word_b$ appear in.



- Think about $\mathbf{X}\mathbf{X}^T$ as a similarity matrix (gram matrix, kernel matrix) with entry (a, b) being the similarity between $word_a$ and $word_b$.

EXAMPLE: WORD EMBEDDING

LSA gives a way of embedding words into k-dimensional space.

- Embedding is via low-rank approximation of $\mathbf{X}\mathbf{X}^T$: where $(\mathbf{X}\mathbf{X}^T)_{a,b}$ is the number of documents that both $word_a$ and $word_b$ appear in.

- Think about $\mathbf{X}\mathbf{X}^T$ as a similarity matrix (gram matrix, kernel matrix) with entry (a, b) being the similarity between $word_a$ and $word_b$.
- Many ways to measure similarity: number of sentences both occur in, number of time both appear in the same window of w words, in similar positions of documents in different languages, etc.

EXAMPLE: WORD EMBEDDING

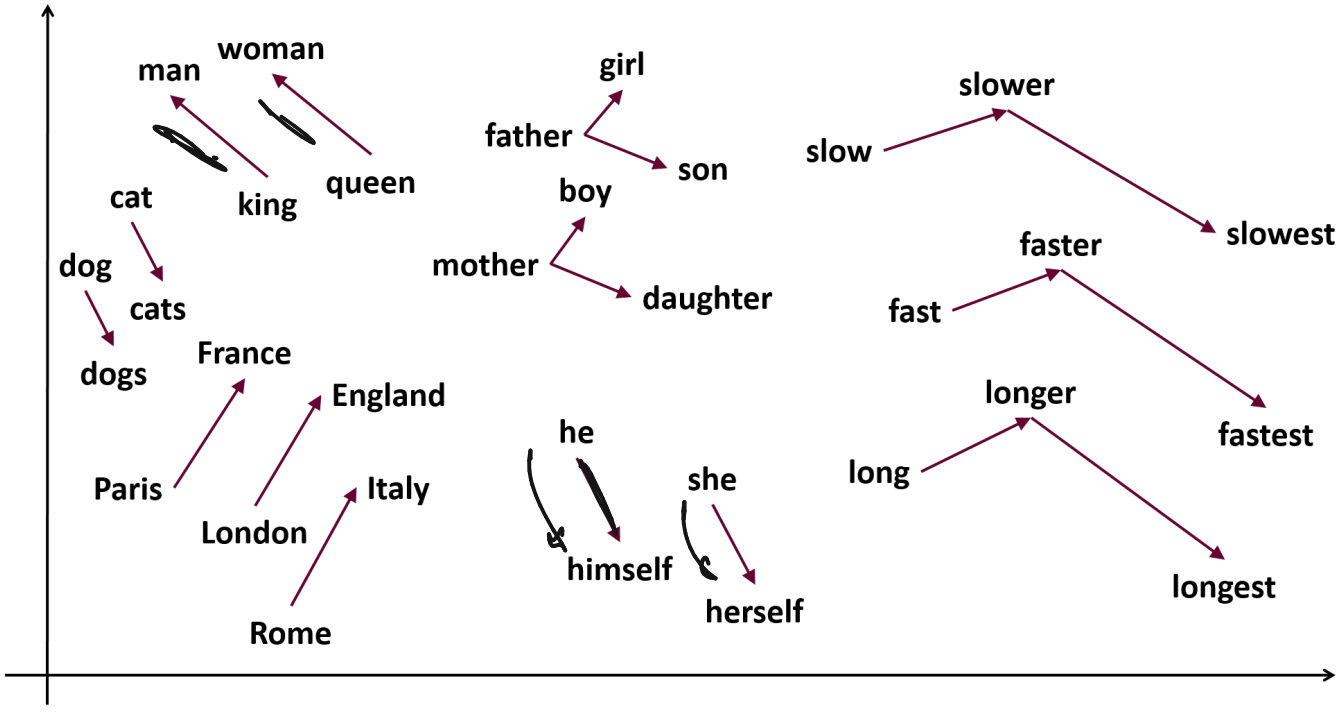
LSA gives a way of embedding words into k-dimensional space.

- Embedding is via low-rank approximation of $\mathbf{X}\mathbf{X}^T$: where $(\mathbf{X}\mathbf{X}^T)_{a,b}$ is the number of documents that both $word_a$ and $word_b$ appear in.

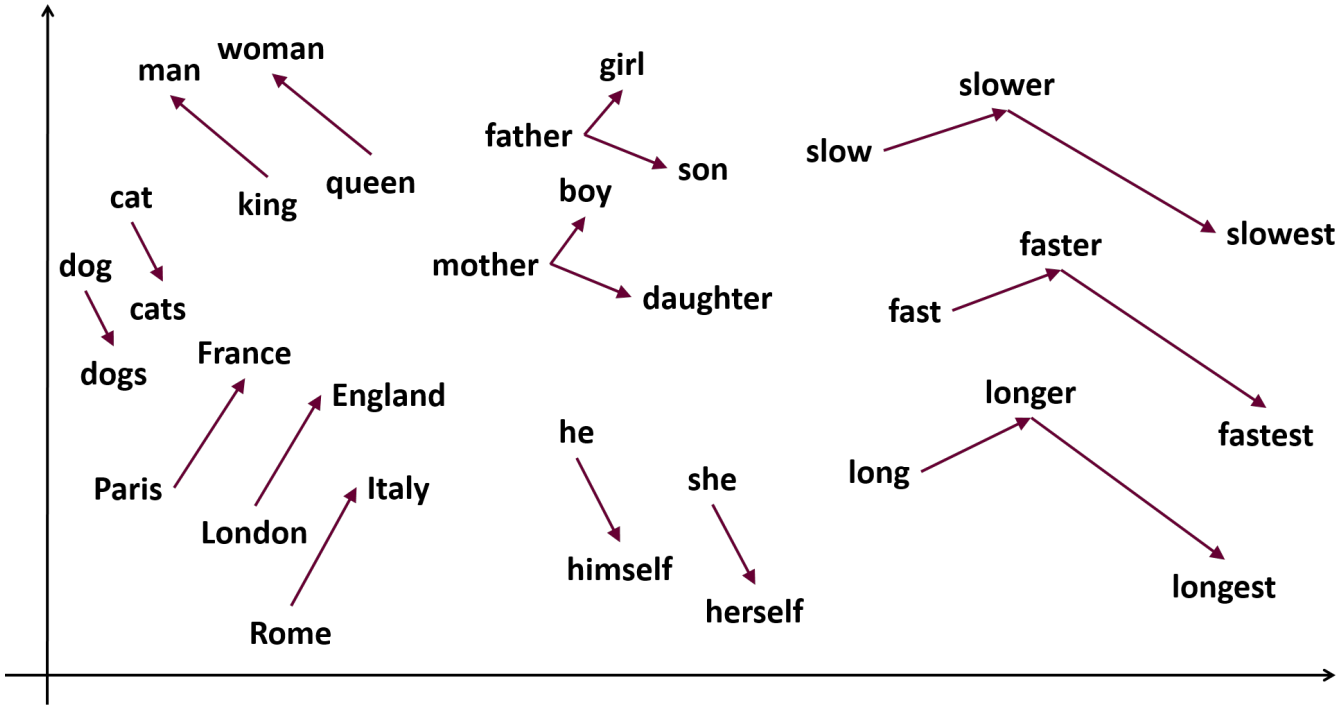
- Think about $\mathbf{X}\mathbf{X}^T$ as a similarity matrix (gram matrix, kernel matrix) with entry (a, b) being the similarity between $word_a$ and $word_b$.
- Many ways to measure similarity: number of sentences both occur in, number of time both appear in the same window of w words, in similar positions of documents in different languages, etc.
- Replacing $\mathbf{X}\mathbf{X}^T$ with these different metrics (sometimes appropriately transformed) leads to popular word embedding algorithms: word2vec, GloVe, fastText, etc.

EXAMPLE: WORD EMBEDDING

word2vec.



EXAMPLE: WORD EMBEDDING



Note: word2vec is typically described as a neural-network method, but it is really just low-rank approximation of a specific similarity matrix. *Neural word embedding as implicit matrix factorization,* Levy and Goldberg.

