# THE SAMPLE COMPLEXITY OF TOEPLITZ COVARIANCE ESTIMATION 

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Joint with Yonina Eldar, Jerry Li, and Christopher Musco.

## TOEPLITZ COVARIANCE ESTIMATION

Covariance Estimation Problem. Consider positive semidefinite matrix $T \in \mathbb{R}^{d \times d}$ and distribution $\mathcal{D}$ over d-dimensional vectors with covariance $\mathbb{E}_{x \sim \mathcal{D}}\left[x x^{\top}\right]=T$ (i.e., $T_{j, k}$ is the covariance between $x_{j}$ and $x_{k}$ ).

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\mathrm{c} & \mathrm{~b} & \mathrm{a} & \mathrm{~b} & \mathrm{c} \\
\mathrm{~d} & \mathrm{c} & \mathrm{~b} & \mathrm{a} & \mathrm{~b} \\
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Arises often in signal processing, when measurements are taken on a spatial or temporal grid and covariance depends only on the distance between them - i.e., $\mathbb{E}\left[x_{j} \cdot x_{k}\right]=f(|j-k|)$.


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- Applications: spectrum sensing, Doppler radar, direction of arrival estimation, prediction via Gaussian process regression, etc.
- Kernel matrices in machine learning are Toeplitz covariance matrices when data points are on a grid.


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- Total sample complexity: Total number of entries read, n•s.
- Seems to be interesting even beyond Toeplitz covariance matrices, but not well studied.


## EXAMPLE: DIRECTION OF ARRIVAL ESTIMATION

narrowband signal:
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With delay, $\mathbb{E}\left[x_{k}^{(j)} \cdot x_{\ell}^{(j)}\right] \approx \mathbb{E}\left[a(t)^{2}\right] \cdot \cos \left(f \Delta_{k, \ell}\right)$


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- Show that sparse ruler methods give sublinear total sample complexity when $T$ is low-rank (e.g., DOA with $k \ll d$ senders).


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## Our contributions:

- Give non-asymptotic sample complexity bounds by analyzing classic algorithms, including those with sublinear entry sample complexity based on sparse ruler measurements.
- Show that sparse ruler methods give sublinear total sample complexity when $T$ is low-rank (e.g., DOA with $k \ll d$ senders).
- Develop improved algorithms in the low-rank setting using techniques from matrix sketching, leverage score-based sampling, and sparse Fourier transforms. Resemble popular 'subspace methods' such as MUSIC and ESPRIT.


## BROADER AGENDA

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- Column-based matrix approximation, combinatorial sparsification $\Longleftrightarrow$ nonlinear function approximation, Fourier-sparse approximations


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Apply tools from TCS to tackle fundamental signal processing problems. A Universal Sampling Method for Reconstructing Signals with Simple Fourier Transforms [AKMMVZ STOC '19]

## SUBSET BASED ESTIMATION

For today, consider algorithms that sample $x^{(1)}, \ldots, x^{(n)} \sim \mathcal{D}$ with covariance $T$, read a fixed subset of entries $R \subseteq[d]$ from each $x^{(j)}$, and approximate $T$ using $x_{R}^{(1)}, \ldots, x_{R}^{(n)} \in \mathbb{R}^{|R|}$.

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Entry sample complexity: $|R|$. Total sample complexity: $|R| \cdot n$.

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T_{1}=\left[\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right] \quad \text { vs. } \quad T_{2}=\left[\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 1 \\
0 & 0 & 1 & 0 \\
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To notice correlation between $x_{j}$ and $x_{k}$ must read both.

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Will see that we can achieve $|R|=O(\sqrt{d})$.

## SPARSE RULER BASED ESTIMATION

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E.g., for $d=10, R=\{1,2,5,8,10\}$ is a ruler.


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Claim For any $d$ there exists a sparse ruler $R$ with $|R|=2 \sqrt{d}$

- Suffices to take $R=[1,2, \ldots, \sqrt{d}] \cup[2 \sqrt{d}, 3 \sqrt{d}, \ldots, d]$.



