

First Application of Network Flows: Bipartite Matching

- Given a bipartite graph $G=(L \cup R, E)$, a subset of edges $M \subseteq E \subseteq L \times R$ is a matching if each node appears in at most one edge in $M$.
- The maximum matching problem is to find the matching with the most edges.
- We'll design an efficient algorithm for maximum matching in a bipartite graph.

Formulating Matching as Network Flow problem

- Goal: given matching instance $G=(L \cup R, E)$ :
- create a flow network $G^{\prime}$.
create a flow network $G^{\prime}$,
- use $f$ to construct a maximum matching $M$ in $G$.
- Exercise
- Convert undirected bipartite graph $G$ to flow network $G^{\prime}$
- Direction of edges?
- Capacities?
- Source and sink?


## Maximal Matching as Network Flow

- Add a source $s$ and sink $t$
- For each edge $(u, v) \in E$, add $u \rightarrow v$ (directed), capacity 1
- Add an edge with capacity 1 from $s$ to each node $u \in L$
- Add an edge with capacity 1 from each node $v \in R$ to $t$.



## Maximum Matching: Analysis

- Run F-F to get an integral max-flow $f$
- Set $M$ to the set of edges from $L$ to $R$ with flow $f(e)=1$
- Claim: The set $M$ is a maximum matching.

Correctness: We will show that for every integer flow of value $k$ we can construct a matching $M$ of size $k$ and vice versa. Therefore, a maximum integer-valued flow yields a maximum matching.

## Clicker

Let $G^{\prime}$ be the flow network as constructed above and let $e$ be an edge from $L$ to $R$.
A. For every flow $f$, either $f(e)=0$ or $f(e)=1$.
B. For every maximum flow $f$, either $f(e)=0$ or $f(e)=1$.
C. There is some maximum flow $f$ such that either $f(e)=0$ or $f(e)=1$.
D. B and C
E. A, B, and C

## Correctness 1

1. Integral flow $f$ of value $k \Rightarrow$ matching $M$ of size $k$

- Suppose $f$ is a flow of value $k$
- Let $M=$ edges from $L$ to $R$ carrying one unit of flow
- There are $k$ such edges, because the net flow across cut between $L$ and $R$ is $k$, and there are no edges from $R$ to $L$
- There is at most 1 unit of flow entering $u \in L$, and therefore at most 1 unit of flow leaving $u$
- Since all flow values are 0 or 1 , this means $M$ has at most one edge incident to $u$.
- A similar argument for $v \in L$ means that $M$ has at most one edge incident to $v$
- Therefore, $M$ is a matching with size $k$

Correctness 2 (Review on Own)
2. Matching $M$ of size $k \Rightarrow$ integral flow $f$ of value $k$

- Suppose $M$ is a matching of size $k$
- Send one unit of flow from $s$ to $u \in L$ if $u$ is matched
- Send one unit of flow from $v \in R$ to $t$ if $t$ is matched
- Send one unit of flow on $e$ if $e$ is in $M$
- All other edge flow values are zero
- Verify that capacity and flow conservation constraints are satisfied, and that $v(f)=k$.


## Perfect Matchings in Bipartite Graphs

Recall: A matching $M$ is perfect if every node appears in (exactly) one edge in $M$.
Question: When does a bipartite graph have a perfect matching?

- Clearly, we must have $|L|=|R|$
- Clearly, every node must have at least one edge
- What other conditions are necessary? Sufficient?


## Clicker

What is the running time of the Ford-Fulkerson algorithm to find a maximum matching in a bipartite graph with $|L|=|R|=n$ ?
(Assume each node has at least one incident edge.)
A. $O(m+n)$
B. $O(m n)$
C. $O\left(m n^{2}\right)$
D. $O\left(m^{2} n\right)$

## Perfect Matchings in Bipartite Graphs

For $S \subseteq L$, let $N(S) \subseteq R$ be the set of all neighbors of nodes in $S$


Observation: For a perfect matching we need

$$
\forall S \subseteq L, \quad|N(S)| \geq|S|
$$

Otherwise we can't match all nodes in $S$

## Hall's Marriage Theorem

Assume $G$ is bipartite with $|L|=|R|=n$.
Simple Observation: If $G$ has a perfect matching then:

$$
\begin{equation*}
\forall S \subseteq L, \quad|N(S)| \geq|S| \tag{}
\end{equation*}
$$

Theorem (Hall 1935, earlier by Frobenius, Kőnig): $G$ has a perfect matching if and only if $\left(^{*}\right)$
We will prove: if $G$ does not have a perfect matching then $\left({ }^{*}\right)$ does not hold $\Longrightarrow$ there is some $S \subseteq L$ with $|N(S)|<|S|$.
Use max-flow / min-cut theorem on bipartite-matching flow network.

## Hall's Marriage Theorem

Picture on board: $G^{\prime}$ w/ infinite-capacity $L \rightarrow R$ edges

- Suppose $G$ does not have a perfect matching
- Let $(A, B)$ be the minimum-cut in $G^{\prime} \Longrightarrow c(A, B)<n$
- Let $S=A \cap L$
- All neighbors of nodes in $S$ are also in $A$, else an edge of infinite capacity is cut $\Longrightarrow N(S) \subseteq A \cap R$
- The cut capacity is

$$
\begin{aligned}
n>c(A, B) & =|B \cap L|+|A \cap R| \\
& =n-|S|+|A \cap R| \\
& \geq n-|S|+|N(S)|
\end{aligned}
$$

- $\Longrightarrow|S|>|N(S)|$


## Clicker



Consider the flow network construction for bipartite matching. Which of the following is true?
A. The construction still works if edges from $s$ to $L$ have infinite capacity.
B. The construction still works if edges from $L$ to $R$ have infinite capacity.
C. The construction still works if edges from $R$ to $t$ have infinite capacity.

## Baseball Elimination?

Board work

Bokeh Effect: Blurring Background

- Using an expensive camera and appropriate lenses, you can get a "bokeh" effect on portrait photos in which the background is blurred and the foreground is in focus.

- Can fake effect using cheap phone cameras and appropriate software


## Formulating the Problem

Problem: given set $V$ of pixels, classify each as foreground or background. Assume you have:

- Numeric "cost" for assigning each pixel foreground/background
- Numeric penalty for assigning neighboring pixels to different classes

Sketch of approach: other slides, board work, demo