SIMILARITY VIA GRAPHS

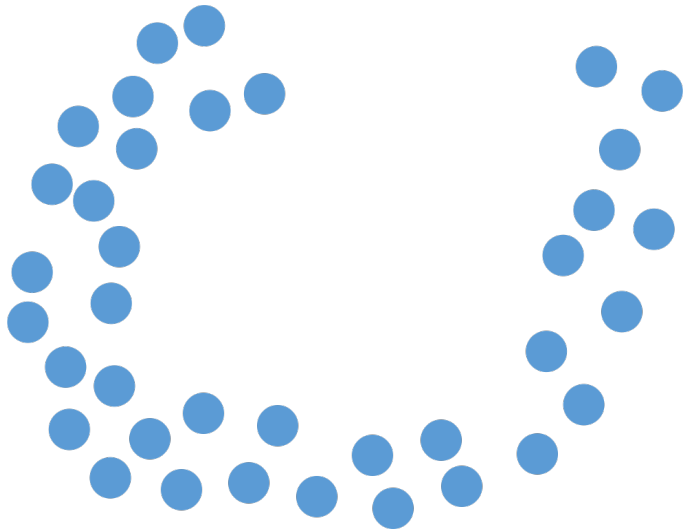
A common way of encoding similarity is via a graph. E.g., a k-nearest neighbor graph.

- Connect items to similar items, possibly with higher weight edges when they are more similar.

SIMILARITY VIA GRAPHS

A common way of encoding similarity is via a graph. E.g., a k-nearest neighbor graph.

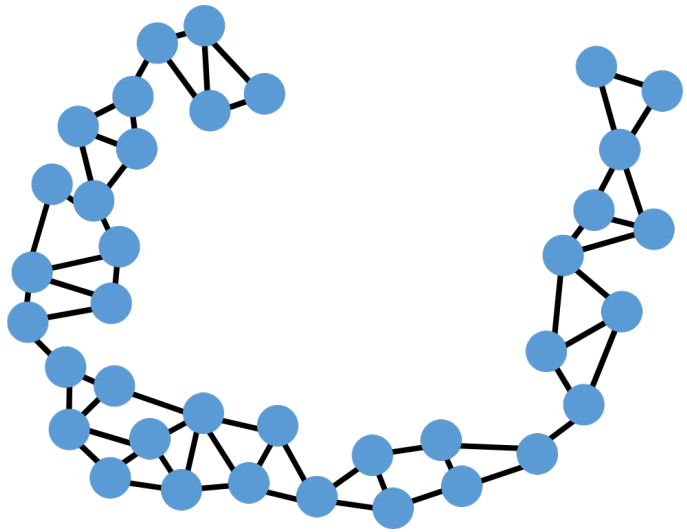
- Connect items to similar items, possibly with higher weight edges when they are more similar.



SIMILARITY VIA GRAPHS

A common way of encoding similarity is via a graph. E.g., a k-nearest neighbor graph.

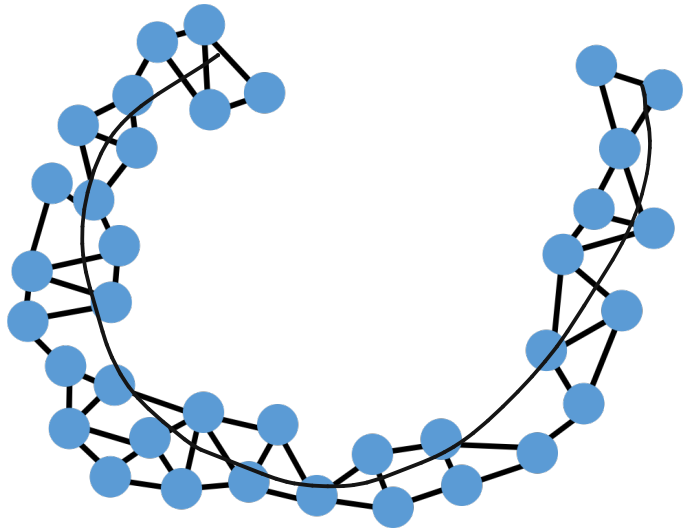
- Connect items to similar items, possibly with higher weight edges when they are more similar.



SIMILARITY VIA GRAPHS

A common way of encoding similarity is via a graph. E.g., a k-nearest neighbor graph.

- Connect items to similar items, possibly with higher weight edges when they are more similar.

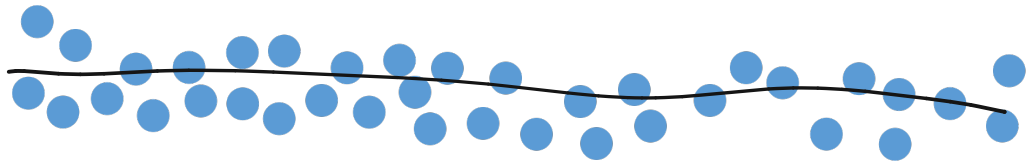


Is this set of points compressible? Does it lie close to a low-dimensional subspace?

SIMILARITY VIA GRAPHS

A common way of encoding similarity is via a graph. E.g., a k-nearest neighbor graph.

- Connect items to similar items, possibly with higher weight edges when they are more similar.



Is this set of points compressible? Does it lie close to a low-dimensional subspace?

LINEAR ALGEBRAIC REPRESENTATION OF A GRAPH

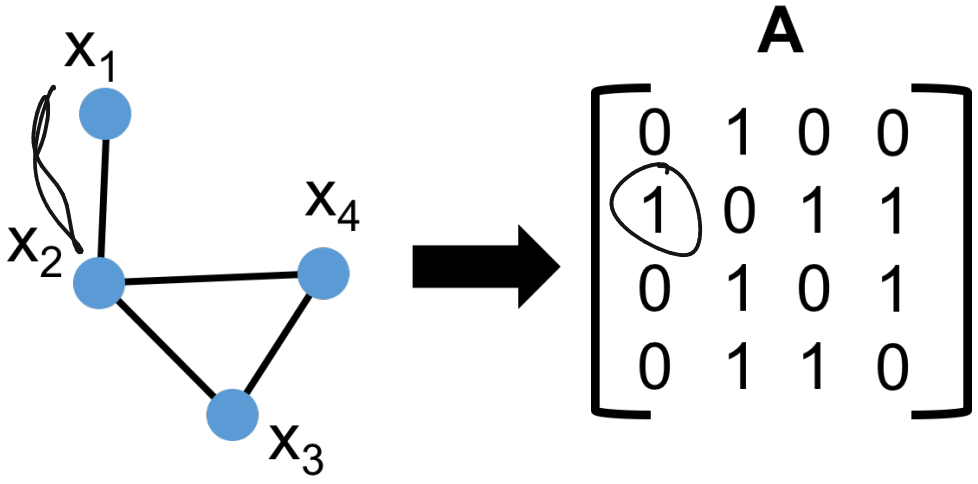
Once we have connected n data points $x_1, \ldots, x_n$ into a graph, we can represent that graph by its (weighted) adjacency matrix.

$$\mathbf{A} \in \mathbb{R}^{n \times n} \text{ with } \mathbf{A}_{i,j} = \text{ edge weight between nodes } i \text{ and } j$$

LINEAR ALGEBRAIC REPRESENTATION OF A GRAPH

Once we have connected n data points $x_1, \ldots, x_n$ into a graph, we can represent that graph by its (weighted) adjacency matrix.

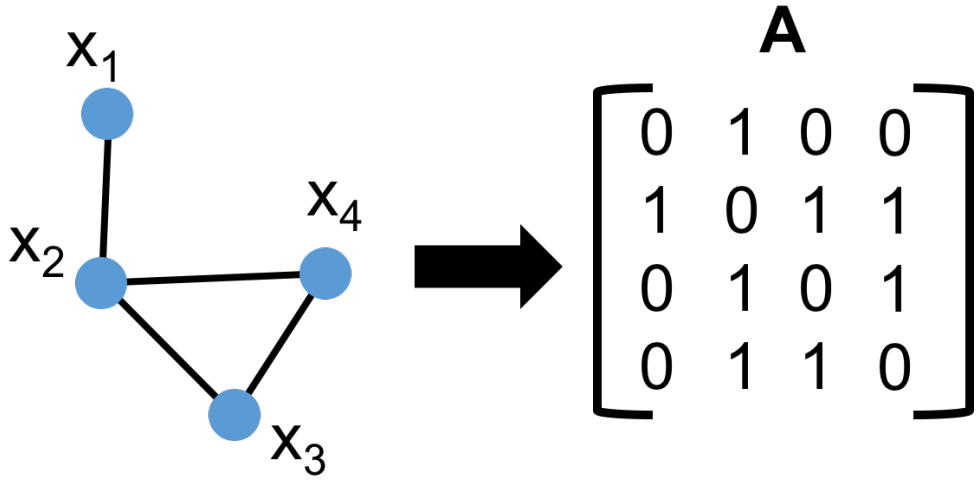
$$\mathbf{A} \in \mathbb{R}^{n \times n} \text{ with } \mathbf{A}_{i,j} = \text{ edge weight between nodes } i \text{ and } j$$