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- If $R$ is a ruler, for each $s \in\{0, \ldots, d-1\}$, there is at least one $k, \ell \in R$ with $|k-\ell|=s$ and thus with covariance

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- Get at least one independent sample of $a_{s}$ from every $x_{R}^{(j)}$.
- With enough samples $n$ from $\mathcal{D}$, will converge on an estimate of each $a_{s}$ and so of the full matrix $T$.


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- How does the total sample complexity compare to methods that read every entry of each $x^{(j)}$, e.g., estimating $T$ with the empricial covariance $\hat{T}=\frac{1}{n} \sum_{j} x^{(j)} X^{(j)^{T}}$.


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- Setting $\varepsilon^{\prime}=\varepsilon / \sqrt{d}, n=\tilde{O}\left(\frac{d}{\varepsilon^{2}}\right)$ would give

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\|\tilde{T}-T\|_{2} \leq \varepsilon \leq \varepsilon\|T\|_{2}
$$

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- In the worst case, $\|\tilde{T}-T\|_{2}=\varepsilon d$ but if $\varepsilon_{s}$ were independent, $\|\tilde{T}-T\|_{2} \leq \varepsilon \sqrt{d}$ [Meckes '07].
- Setting $\varepsilon^{\prime}=\varepsilon / \sqrt{d}, n=\tilde{O}\left(\frac{d}{\varepsilon^{2}}\right)$ would give

$$
\|\tilde{T}-T\|_{2} \leq \varepsilon \leq \varepsilon\|T\|_{2}
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## SPARSE RULER SAMPLE COMPLEXITY

Theorem. For any ruler $R \subset[d]$, covariance estimation with $R$ gives $\|\tilde{T}-T\|_{2} \leq \varepsilon\|T\|_{2}$ with entry sample complexity $|R|$ and vector sample complexity $n=\tilde{O}\left(\frac{d}{\varepsilon^{2}}\right)$.

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- Vector sample complexity matches the complexity of estimating an unstructured covariance with the empirical covariance but entry sample complexity can be $O(\sqrt{d})$ instead of $d$.
- Proof uses the Fourier structure of Toeplitz matrices.


## SPARSE RULER PROOF SKETCH

Algorithm: For each $s \in\{0,1\}$ approximate $a_{s}$ by average over the ruler $R$ :
$\tilde{a}_{s}=\frac{1}{n\left|R_{s}\right|} \sum_{j=1}^{n} \sum_{(k, \ell) \in R_{s}} x_{k}^{(j)} \cdot x_{\ell}^{(j)}$ where $R_{s}=\{k, \ell \in R:|k-\ell|=s\}$.
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- Let $E=T-\tilde{T}$ and $e=a-\tilde{a}$. We want to bound $\|E\|_{2}$.


## SPARSE RULER PROOF SKETCH

Entry approximation to matrix approximation: Can bound $\|\tilde{T}-T\|_{2}=\|E\|_{2}$ in terms of the Fourier transform of $e$.

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Formulation as Trace Bound: For fixed $f$ let $M_{f}$ be the Toeplitz matrix with $\left(M_{f}\right)_{j, k}=\frac{\sin (2 \pi s f)}{\left|R_{s}\right|}$ when $|j-k|=s$.

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Can rewrite the Fourier transform as:

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\|\tilde{T}-T\|_{2} \leq \max _{f \in[0,1]} \sum_{s=0}^{d}\left[a_{s}-\tilde{a}_{s}\right] \cdot \sin (2 \pi s f)=\max _{f \in[0,1]} \operatorname{tr}\left(T_{R}-\tilde{T}_{R}, M_{f}\right)
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- Setting $\varepsilon^{\prime}=\varepsilon / \sqrt{d}$ and union bounding over a net of $f$ values gives our $n=\tilde{O}\left(d / \varepsilon^{2}\right)$ bound.
- The more coverage $R$ has (the larger the $\left|R_{s}\right|$ is on average), the smaller $\left\|M_{f}\right\|_{F}$ will be. Let's us interpolate between minimal entry sample complexity and minimal vector sample complexity.


