

Main Idea
Demo: $P(x)$, $E(x)$, motion in 1D
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Generalization: Kinetic Energy
Define $K(\mathbf{p}) = \frac{\mathbf{p}^T \mathbf{p}}{2m}$ kinetic energy $\frac{d\mathbf{x}}{dt} = \frac{\mathbf{p}}{m}$ $\frac{d\mathbf{p}}{dt} = -\frac{\partial E(\mathbf{x})}{\partial \mathbf{x}} \implies \qquad \implies \qquad \frac{d\mathbf{x}}{dt} = \frac{\partial K(\mathbf{p})}{\partial \mathbf{p}}$ $\frac{d\mathbf{p}}{dt} = -\frac{\partial E(\mathbf{x})}{\partial \mathbf{x}}$







Example

Setup: 100D Gaussian, standard deviations in different dimensions are $0.01, 0.02, \ldots, 1.00$