LINEAR ALGEBRAIC REPRESENTATION OF A GRAPH

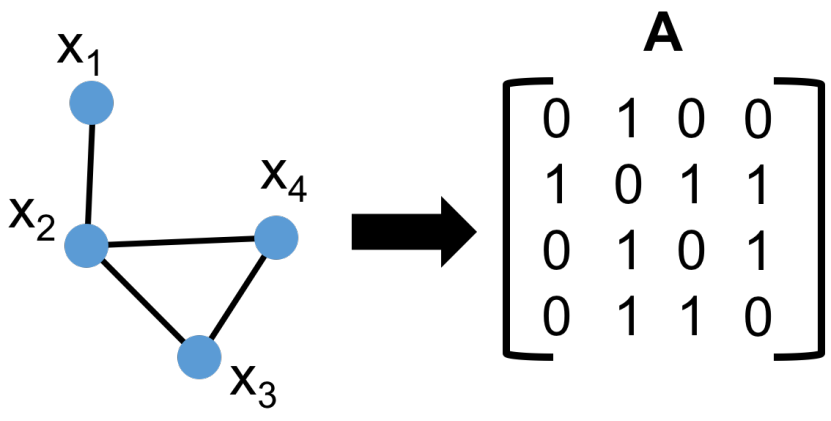
Once we have connected n data points $x_1, \ldots, x_n$ into a graph, we can represent that graph by its (weighted) adjacency matrix.

$$\mathbf{A} \in \mathbb{R}^{n \times n} \text{ with } \mathbf{A}_{i,j} = \text{ edge weight between nodes } i \text{ and } j$$



In LSA example, when $\mathbf{X}$ is the term-document matrix, $\mathbf{X}^T\mathbf{X}$ is like an adjacency matrix, where $word_a$ and $word_b$ are connected if they appear in at least 1 document together (edge weight is # documents they appear in together).

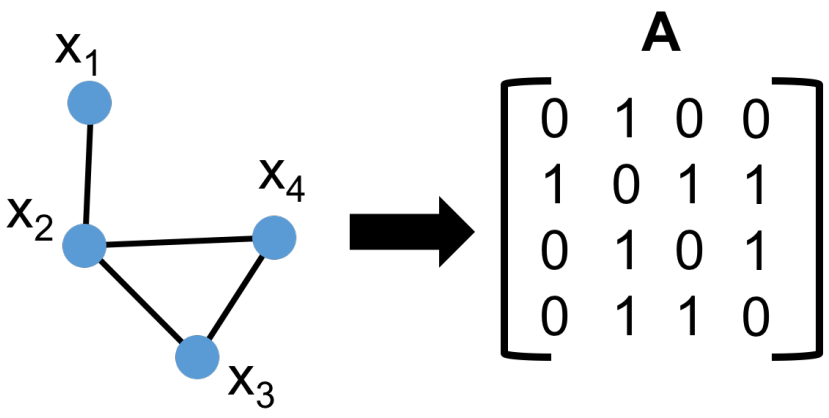
NORMALIZED ADJACENCY MATRIX



What is the sum of entries in the i^{th} column of A?

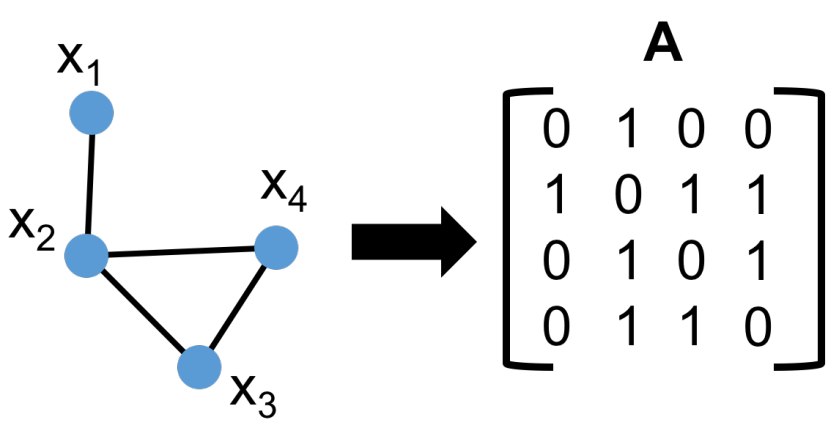
deg (vertex i)

NORMALIZED ADJACENCY MATRIX



What is the sum of entries in the i^{th} column of A? The (weighted) degree of vertex i.

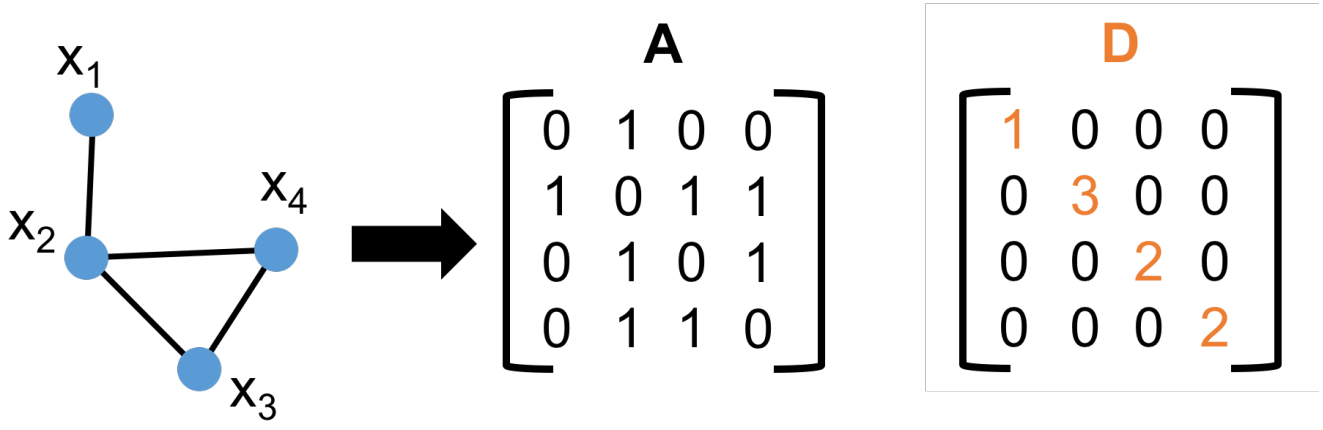
NORMALIZED ADJACENCY MATRIX



What is the sum of entries in the i^{th} column of A? The (weighted) degree of vertex i.

Often, $\mathbf{A}$ is normalized as $\bar{\mathbf{A}} = \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2}$ where $\mathbf{D}$ is the degree matrix.

NORMALIZED ADJACENCY MATRIX



What is the sum of entries in the i^{th} column of A? The (weighted) degree of vertex i.

Often, $\mathbf{A}$ is normalized as $\bar{\mathbf{A}} = \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2}$ where $\mathbf{D}$ is the degree matrix.

NORMALIZED ADJACENCY MATRIX

$$\bar{\mathbf{A}} = \begin{bmatrix} 0 & \frac{1}{\sqrt{3}} & 0 & 0 \\ \frac{1}{\sqrt{3}} & 0 & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{6}} & 0 & \frac{1}{2} \\ 0 & \frac{1}{\sqrt{3}} & \frac{1}{2} & 0 \end{bmatrix} = \mathbf{D}^{-1/2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 0 & \frac{1}{\sqrt{2}} \end{bmatrix} \mathbf{A} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 0 & \frac{1}{\sqrt{2}} \end{bmatrix} \mathbf{D}^{-1/2} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

What is the sum of entries in the i^{th} column of A? The (weighted) degree of vertex i.

Often, $\mathbf{A}$ is normalized as $\bar{\mathbf{A}} = \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2}$ where $\mathbf{D}$ is the degree matrix.

NORMALIZED ADJACENCY MATRIX

$$\bar{A} = D^{-1} A$$

$$\bar{\mathbf{A}} = \begin{bmatrix} 0 & \frac{1}{\sqrt{3}} & 0 & 0 \\ \frac{1}{\sqrt{3}} & 0 & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{6}} & 0 & \frac{1}{2} \\ 0 & \frac{1}{\sqrt{3}} & \frac{1}{2} & 0 \end{bmatrix} = \mathbf{D}^{-1/2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 0 & \frac{1}{\sqrt{2}} \end{bmatrix} \mathbf{A} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 0 & \frac{1}{\sqrt{2}} \end{bmatrix} \mathbf{D}^{-1/2}$$

What is the sum of entries in the i^{th} column of A? The (weighted) degree of vertex i.

Often, $\mathbf{A}$ is normalized as $\bar{\mathbf{A}} = \mathbf{D}^{-1/2}\mathbf{A}\mathbf{D}^{-1/2}$ where $\mathbf{D}$ is the degree matrix.