## FULL RULER SAMPLE COMPLEXITY

For $R=[d]$, coverage is maximal and $\left\|M_{f}\right\|_{F}=O(\sqrt{\log d})$, letting us achieve vector sample complexity $n=\tilde{O}\left(\frac{1}{\varepsilon^{2}}\right)$.

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True covariance $T$


Empirical covariance $\widehat{T}$


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True covariance $T$


Empirical covariance $\hat{T}$


Improved estimator $\operatorname{avg}(\widehat{T})$

- Improves on sample complexity of just using the empirical covariance by a $\tilde{O}(d)$ factor.


## SPARSE RULER VS. FULL RULER

Total sample complexity is $O(\sqrt{d}) \cdot \tilde{O}(d)=\tilde{O}\left(d^{3 / 2}\right)$ for sparse ruler vs. $d \cdot \tilde{O}(1)=\tilde{O}(d)$ for full sample estimation.

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- Prove bounds are tight when $T$ is the identity.


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- Total sample complexity is $\tilde{O}(\sqrt{d})$ for sparse ruler estimation vs. $\tilde{O}(d)$ for full sample estimation.
- Sparse rulers give much better total sample complexity when $T$ is (approximately) low-rank. Can we explain this?


## SPARSE RULERS FOR LOW-RANK MATRICES

Recall that we have with $n=\tilde{O}\left(1 / \varepsilon^{2}\right)$ samples:

$$
\|T-\tilde{T}\|_{2} \leq \varepsilon\left\|T_{R}\right\|_{2} \cdot\left\|M_{f}\right\|_{F} \leq \varepsilon\left\|T_{R}\right\|_{2} \sqrt{d} \leq \varepsilon\|T\|_{2} \sqrt{d} .
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- Low-rank matrices cannot look like the identity - have significant off diagonal mass [MMW '19].
- Upshot: Show $\left\|T_{R}\right\|_{2} \leq \frac{k}{\sqrt{d}}\|T\|_{2}$. Setting $\varepsilon^{\prime}=\varepsilon / k$ obtain total sample complexity Õ $\left(\frac{\sqrt{d} k^{2}}{\varepsilon^{2}}\right)$.


## AN APPROACH VIA FOURIER METHODS

Remainder of the talk: Will sketch a different approach to low-rank Toeplitz covariance estimation using sparse Fourier transform methods.

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- Connections between these two approaches.


## THE FOURIER PERSPECTIVE

Vandermonde Decomposition: Any rank- $k$ Toeplitz $T \in R^{d \times d}$ can be written as $F_{S} D F_{S}$ where $F_{S} \in \mathbb{R}^{d \times k}$ is an 'off-grid' Fourier transform matrix with frequencies $f_{1}, \ldots, f_{k}$ and $D$ is a positive diagonal matrix.


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- Any sample $x \sim \mathcal{N}(0, T)$ can be written as $F_{S} D^{1 / 2} g$ for $g \sim \mathcal{N}(0, I) . \mathbb{E}\left[x x^{\top}\right]=F_{S} D^{1 / 2} \mathbb{E}\left[g g^{\top}\right] D^{1 / 2} F_{S}^{*}=T$.


## SAMPLE RECOVERY VIA SPARSE FOURIER TRANSFORM

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x \sim \mathcal{N}(0, T)=F_{S} D^{1 / 2} g \text { is a Fourier sparse function. }
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- Can recover exactly e.g. via Prony’s sparse Fourier transform method by reading any $2 k$ entries.
- Take $n=\tilde{O}\left(1 / \varepsilon^{2}\right)$ samples, recover each in full by reading $2 k$ entries, and then apply our earlier resut for full ruler $R=[d]$. Total sample complexity: $\tilde{O}\left(k / \varepsilon^{2}\right)$.


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What about when $T$ is close to, but not exactly rank- $k$ ?

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Step 2: Use a robust sparse Fourier transform method to approximately recover $x^{(1)}, \ldots, x^{(n)}$ and then estimate $T$ from these samples.

