

# On the Difficulty of Unbiased Alpha Divergence Minimization

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## Overview and Summary

- Variational Inference minimizes  $\text{KL}(q||p)$ .
- Could target alpha-divergence

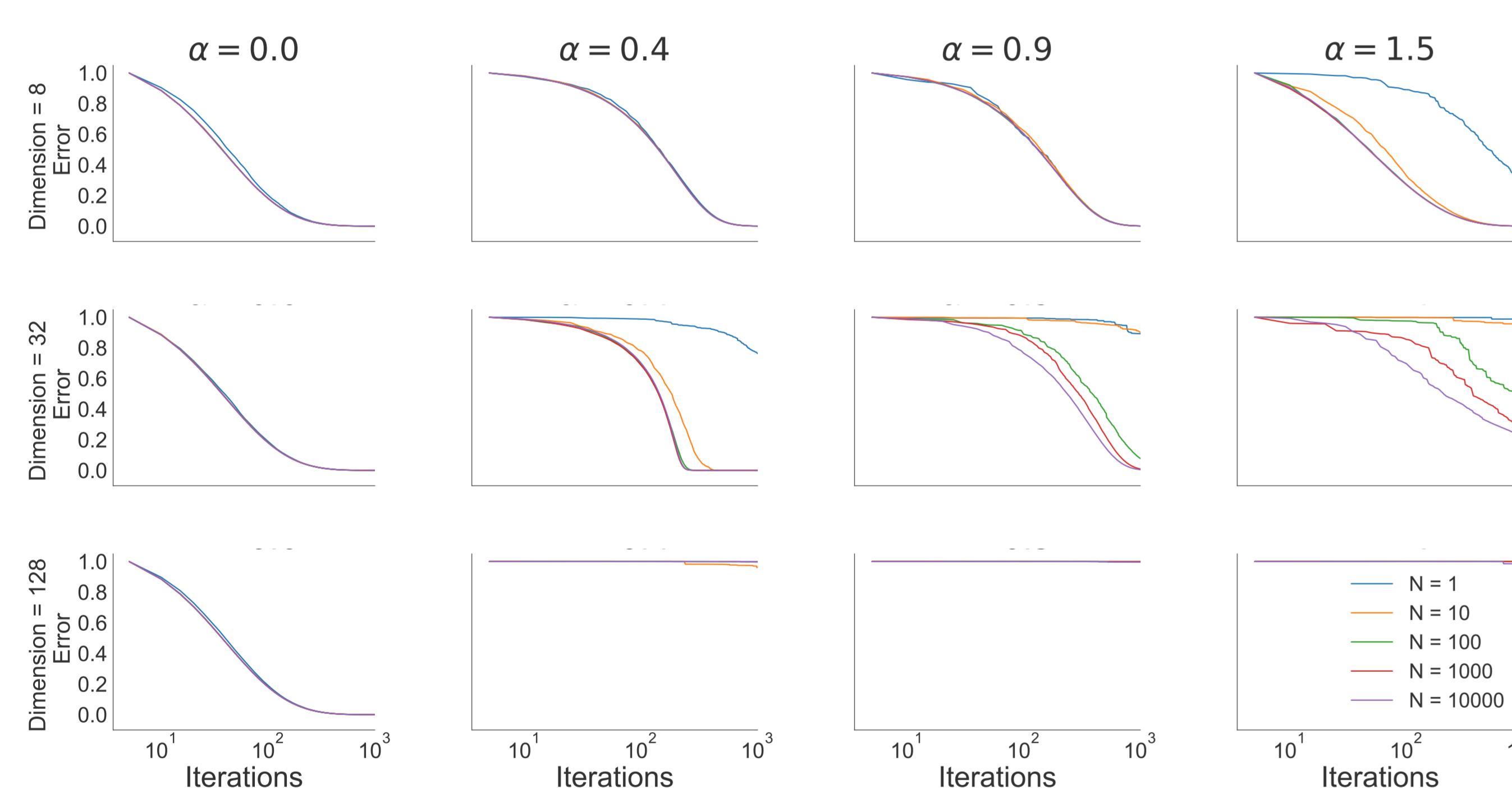
$$D_\alpha(p||q) = \frac{1}{\alpha(\alpha-1)} \mathbb{E}_{q(z)} \left[ \left( \frac{p(z)}{q(z)} \right)^\alpha - 1 \right].$$

- Previous work: use unbiased reparameterization gradients.
- We observe this often fails in high dimensions and high alpha.
- Why? Estimator's SNR decreases exponentially with dimension.