Spectral graph theory is the field of representing graphs as matrices and applying linear algebraic techniques.

ADJACENCY MATRIX EIGENVECTORS

How do we compute an optimal low-rank approximation of $\mathbf{A}$?

ADJACENCY MATRIX EIGENVECTORS

How do we compute an optimal low-rank approximation of $\mathbf{A}$?

- Project onto the top k eigenvectors of $\mathbf{A}^T\mathbf{A} = \mathbf{A}^2$.

How do we compute an optimal low-rank approximation of $\mathbf{A}$?

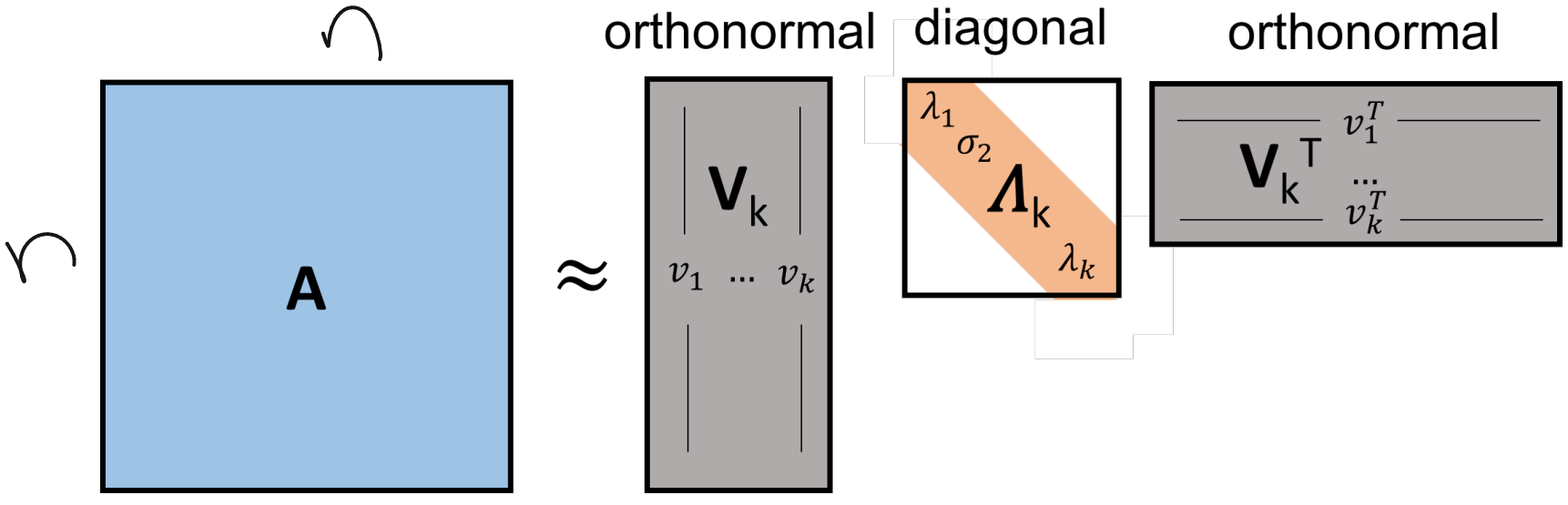
- Project onto the top k eigenvectors of $\mathbf{A}^T\mathbf{A} = \mathbf{A}^2$. These are just the eigenvectors of $\mathbf{A}$.

$A = V \Lambda V^T$ $\quad A^2 = V \Lambda V^T V \Lambda V^T = V \Lambda^2 V^T$

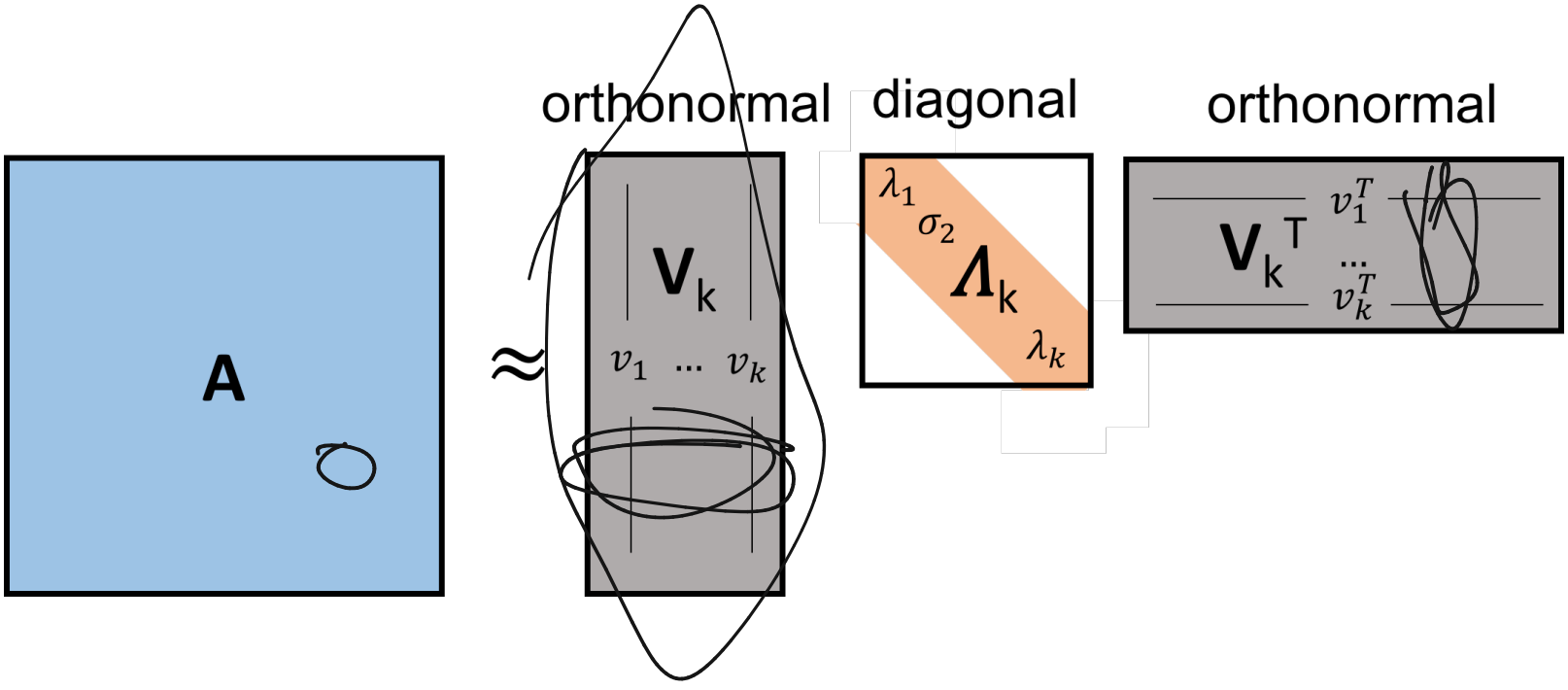
$A \approx A V_k V_k^T = V \Lambda V^T V_k V_k^T$

$= V_k \Lambda_k V_k^T$ best LR approx. of A.

