

Reasoning about Reachability

at Tom Rep's 60th Birthday Celebration

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1978: Tom 22

Neil 24

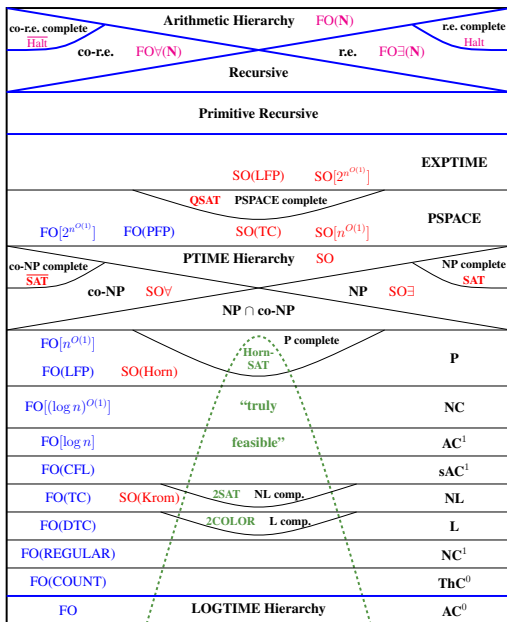
@Cornell

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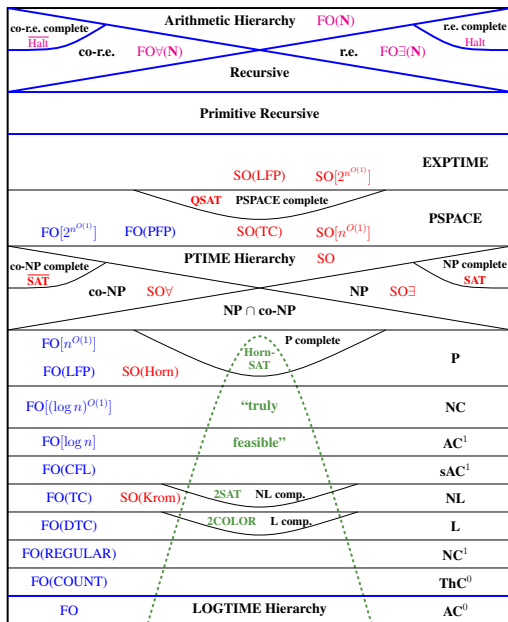
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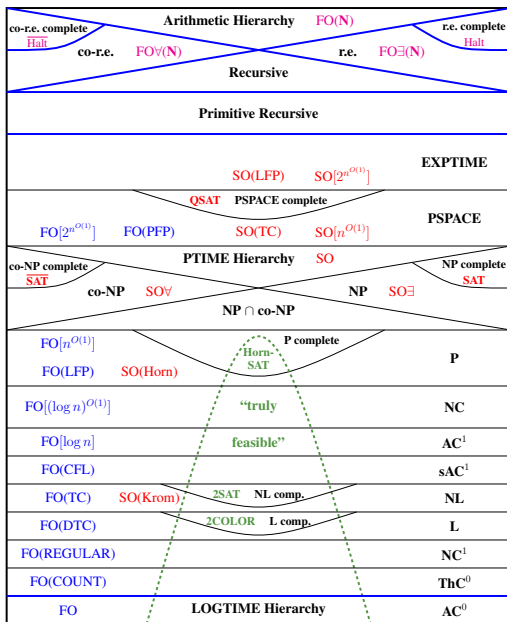