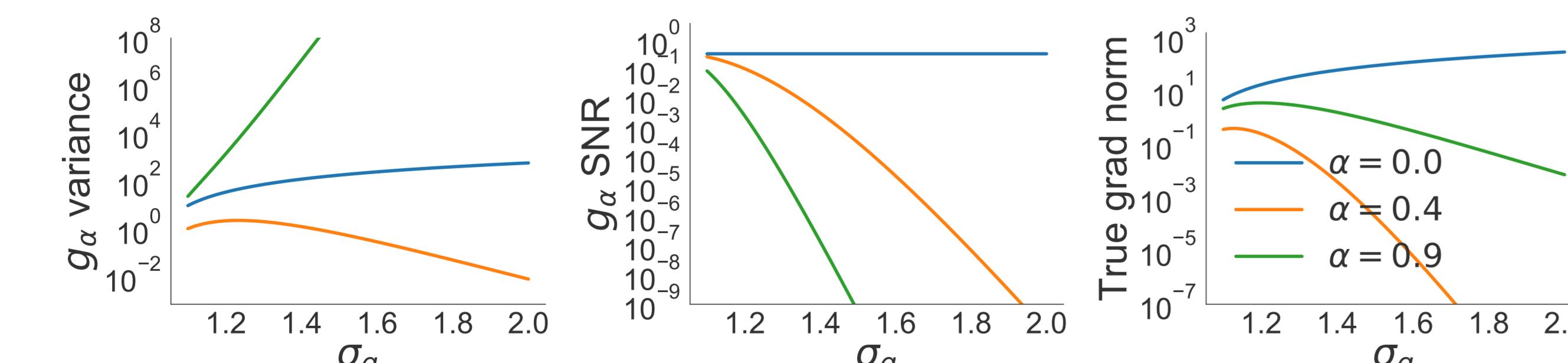
We use  $\text{SNR}[X] = \frac{\mathbb{E}\|X\|^2}{\mathbb{E}\|X\|^2} \leq 1$ .

## Motivating example

- $p$  and  $q$  factorized Gaussians with mean zero and variances  $\sigma_{pi}^2 = 1, \sigma_{qi}^2 = 4$ .
- Find parameters  $\sigma_{qi}$  that minimize alpha-divergence.
- (Solution easy, just want simple empirical test for estimator.)



Variance alone does not explain failure, SNR does:



## Fully Factorized Distributions

**Theorem.** Let  $p(z) = \prod_{i=1}^d p_i(z_i)$  and  $q(z) = \prod_{i=1}^d q_i(z_i)$ , and let  $g(p, q)$  be the unbiased reparameterization estimator of the alpha-divergence between  $p$  and  $q$ . Then

$$\begin{aligned} \text{SNR}[g_j(p, q)] &= \text{SNR}[g(p_j, q_j)] && \text{if } \alpha \rightarrow 0 \\ \text{SNR}[g_j(p, q)] &= \text{SNR}[g(p_j, q_j)] \prod_{i=1, i \neq j}^d \text{SNR}[\tilde{D}_\alpha(p_i, q_i)] && \text{if } \alpha \neq 0, \end{aligned}$$

where  $\tilde{D}_\alpha(p_i, q_i)$  is an unbiased estimator (up to constants) of  $D_\alpha(p_i, q_i)$ .

Simply put:

- If  $\alpha \rightarrow 0$  the SNR is just the SNR of the gradient estimator of a divergence between two 1-dimensional distributions.
- If  $\alpha \neq 0$  the SNR includes the product of  $d$  terms, all less than one (unless  $p_i = q_i$ ).