ADJACENCY MATRIX EIGENVECTORS

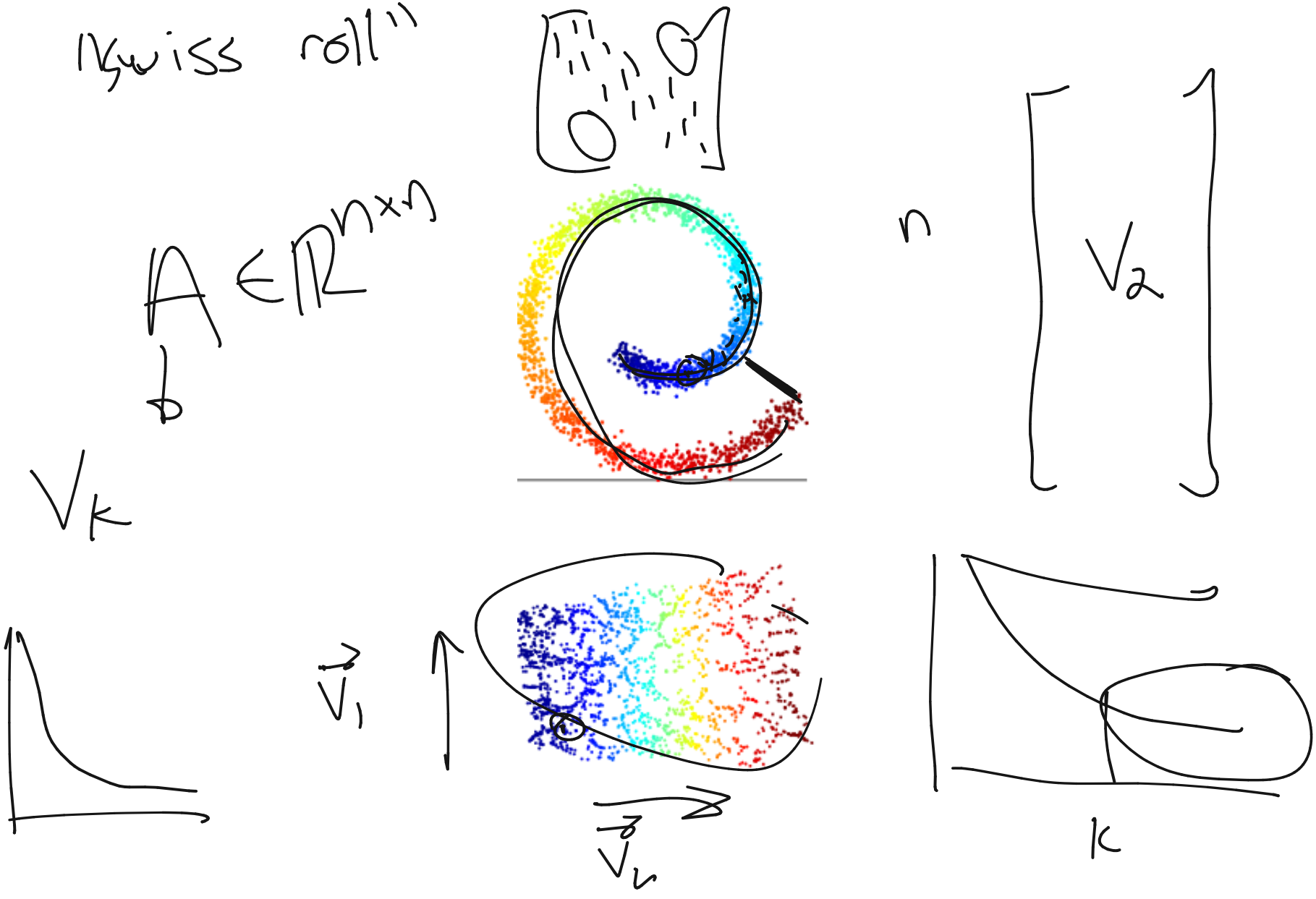


ADJACENCY MATRIX EIGENVECTORS



- Similar vertices (close with regards to graph proximity) should have similar embeddings. I.e., $\mathbf{V}_k(i)$ should be similar to $\mathbf{V}_k(j)$.

SPECTRAL EMBEDDING

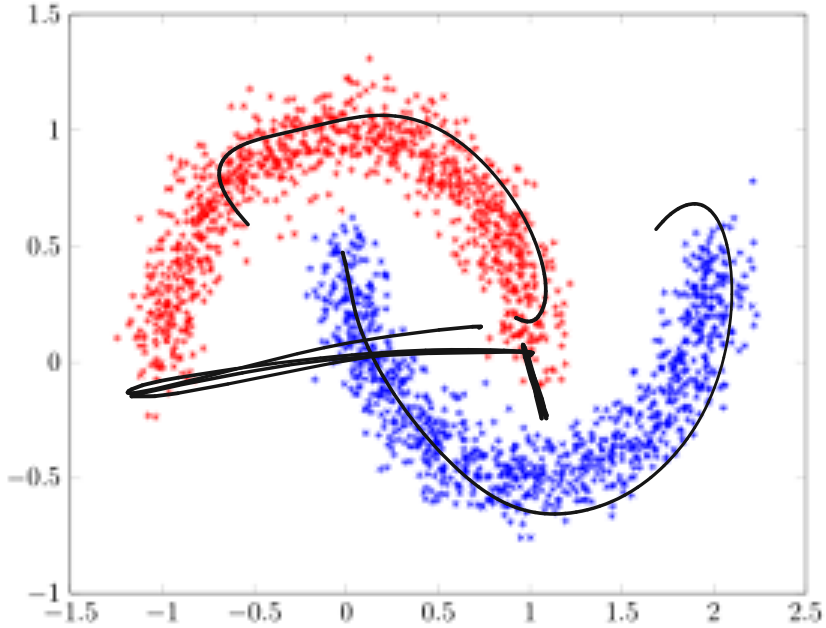


SPECTRAL CLUSTERING

A very common task aside from just embedding points via graph based similarity and SVD, is to partition or cluster vertices based on this similarity.

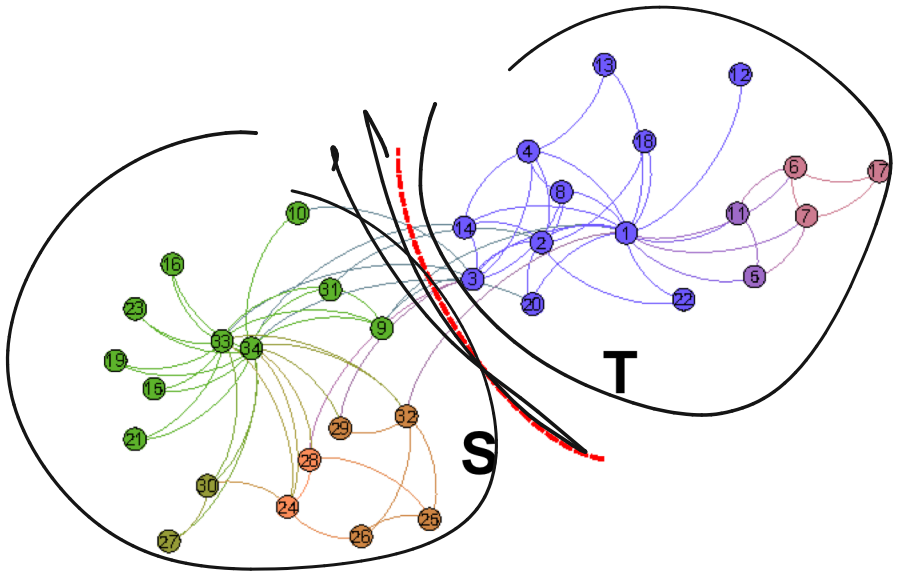
A very common task aside from just embedding points via graph based similarity and SVD, is to partition or cluster vertices based on this similarity.

Non-linearly separable data.



A very common task aside from just embedding points via graph based similarity and SVD, is to partition or cluster vertices based on this similarity.

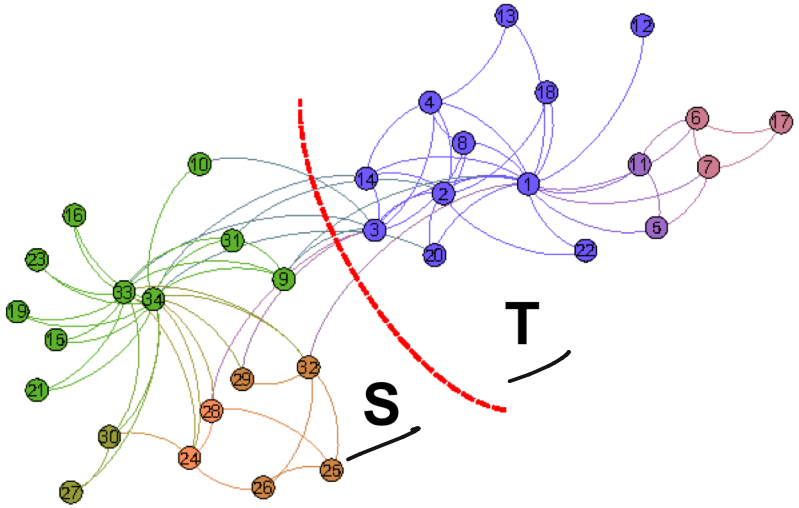
Community detection in naturally occuring networks.