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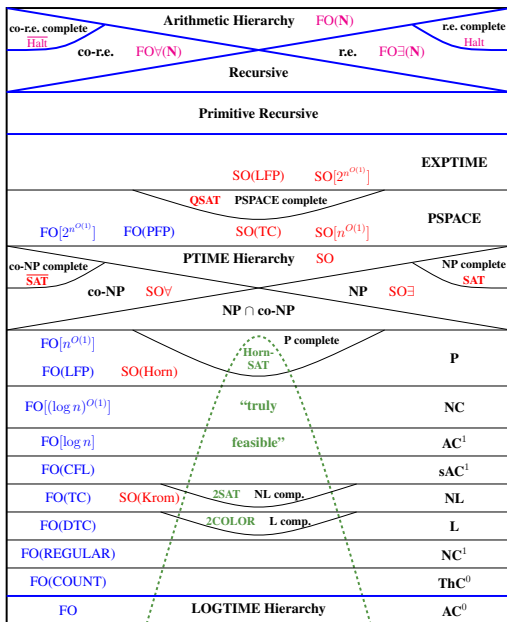
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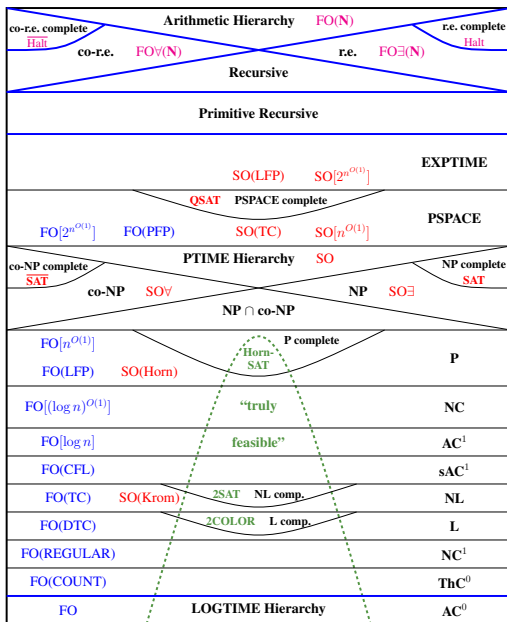
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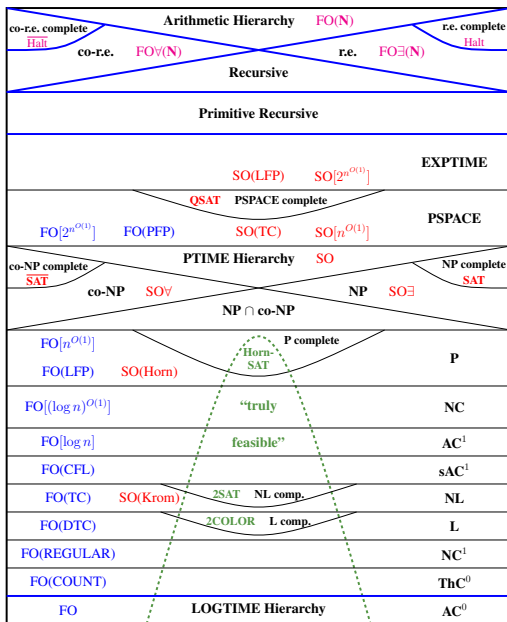
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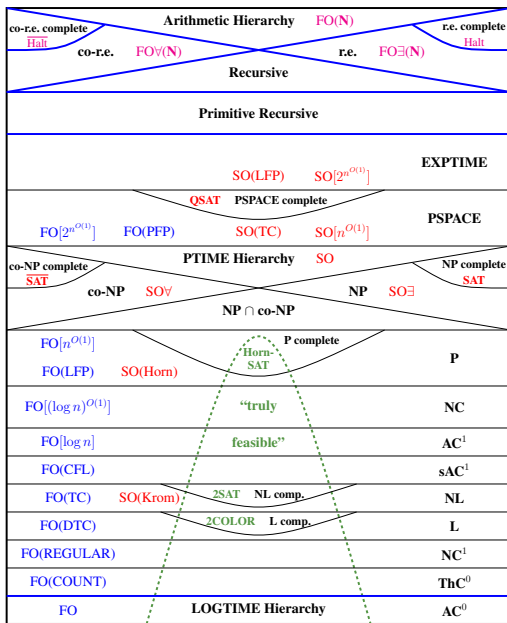
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2016: still
working on it