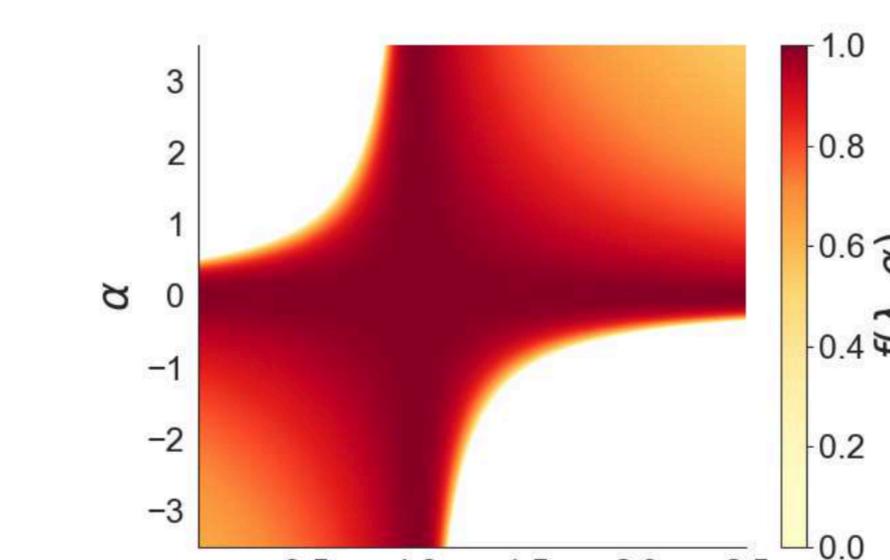
**Corollary:** Let  $p$  and  $q$  be mean-zero factorized Gaussians with vars  $\sigma_{pi}^2, \sigma_{qi}^2$ . Let  $\lambda_i = \frac{\sigma_{qi}^2}{\sigma_{pi}^2}$ . Then, if all expectations exist,

$$\text{SNR}[g_j(p, q)] = \underbrace{\frac{1+2\alpha(\lambda_j-1)}{3}}_{\text{SNR}[g(p_j, q_j)]} f(\lambda_j, \alpha)^3 \prod_{i=1, i \neq j}^d \underbrace{\text{SNR}[\tilde{D}_\alpha(p_i, q_i)]}_{f(\lambda_i, \alpha)},$$

where

$$f(\lambda, \alpha) = \frac{1}{\sqrt{1 + \alpha^2 \frac{(\lambda-1)^2}{1+2\alpha(\lambda-1)}}}.$$

Simply put, the SNR contains the product of  $d$  terms all less than one, which get smaller for alpha far from zero and for  $p$  and  $q$  very different.



## Full Rank Gaussians

**Theorem.** Let  $p$  and  $q$  be mean-zero Gaussians with covariances  $\Sigma_p$  and  $\Sigma_q$ . Let  $\lambda_1, \dots, \lambda_d$  be the eigenvalues of  $\Sigma_p^{-1} \Sigma_q$ . Then, if all expectations exist,

$$\text{SNR}[(p, q)] = \frac{1}{d+2} \quad \text{if } \alpha \rightarrow 0,$$

$$\text{SNR}[(p, q)] \leq \left( \frac{1+\alpha(\lambda_{\min}-1)}{1+2\alpha(\lambda_{\max}-1)} \right)^2 \prod_{i=1}^d f(\lambda_i, \alpha) \quad \text{if } \alpha > 0.$$

## Empirical Evaluation

- Bayesian logistic regression.
- Two datasets: *iris* ( $d = 4$ ) and *australian* ( $d = 14$ ).

