COMPSCI 614: Randomized Algorithms with Applications to Data Science

Prof. Cameron Musco University of Massachusetts Amherst. Spring 2024. Lecture 8

- Problem Set 2 is due next Wednesday.
- One page project proposal due Tuesday 3/12.
- No quiz this week focus on the problem set/project proposal.

Last Time:

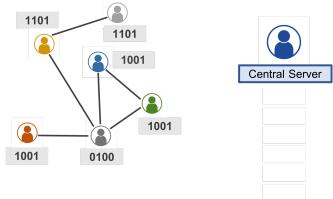
- Graph connectivity with low communication
- Approach via Boruvka's algorithm and sparse recovery/ $\ell_{\rm 0}$ sampling.

Today:

- Finish up ℓ_0 sampling analysis.
- Other approaches to sparse recovery and applications to data processing in streams.
- The count-sketch algorithm.

ℓ_0 Sampling and Graph Sketching

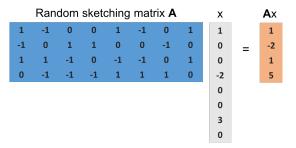
Consider *n* nodes, each only knows its own neighborhood. They want to send messages to a central server, who will then determine if the graph is connected.



Saw how this can be accomplished via ℓ_0 sampling using with messages of size just $O(\log^3 n)$.

Key Ingredient 1: ℓ_0 Sampling

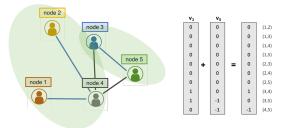
Theorem: There exists a distribution over random matrices $\mathbf{A} \in \mathbb{Z}^{O(\log^2 n) \times n}$ such that for any fixed $x \in \mathbb{Z}^n$, with probability at least $1 - 1/n^c$, we can learn (i, x_i) for some $x_i \neq 0$ from $\mathbf{A}x$.



Key Property: Given sketches Ax_1 and Ax_2 , can easily compute $A(x_1 + x_2)$ and recover a nonzero entry from $x_1 + x_2$ with high probability.

Simulating Boruvka's Algorithm via Sketches

- For independent l₀ sampling matrices A₁,..., A_{log₂}, each node computes A_jv_i and sends these sketches to the central server.
 O(log³ n) bits in total.
- The central server uses A₁v₁,..., A₁v_n to simulate the first step of Boruvka's – i.e., to identify one outgoing edge from each node.
- For each subsequent step *j*, let S_1, S_2, \ldots, S_c be the current connected components. Observe that $\sum_{i \in S_k} v_i$ has non-zero entries corresponding exactly to the outgoing edges of S_k .



• So, from $A_i \sum_{i \in S} v_i = \sum_{i \in S} A_i v_i$, the server can find an outgoing

Implementing ℓ_0 Sampling

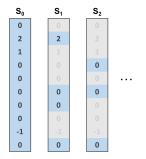
ℓ_0 Sampling Construction

Construction:

- Let $S_0, S_1, \ldots, S_{\log_2 n}$ be random subsets of [n]. Each element is included in S_j independently with probability $1/2^j$.
- For each S_j , compute $a_j = \sum_{i \in S_j} x_i$, $b_j = \sum_{i \in S_j} x_i \cdot i$ and $c_j = \sum_{i \in S_j} x_i \cdot r^i \mod p$, where r is a random value in [p] and p is a prime with $p \ge n^c$ for some large constant c.
- **Observe:** The vector $[a_1, \ldots, a_{\log_2 n}, b_1, \ldots, b_{\log_2 n}, c_1, \ldots, c_{\log_2 n}]$ can be written as **A**x, where $\mathbf{A} \in \mathbb{Z}^{3 \log_2 n \times n}$ is a random matrix.

Construction Intuition

We will recover a nonzero element from a sampling level when there is exactly one nonzero element at that level.



With good probability, there is will exactly one element at some level. Can improve success probability via repetition.

 $S_0, \ldots, S_{\log_2 n}$ are random subsets of [n], sampled at rates $1/2^j$. $a_j = \sum_{i \in S_j} x_i, b_j = \sum_{i \in S_j} x_i \cdot i$ and $c_j = \sum_{i \in S_j} x_i \cdot r^i \mod p$, where r is a random value in [p] and $p = n^c$ for large enough constant c.

Claim 1: If there is a unique $i \in S_j$ with $x_i \neq 0$, then $a_j = x_i$ and $b_j = x_i \cdot i$. So, from these quantities we can exactly determine (i, x_j) .

Claim 2: c_j lets us test if there is a unique such *i*. In particular, we check that $\frac{b_j}{a_i} \in [n]$ and that $c_j = a_j \cdot r^{b_j/a_j} \mod p$.

- If there is a unique $i \in S_i$ with $x_i \neq 0$, the test passes.
- If not, it fails with probability at most $\frac{n}{p} = \frac{1}{n^{c-1}}$.

Recovering Unique Nonzeros

Claim 2: c_j lets us test if there is a unique such *i*. In particular, we check that $\frac{b_j}{a_i} \in [n]$ and that $c_j = a_j \cdot r^{b_j/a_j} \mod p$.