(a) Zachary Karate Club Graph

CUT MINIMIZATION

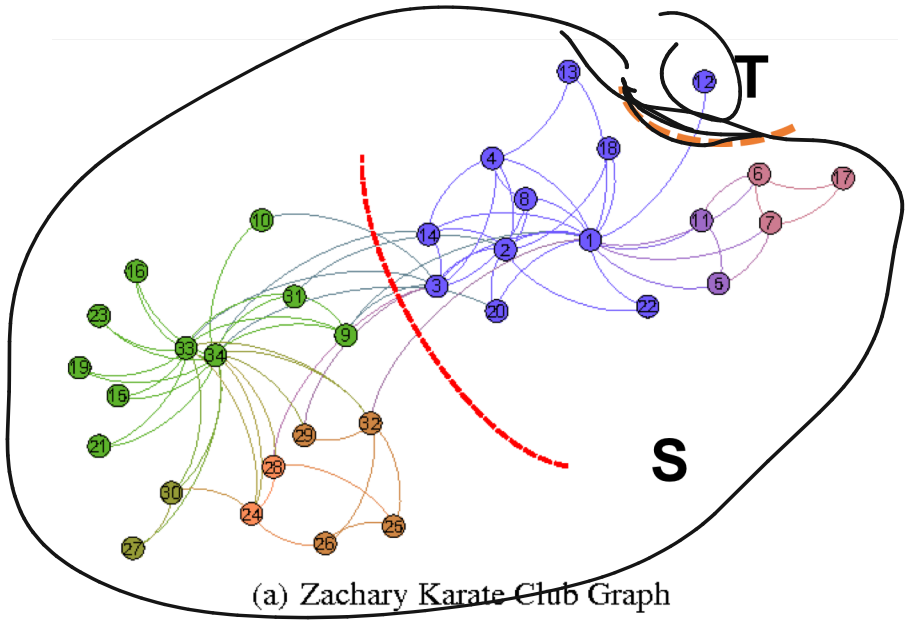
Simple Idea: Partition clusters along minimum cut in graph.



(a) Zachary Karate Club Graph

CUT MINIMIZATION

Simple Idea: Partition clusters along minimum cut in graph.

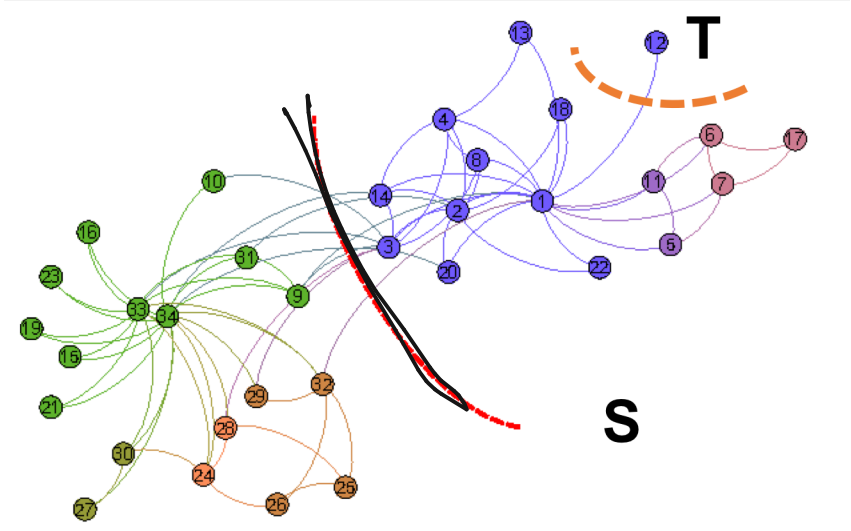


(a) Zachary Karate Club Graph

Small cuts are often not informative.

CUT MINIMIZATION

Simple Idea: Partition clusters along minimum cut in graph.



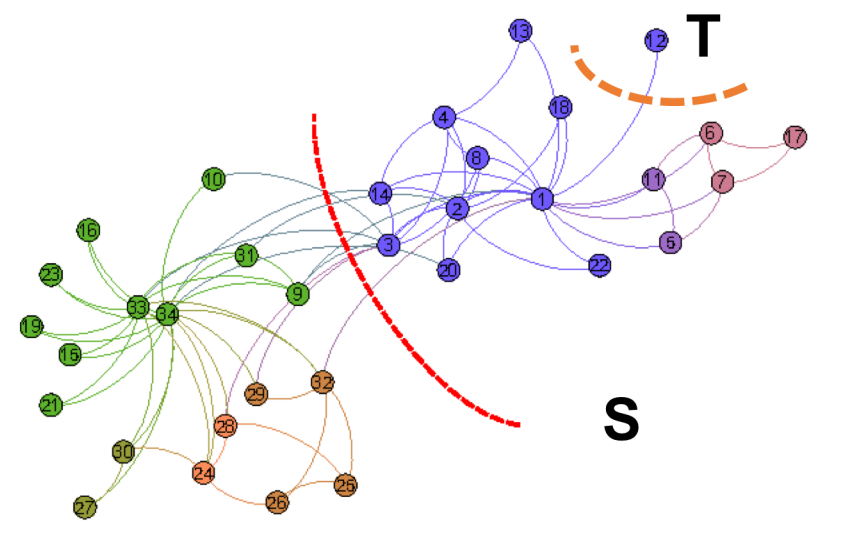
(a) Zachary Karate Club Graph

Small cuts are often not informative.

Solution: Encourage cuts that separate large sections of the graph.

CUT MINIMIZATION

Simple Idea: Partition clusters along minimum cut in graph.



(a) Zachary Karate Club Graph

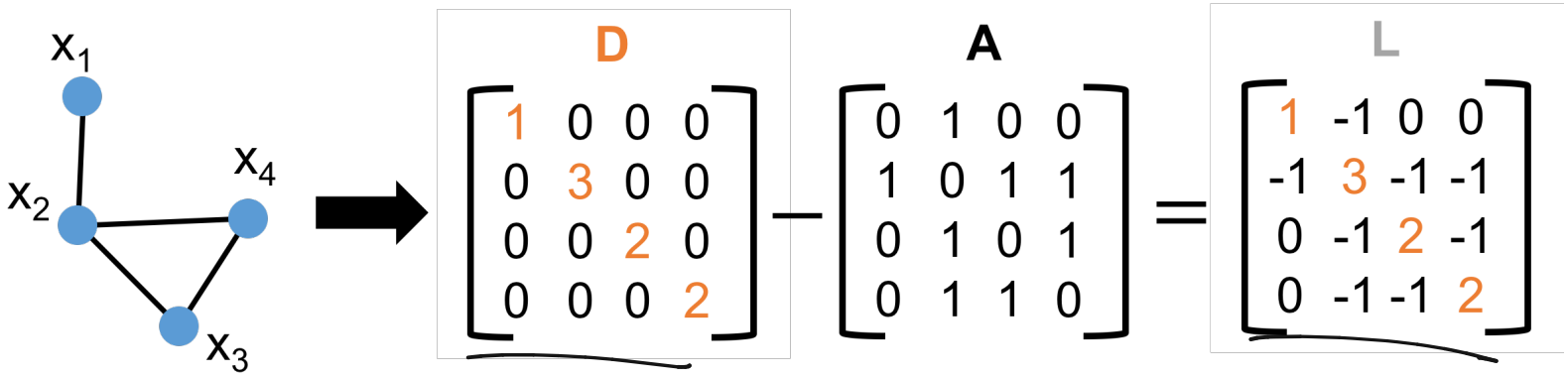
Small cuts are often not informative.

Solution: Encourage cuts that separate large sections of the graph.

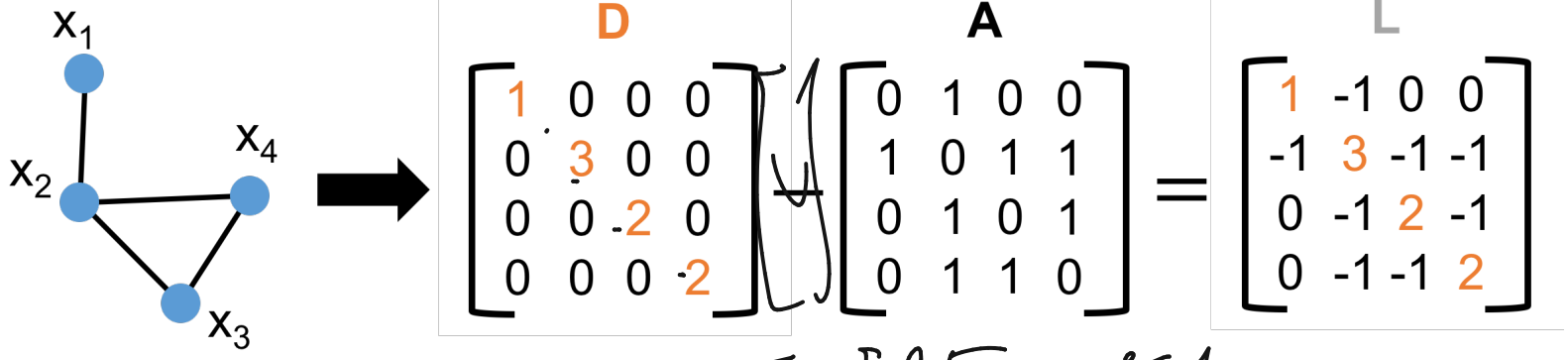
- Let $\vec{v} \in \mathbb{R}^n$ represent a cut: $\vec{v}(i) = 1$ if $i \in S$ and $\vec{v}(i) = -1$ if $i \in T$. Want $\vec{v}$ to have roughly equal numbers of 1s and -1s. I.e., $\vec{v}^T\vec{1} \approx 0$.