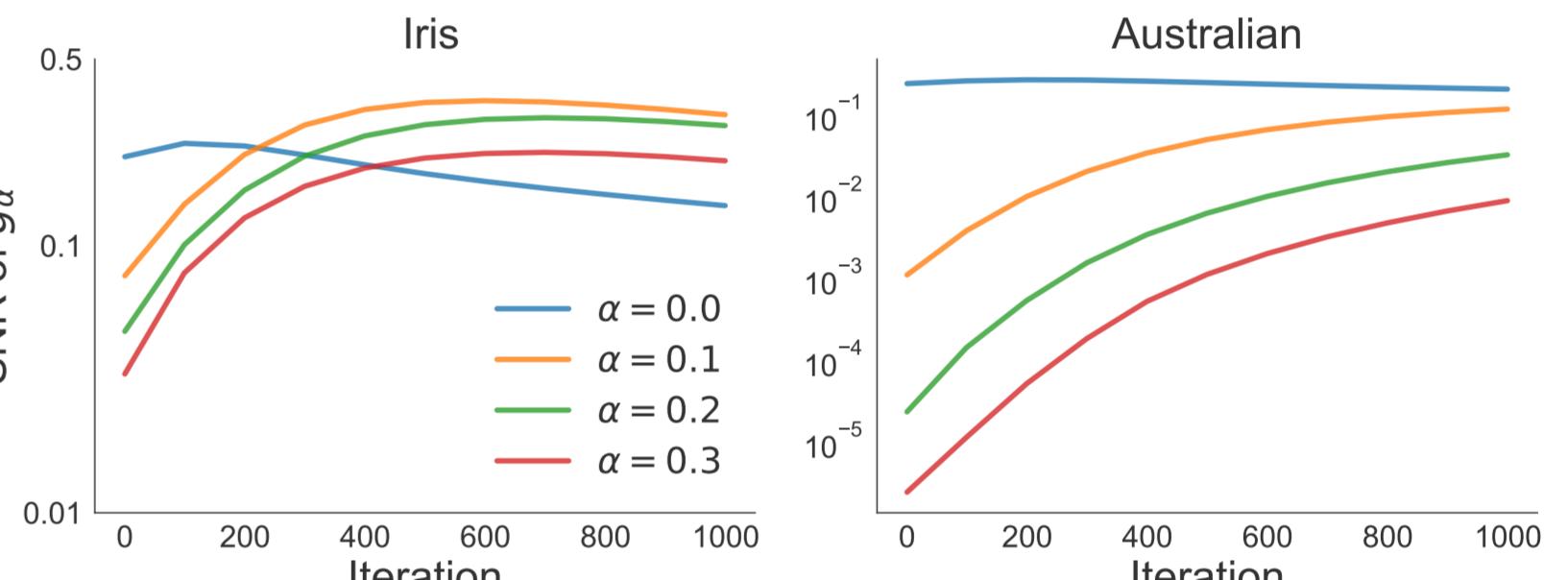
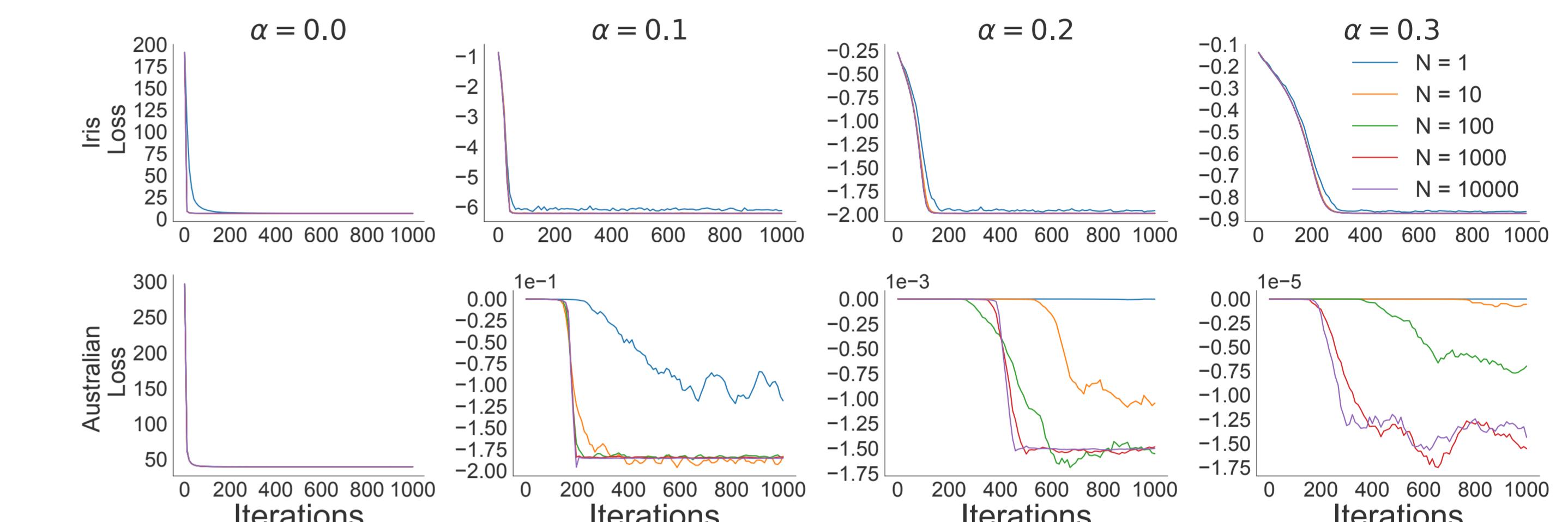


Figure 1: SNR along a single optimization trace.

## Final thoughts

- Optimization theory suggests that an exponential amount of computation time would be needed to optimize the objectives.
- One might hope to guarantee a good SNR under some assumptions about the target. For example, if the log-posterior were fully-factorized, concave, strongly concave, Lipschitz smooth, or Gaussian. Our results show that, for general alpha-divergences, no such guarantee is possible.
- A general-purpose algorithm for optimizing an alpha-divergence based on currently available unbiased gradient estimators may be unachievable.
- Other optimizers (e.g. Adam) do not fix the issue.