- If there is a unique $i \in S_j$ with $x_i \neq 0$, the test passes.
- If not, it fails with probability at most $\frac{n}{p} \leq \frac{1}{n^{c-1}}$.

Proof via polynomial identity testing: If $|\{i \in S_j : x_i \neq 0\}| > 1$, then

$$p(r) = c_j - a_j r^{b_j/a_j} \mod p = \sum_{i \in S_j} x_i r^i - a_j r^{b_j/a_j} \mod p$$

is a non-zero polynomial of degree at most *n* over \mathbb{Z}_p .

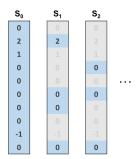
• This polynomial has $\leq n$ roots, so for a random $r \in [p]$, $\Pr[p(r) = 0] \leq \frac{n}{p}$.

• Thus, $c_j = a_j r^{b_j/a_j}$ with probability $\leq \frac{n}{p} \leq \frac{1}{n^{c-1}}$.

Completing The Analysis

Recall: $S_0, \ldots, S_{\log_2 n}$ are random subsets of [n], sampled at rates $1/2^j$.

- If any S_j contains a unique *i* with $x_i \neq 0$, we will recover it.
- It remains to show that with good probability, at least one S_j contains such an *i*.



Claim: For *j* with $2^{j-2} \le ||x||_0 \le 2^{j-1}$, $\Pr[|\{i \in S_j : x_i \ne 0\}| = 1] \ge 1/8$. $\Pr[|\{i \in S_i : x_i \ne 0\}| = 1] = ||x||_0 \cdot \frac{1}{1} \cdot \left(1 - \frac{1}{1}\right)^{||x||_0 - 1}$

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Application to Streaming Computation

A Graph Streaming Problem

Consider a setting where an algorithm must process a stream of edge insertions or deletions, which define a graph. At the end of the stream, the algorithm should output whether that graph is connected or not.

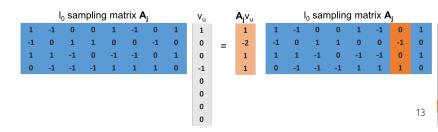


Algorithmic Question: How much memory must an algorithm use to solve this problem with high probability?

What is the worst-case memory required by a naive deterministic algorithm that just stores the current state of the graph? How can you improve on this when there are no edge deletions?

Randomized Solution via ℓ_0 sampling

- The algorithm samples independent ℓ_0 sampling matrices $A_1, \ldots, A_{\log_2 n}$ and maintains $A_j v_u$ for all j and all $u \in [n]$, where $v_u \in \mathbb{R}^{\binom{n}{2}}$ is the incidence vector for node u.
- $O(n \log^3 n)$ bits of storage in total.
- Key Idea: Linear Updates. When an edge (u, v) is inserted or deleted, one entry is either incremented or decremented in each of v_u, v_v . The algorithm can update $A_j v_u$ and $A_j v_v$ in $O(\log^2 n)$ time – simply set $A_j v_u = A_j v_u \pm A_{j,k}$.



Other Applications of Linear Sketching

Linear Sketching

 \$\ell_0\$ sampling is an example of a linear sketching algorithm. We compress our data via a random linear function (i.e., the random matrix A), and prove that we can still recover useful information from the compression.



- Linearity is useful because it lets us easily aggregate sketches in distributed settings and update sketches in streaming settings.
- Aside from recovering non-zero entries we might want to estimate norms or other aggregate statistics of **x**, find large magnitude entries, sample entries with probabilities according to their magnitudes.

Goal: For a vector $\mathbf{x} \in \mathbb{R}^n$ we would like to find all entries of \mathbf{x} with magnitude at least $\epsilon \|\mathbf{x}\|_2$ or $\epsilon \|\mathbf{x}\|_1$.

Common Application:

- **x** is a vector of counts (e.g., views of videos, searches for products, visits from IP addresses, etc.) and we would like to identity all items with large counts.
- We often cannot store all of x in one place but must store a small-space compression of x as counts are updated over time, or must aggregate information about x across multiple machines.

Count Sketch

Set up: We would like to estimate all entries of a vector $\mathbf{x} \in \mathbb{R}^n$ up to error $\epsilon \|\mathbf{x}\|_2$ with probability at least $1 - \delta$, from a small linear sketch, of size $O\left(\frac{\log(1/\delta)}{\epsilon^2}\right)$.

- Let $m = O(1/\epsilon^2)$ and $t = O(\log(1/\delta))$.
- Pick *t* random pairwise independent hash functions $h_1, \ldots, h_t : [n] \rightarrow [m]$.
- Pick *t* random pairwise independent hash functions $\mathbf{s}_1, \ldots, \mathbf{s}_t : [n] \to \{-1, 1\}.$
- Compute *t* independent estimates of $\mathbf{x}(i)$ as $\tilde{\mathbf{x}}_{j}(i) = \mathbf{s}(i) \cdot \sum_{k:\mathbf{h}_{j}(k)=\mathbf{h}_{j}(i)} \mathbf{x}(k) \cdot \mathbf{s}(k).$
- Output the median of $\{\tilde{\mathbf{x}}_1(i), \dots, \tilde{\mathbf{x}}_t(i)\}$ as our estimate.