THE LAPLACIAN VIEW

For a graph with adjacency matrix $\mathbf{A}$ and degree matrix $\mathbf{D}$, $\mathbf{L} = \mathbf{D} - \mathbf{A}$ is the graph Laplacian.



For a graph with adjacency matrix **A** and degree matrix **D**, $\mathbf{L} = \mathbf{D} - \mathbf{A}$ is the graph Laplacian.



For any vector $\vec{v}$,

$$\vec{v}^T L \vec{v} = \vec{v}^T D \vec{v} - \vec{v}^T A \vec{v} = \sum_{i=1}^{n} d(i)\vec{v}(i)^2 - \sum_{i=1}^{n}\sum_{j=1}^{n} A(i,j) \cdot v(i) \cdot v(j)$$

$$= \sum_{ij \in E} (v(i) - v(j))^2 = \sum_{ij \in E} \left[v(i)^2 + v(j)^2 - 2v(i)v(j) \right]$$

For a cut indicator vector $\vec{v} \in \{-1, 1\}^n$ with $\vec{v}(i) = -1$ for $i \in S$ and $\vec{v}(i) = 1$ for $i \in T$:

$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} (\vec{v}(i) - \vec{v}(j))^2 = 4 \cdot cut(S, T).$$

So minimizing $\vec{v}^T L \vec{v}$ corresponds to minimizing the cut size.

For a cut indicator vector $\vec{v} \in \{-1, 1\}^n$ with $\vec{v}(i) = -1$ for $i \in S$ and $\vec{v}(i) = 1$ for $i \in T$:

$$\vec{v}^T L \vec{V} = \sum_{(i,j) \in E} (\vec{v}(i) - \vec{v}(j))^2 = 4 \cdot cut(S, T).$$

So minimizing $\vec{v}^T L \vec{v}$ corresponds to minimizing the cut size.

$$\arg\min_{v \in \{-1,1\}^n} \vec{v}^T L \vec{V}$$

For a cut indicator vector $\vec{v} \in \{-1, 1\}^n$ with $\vec{v}(i) = -1$ for $i \in S$ and $\vec{v}(i) = 1$ for $i \in T$:

$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} (\vec{v}(i) - \vec{v}(j))^2 = 4 \cdot cut(S, T).$$

So minimizing $\vec{v}^T L \vec{v}$ corresponds to minimizing the cut size.

$$\arg\min_{v \in \mathbb{R}^d \text{ with } \|\vec{v}\|=1} \vec{v}^T L \vec{v}$$

For a cut indicator vector $\vec{v} \in \{-1, 1\}^n$ with $\vec{v}(i) = -1$ for $i \in S$ and $\vec{v}(i) = 1$ for $i \in T$:

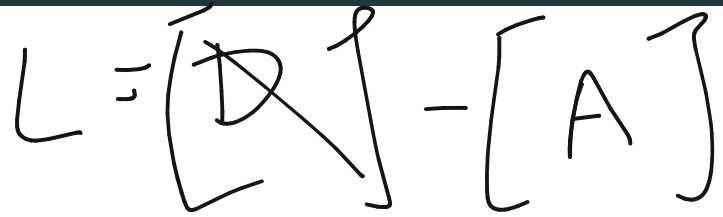
$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} (\vec{v}(i) - \vec{v}(j))^2 = 4 \cdot cut(S, T).$$

So minimizing $\vec{v}^T L \vec{v}$ corresponds to minimizing the cut size.

$$\arg\min_{v \in \mathbb{R}^d \text{ with } \|\vec{v}\|=1} \vec{v}^T L \vec{v}$$

By the Courant-Fischer theorem, $\vec{v}$ is the smallest eigenvector of $L = D - A$.

SMALLEST LAPLACIAN EIGENVECTOR



We have:

$$\vec{v}_n = \frac{1}{\sqrt{n}} \cdot \vec{1} = \underset{v \in \mathbb{R}^d \text{with } \|\vec{v}\|=1}{\arg\min} \vec{v}^T L \vec{V}$$

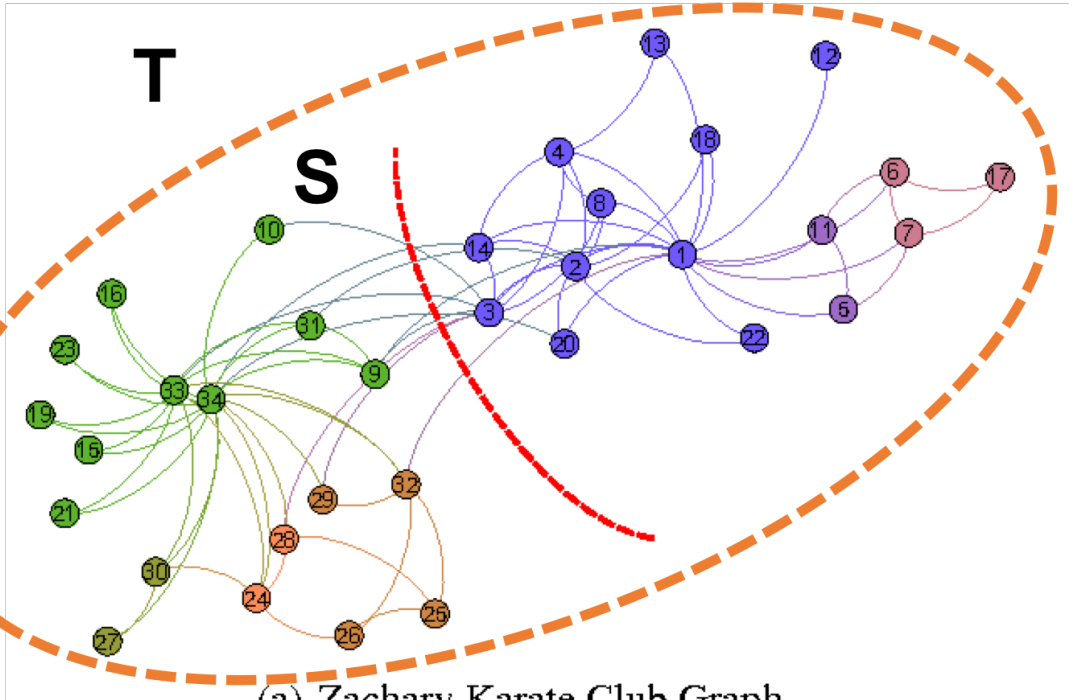
with $\vec{v}_n^T L \vec{v}_n = 0$.

SMALLEST LAPLACIAN EIGENVECTOR

We have:

$$\vec{v}_n = \frac{1}{\sqrt{n}} \cdot \vec{1} = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1}{\arg\min} \vec{v}^T L \vec{V}$$

with $\vec{v}_n^T L \vec{v}_n = 0$.



(a) Zachary Karate Club Graph

SECOND SMALLEST LAPLACIAN EIGENVECTOR

By Courant-Fischer, second small eigenvector is obtained greedily:

$$\vec{v}_1 = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1}{\arg\min} \vec{v}^T L \vec{V}$$

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1,\ \vec{v}_2^T \vec{v}_1 = 0}{\arg\min} \vec{v}^T L \vec{V}$$

SECOND SMALLEST LAPLACIAN EIGENVECTOR

By Courant-Fischer, second small eigenvector is obtained greedily:

$$\vec{v}_1 = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1}{\arg\min} \quad \vec{v}^T L \vec{V}$$

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1,\ \vec{v}_2^T \vec{v}_1 = 0}{\arg\min} \quad \vec{v}^T L \vec{V}$$

If $\vec{v}_2$ were binary $\{-1, 1\}^d$, orthogonality condition ensures that there are an equal number of vertices on each side of the cut.

SECOND SMALLEST LAPLACIAN EIGENVECTOR

By Courant-Fischer, second small eigenvector is obtained greedily:

$$\vec{v}_1 = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1}{\arg\min} \quad \vec{v}^T L \vec{V}$$

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } ||\vec{v}||=1,\ \vec{v}_2^T \vec{v}_1 = 0}{\arg\min} \quad \vec{v}^T L \vec{V}$$

If $\vec{v}_2$ were binary $\{-1, 1\}^d$, orthogonality condition ensures that there are an equal number of vertices on each side of the cut. When $\vec{v}_2 \in \mathbb{R}^d$, enforces a 'relaxed' version of this constraint.