- Well studied in TCS, especially in the case when $f_{1}, \ldots, f_{k}$ are 'on grid' integer frequencies.


## FREQUENCY-BASED LOW-RANK APPROXIMATION

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Theorem: Any $A \in \mathbb{R}^{n \times d}$, contains a subset of $O(k / \varepsilon)$ columns, C such that:

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\left\|A-P_{C} \cdot A\right\|_{F}^{2} \leq(1+\varepsilon) \min _{\text {rank }-k M}\|A-M\|_{F}^{2}
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## RECOVERING A SPARSE REPRESENTATION

Step 2: Recover frequencies $f_{1}, \ldots, f_{m}$ and $Z \in \mathbb{C}^{m \times n}$ with $X \approx F_{M} \cdot Z$. Then estimate $T$ using this approximation.

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- Find frequencies via brute force search over a net.
- At each step of the search, for a given $F_{M}$, we must find $Z$ that reconstructs $X$ as well as possible using these frequencies. How do we do this without reading all of $X$ ?


## APPROXIMATE FREQUENCY REGRESSION

Want to find $Z$ satisfying the approximate regression guarantee:

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\left\|X-F_{M} Z\right\|_{F}^{2}=O(1) \cdot \min _{Y}\left\|X-F_{M} Y\right\|_{F}^{2} .
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- Suffices to sample $\tilde{O}(k)$ rows by the leverage scores of $F_{M}$ and solve the regression problem just considering these rows.
- Remark: If $f_{1}, \ldots, f_{m}$ are 'on-grid' integers, the columns of $F_{M}$ are orthonormal and the leverage scores are all $k / n$


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Want to find $Z$ satisfying the approximate regression guarantee:

$$
\left\|X-F_{M} Z\right\|_{F}^{2}=O(1) \cdot \min _{Y}\left\|X-F_{M} Y\right\|_{F}^{2} .
$$



- Suffices to sample $\tilde{O}(k)$ rows by the leverage scores of $F_{M}$ and solve the regression problem just considering these rows.
- Remark: If $f_{1}, \ldots, f_{m}$ are 'on-grid' integers, the columns of $F_{M}$ are orthonormal and the leverage scores are all $k / n \rightarrow$ RIP for subsampled Fourier matrices.


## FOURIER LEVERAGE SCORES

Leverage scores measure much large a function in the column span of $F_{M}$ can be at index $i$ (i.e., how important that index may be in the regression.)

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- Using that $F_{M y}$ is a Fourier sparse function we can bound this quantity a priori, without any dependence on $F_{M}$.


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Extend bounds of [Chen Kane Price Song '16] to give explicit function upper bounding the leverage scores of any $F_{M}$ :


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Since this distribution is universal, can sample one set of entries by these leverages scores, and find $X \approx F_{M} \cdot Z$ with high probability for any set of frequencies $f_{1}, \ldots, f_{m}$ in net.

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Z=\underset{Z \in \mathbb{C}^{m} \times n}{\arg \min }\left\|X_{R}-\left(F_{M}\right)_{R} Z\right\|_{F}^{2}
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Sample Complexity: Gives $\|T-\tilde{T}\|_{2} \leq \varepsilon\|T\|_{2}+f\left(T-T_{k}\right)$ when $X$ contains $n=\tilde{O}(\operatorname{poly}(k / \epsilon))$ samples. Entry sample complexity $\operatorname{poly}(k / \varepsilon)$, total sample complexity $\tilde{O}(\operatorname{poly}(k / \varepsilon))$.

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- 'Continuous’ setting with sample access to a arbitrary positions of a signal with stationary covariance. (E.g., $x^{(1)}, \ldots, x^{(n)}$ may be snapshots of this signal.)
- Sample complexity bounds and tradeoffs for applications like direction-of-arrival estimation, Doppler imaging.


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- Also connected to multi-coset and non-uniform sampling schemes used in signal processing.
- Seem to have a lot more to understand.


# Thanks! Questions? 

Paper draft and slides available at cameronmusco.com