Static

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4. What **additional information** should we maintain? — **auxiliary data structure**

Dynamic (Incremental) Applications

- ▶ Databases
- ▶ LaTeXing a file
- ▶ Performing a calculation
- ▶ Processing a visual scene
- ▶ Understanding a natural language
- ▶ Verifying a circuit
- ▶ Verifying and compiling a program

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- ▶ Surviving in the wild



Parity

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0000000		0

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	ins (3,S)	

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$$b' \equiv (b \wedge S(a)) \vee (\neg b \wedge \neg S(a))$$

del(a,S)

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Parity

- ▶ Does binary string w have an odd number of 1's?
- ▶ **Static:** TIME[n], FO[$\Omega(\log n / \log \log n)$]
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connectivity,
minimum spanning trees,
 k -edge connectivity, ...

in Dyn-FO

Tom's Question at FLoC 2002

- ▶ In TVLA we build a bounded-size summary of an unbounded data structure, updating it after each program step until we reach a fixed point.

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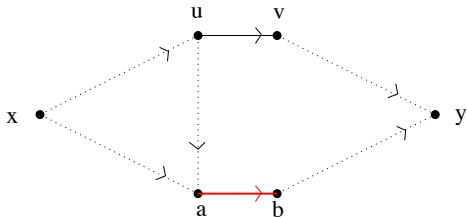
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- ▶ We want to maintain accurate information in that summary concerning pointer reachability.
- ▶ Can some of your ideas for maintaining **auxiliary information** about a dynamic graph in order to compute reachability information **more efficiently**,
- ▶ instead be used in TVLA to keep **auxiliary information** that allows us to maintain reachability information **more accurately**?

Fact: [Dong & Su] $\text{REACH}(\text{acyclic}) \in \text{DynFO}$

ins $(a, b, E) : P'(x, y) \equiv P(x, y) \vee (P(x, a) \wedge P(b, y))$

del (a, b, E) :



$$\begin{aligned} P'(x, y) \equiv & P(x, y) \wedge \left[\neg(P(x, a) \wedge P(b, y)) \right. \\ & \vee (\exists uv)(P(x, u) \wedge E(u, v) \wedge P(v, y) \\ & \left. \wedge P(u, a) \wedge \neg P(v, a) \wedge (a \neq u \vee b \neq v)) \right] \end{aligned}$$

Reachability Problems

REACH = $\{G \mid G \text{ directed, } s \xrightarrow{*}_G t\}$ NL

REACH_d = $\{G \mid G \text{ directed, outdegree} \leq 1, s \xrightarrow{*}_G t\}$ L

REACH_u = $\{G \mid G \text{ undirected, } s \xrightarrow{*}_G t\}$ L

REACH_a = $\{G \mid G \text{ alternating, } s \xrightarrow{*}_G t\}$ P

Facts about dynamic REACHABILITY Problems:

Dyn-REACH(acyclic) \in Dyn-FO [DS]

Dyn-REACH_d \in Dyn-QF [H]

Dyn-REACH_u \in Dyn-FO [PI]

Dyn-REACH \in Dyn-FO(COUNT) [H]

Dyn-PAD(REACH_a) \in Dyn-FO [PI]

Reachability is in DynFO

by Samir Datta, Raghav Kulkarni, Anish Mukherjee, Thomas Schwentick and Thomas Zeume

<http://arxiv.org/abs/1502.07467>

They show that Matrix Rank is in DynFO and REACH reduces to Matrix Rank.

Thm. 1 [Hesse] Reachability of functional DAG is in DynQF.

proof: Maintain E, E^*, D (outdegree = 1).