CUTTING WITH THE SECOND LAPLACIAN EIGENVECTOR

Find a good partition of the graph by computing

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } \|\vec{v}\|=1,\ \vec{v}_2^T\vec{1}=0}{\arg\min} \vec{v}^T L \vec{V}$$

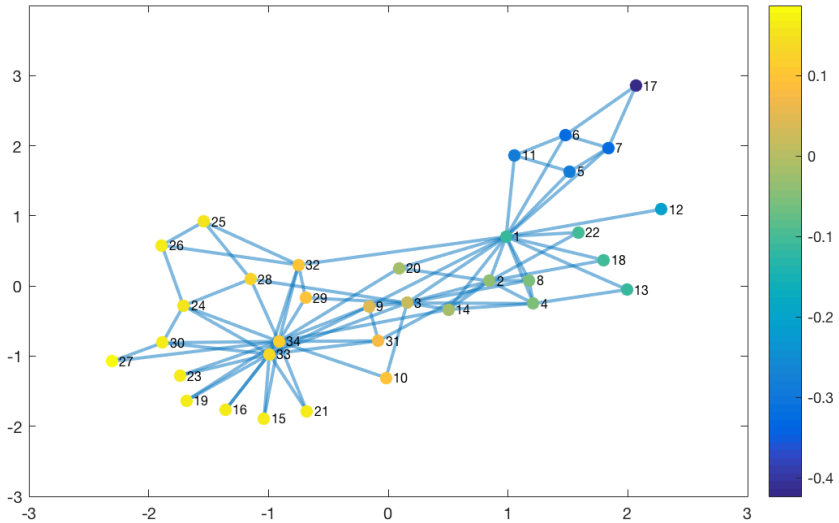
Set S to be all nodes with $\vec{v}_2(i) < 0$, T to be all with $\vec{v}_2(i) \geq 0$.

CUTTING WITH THE SECOND LAPLACIAN EIGENVECTOR

Find a good partition of the graph by computing

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } \|\vec{v}\|=1,\ \vec{v}_2^T\vec{1}=0}{\arg\min} \vec{v}^T L \vec{V}$$

Set S to be all nodes with $\vec{v}_2(i) < 0$, T to be all with $\vec{v}_2(i) \geq 0$.

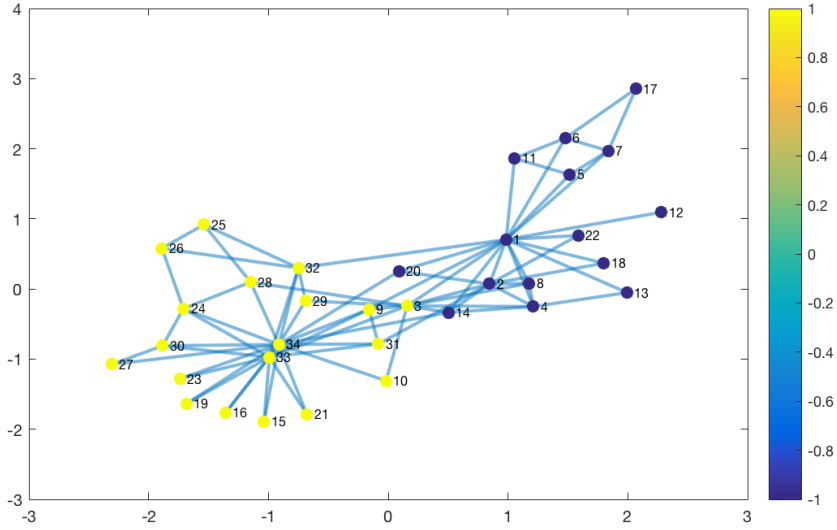


CUTTING WITH THE SECOND LAPLACIAN EIGENVECTOR

Find a good partition of the graph by computing

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } \|\vec{v}\|=1,\ \vec{v}_2^T\vec{1}=0}{\arg\min} \vec{v}^T L \vec{V}$$

Set S to be all nodes with $\vec{v}_2(i) < 0$, T to be all with $\vec{v}_2(i) \geq 0$.

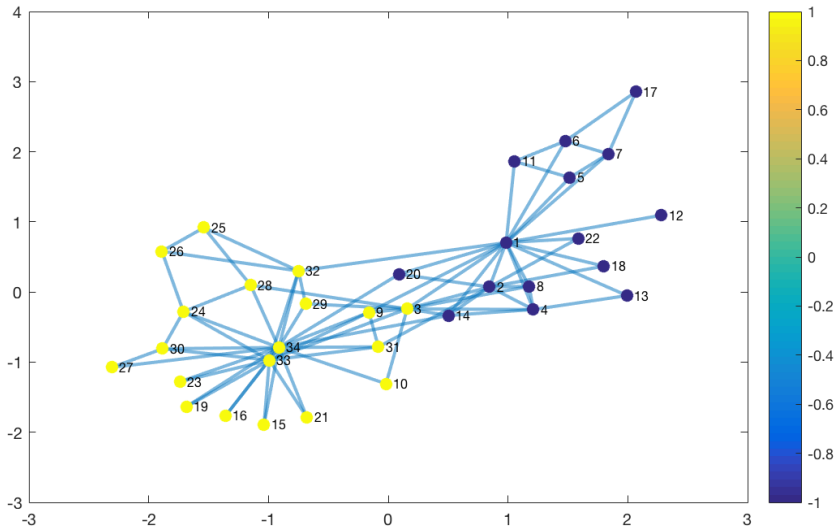


CUTTING WITH THE SECOND LAPLACIAN EIGENVECTOR

Find a good partition of the graph by computing

$$\vec{v}_2 = \underset{v \in \mathbb{R}^d \text{with } \|\vec{v}\|=1,\ \vec{v}_2^T\vec{1}=0}{\arg\min} \vec{v}^T L \vec{V}$$

Set S to be all nodes with $\vec{v}_2(i) < 0$, T to be all with $\vec{v}_2(i) \geq 0$.



The Shi-Malik normalized cuts algorithm is a commonly used variance on this approach, using the normalize Laplacian $\mathbf{D}^{-1/2}\mathbf{L}\mathbf{D}^{-1/2}$.

LAPLACIAN EMBEDDING

The smallest eigenvectors of $\mathbf{L} = \mathbf{D} - \mathbf{A}$ give the orthogonal 'functions' that are smoothest over the graph. I.e., minimize

$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} [\vec{v}(i) - \vec{v}(j)]^2.$$

LAPLACIAN EMBEDDING

The smallest eigenvectors of $\mathbf{L} = \mathbf{D} - \mathbf{A}$ give the orthogonal 'functions' that are smoothest over the graph. I.e., minimize

$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} [\vec{v}(i) - \vec{v}(j)]^2.$$

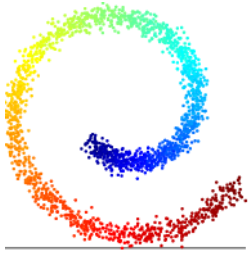
Embedding points with coordinates given by $[\vec{v}_{n-1}(j), \vec{v}_{n-2}(j), \ldots, \vec{v}_{n-k}(j)]$ ensures that coordinates connected by edges have minimum Euclidean distance.

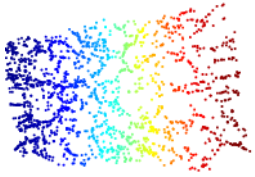
LAPLACIAN EMBEDDING

The smallest eigenvectors of $\mathbf{L} = \mathbf{D} - \mathbf{A}$ give the orthogonal 'functions' that are smoothest over the graph. I.e., minimize

$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} [\vec{v}(i) - \vec{v}(j)]^2.$$

Embedding points with coordinates given by $[\vec{v}_{n-1}(j), \vec{v}_{n-2}(j), \ldots, \vec{v}_{n-k}(j)]$ ensures that coordinates connected by edges have minimum Euclidean distance.



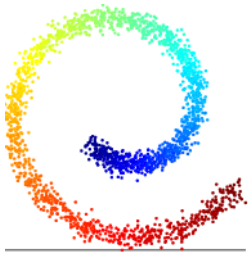


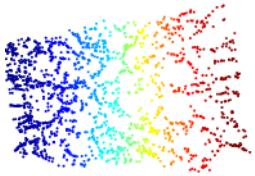
LAPLACIAN EMBEDDING

The smallest eigenvectors of $\mathbf{L} = \mathbf{D} - \mathbf{A}$ give the orthogonal 'functions' that are smoothest over the graph. I.e., minimize

$$\vec{v}^T L \vec{v} = \sum_{(i,j) \in E} [\vec{v}(i) - \vec{v}(j)]^2.$$

Embedding points with coordinates given by $[\vec{v}_{n-1}(j), \vec{v}_{n-2}(j), \ldots, \vec{v}_{n-k}(j)]$ ensures that coordinates connected by edges have minimum Euclidean distance.





- Laplacian Eigenmaps
- Locally linear embedding
- Isomap
- Etc...

Questions?