Insert $E(i, j)$: (ignore if adding edge violates outdegree or acyclicity)

$$E'(x, y) \equiv E(x, y) \vee (x = i \wedge y = j)$$

$$D'(x) \equiv D(x) \vee x = i$$

$$E^{*'}(x, y) \equiv E^*(x, y) \vee (E^*(x, i) \wedge E^*(j, y))$$

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Delete $E(i, j)$:

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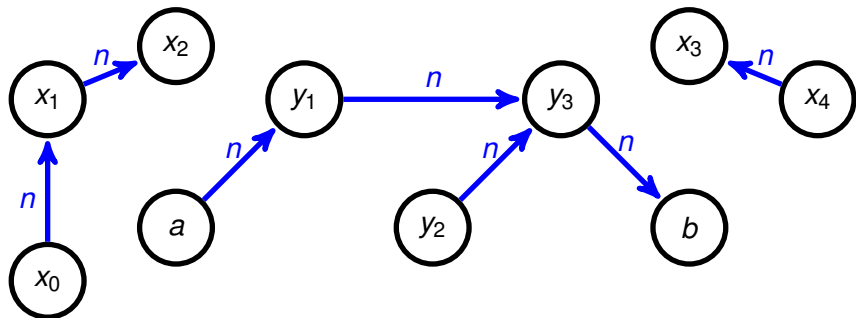
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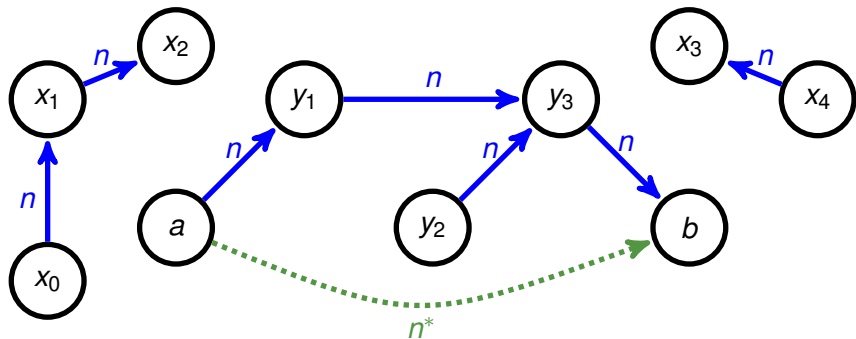
Dynamic Reasoning

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- ▶ Can express tilings and thus runs of Turing Machines.
- ▶ Even worse, can express **finite path** and thus **finite** and thus **standard natural numbers**. Thus FO(TC) is as hard as the Arithmetic Hierarchy [Avron].

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[Itzhaky et. al.]

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$$\mathbf{linear} \equiv \forall xyz (n^*(x, y) \wedge n^*(x, z) \rightarrow n^*(y, z) \vee n^*(z, y))$$

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- ▶ The negation of the correctness condition is $\exists\forall$, thus equi-satisfiable with a propositional formula.
- ▶ Use a SAT solver to automatically prove correctness or find counter-example runs, typically in **only a few seconds**.

Thm. 2 [Hesse] Reachability of functional graphs is in DynQF.

proof idea: If adding an edge, e , would create a cycle, then we maintain relation p^* – the path relation without the edge completing the cycle – as well as E^* , E and D .

Surprisingly this can all be maintained via quantifier-free formulas, **without remembering which edges we are leaving out** in computing p^* . □

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Using Thm. 2, the above methodology has been extended to cyclic deterministic graphs.

- ▶ Itzhaky, Banerjee, Immerman, Aleks Nanevski, Sagiv, “Effectively-Propositional Reasoning About Reachability in Linked Data Structures” CAV 2013.
- ▶ Itzhaky, Banerjee, Immerman, Lahav, Nanevski, Sagiv, “Modular Reasoning about Heap Paths via Effectively Propositional Formulas”, POPL 2014

Thank You!

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Sharon Shoham, Siddharth Srivastava, Greta Yorsh